

# Developing an Execution Plan for Scan to BIM (sBEP)

Raghavendra Bhat | Joseph Huang

Stantec

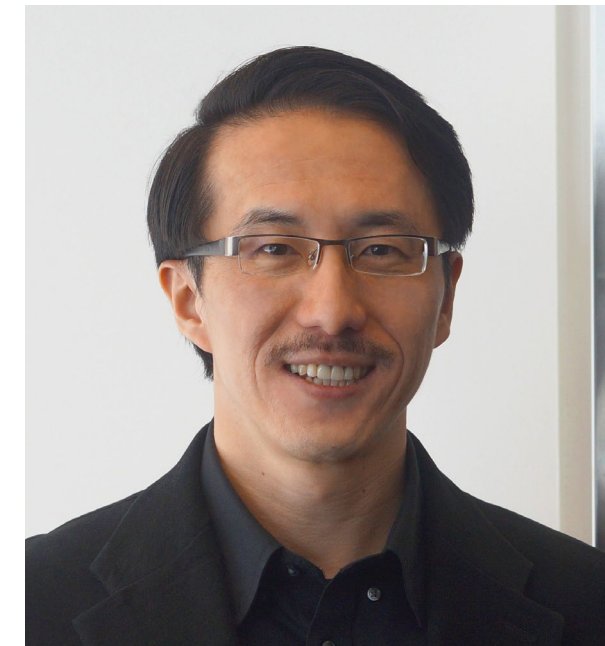


# About the speakers



Raghavendra Bhat

- Pune BIM Leader at Stantec
- Sr. Civil Engineer
- Autodesk Certified Associate and Professional
- Integrator, Mentor & Trainer
- AU Speaker in 2013, 2016, 2017, 2019



Joseph Huang

- Chicago BIM Leader at Stantec
- Registered Architect (Illinois)
- Experience from Buildings to Wet Infrastructure
- XR Professor at Northwestern University
- AU Speaker in 2011, 2013, 2016, 2017, 2019



***Business Lines:***

Buildings

Community Development

Environmental Services

Mining

Oil & Gas

Power

Transportation

Water

Waterpower & Dams

22,000 employees

Over 400 locations

# Key Learning Objectives

At the end of this class, you will be able to:

- Discover requirements for a Scan-to-BIM job
- Learn how to define and set standards for level of accuracy and level of development
- Learn how to save time in handling and modeling from large-size point clouds
- Learn about QC workflows using Revit templates, Navisworks, and Virtual Reality

An aerial photograph of an industrial facility, likely a refinery or chemical plant. The image shows several large, cylindrical storage tanks, a complex network of pipes and structural steel, and various pieces of industrial equipment. The scene is captured from a high angle, providing a comprehensive view of the facility's layout. The text "Scan to BIM Execution Plan" is overlaid on the image in a large, white, sans-serif font. The word "Scan" is in a light blue color, while "to BIM Execution Plan" is in white. The background image is slightly desaturated, emphasizing the text.

# Scan to BIM Execution Plan

# Table of Contents

1.0	INTRODUCTION .....	1.1
1.1	USING THIS SCAN TO BIM EXECUTION PLAN .....	1.1
1.1.1	Heading 3.....	1.1
2.0	PROJECT INFORMATION .....	2.1
2.1	PROJECT DESCRIPTION .....	2.2
2.2	PROJECT SCHEDULE .....	2.2
2.3	KEY PROJECT CONTACTS / ROLES AND RESPONSIBILITIES .....	3.2
3.0	CLIENT OBJECTIVES .....	3.2
3.1	FAQ'S .....	3.2
3.2	REQUIREMENT SHEET TO SURVEYOR.....	4.4
4.0	SCOPE AND PLANNING .....	4.4
4.1	TAKING DOWN REQUIREMENTS .....	4.4
4.2	SETTING EXPECTATIONS - WITH CLIENT AND TEAM .....	4.4
4.3	LOD REQUIREMENTS .....	4.4
4.4	IDENTIFYING RISKS .....	4.4
4.5	IDENTIFYING TOOLS .....	5.5
4.6	DEFINING WORKFLOW .....	6.5
5.0	ESTIMATION (LEVEL OF EFFORT) .....	7.5
6.0	COMPETENCE AND TRAINING .....	8.5
7.0	STANDARDS AND CONVENTIONS .....	8.5
8.0	DATA TRANSFER / INFORMATION MANAGEMENT .....	8.5
8.1	DATA TRANSFER OPTIONS .....	9.6
8.2	MAKING DATA AVAILABLE TO THE MODELLING TEAM .....	10.6
8.2.1	Script to enable copy of relevant scan data to users local.....	10.6
9.0	MODEL SETUP AND MODELLING PRACTICE.....	10.6
10.0	MODEL QC PROCESSWORKFLOWS .....	11.6
10.1	USING REVIT .....	12.1
10.2	USING NAVISWORKS .....	1.1
11.0	ADVANCE VISUALISATION USING EXTENDED REALITY.....	2.1
12.0	REFERENCES .....	1.1
	LIST OF TABLES .....	
	Table 1 Example .....	
	Table 2 Project details .....	
	LIST OF FIGURES .....	
	Figure 1 Example .....	



Figure 2: Sample SOP marked on Site for Reference .....	3.3
Figure 3: Surveyor records the coordinates of these points when on site .....	3.3
Figure 4: Surveyor issues a list of scan positions .....	3.3

## LIST OF APPENDICES

APPENDIX A	LEVEL OF DEFINATION.....	A.1
A.1	Heading 8 .....	A.1
A.1.1	Heading 9 .....	A.1
APPENDIX B	MODEL CHECKING REQUIREMENTS .....	B.1



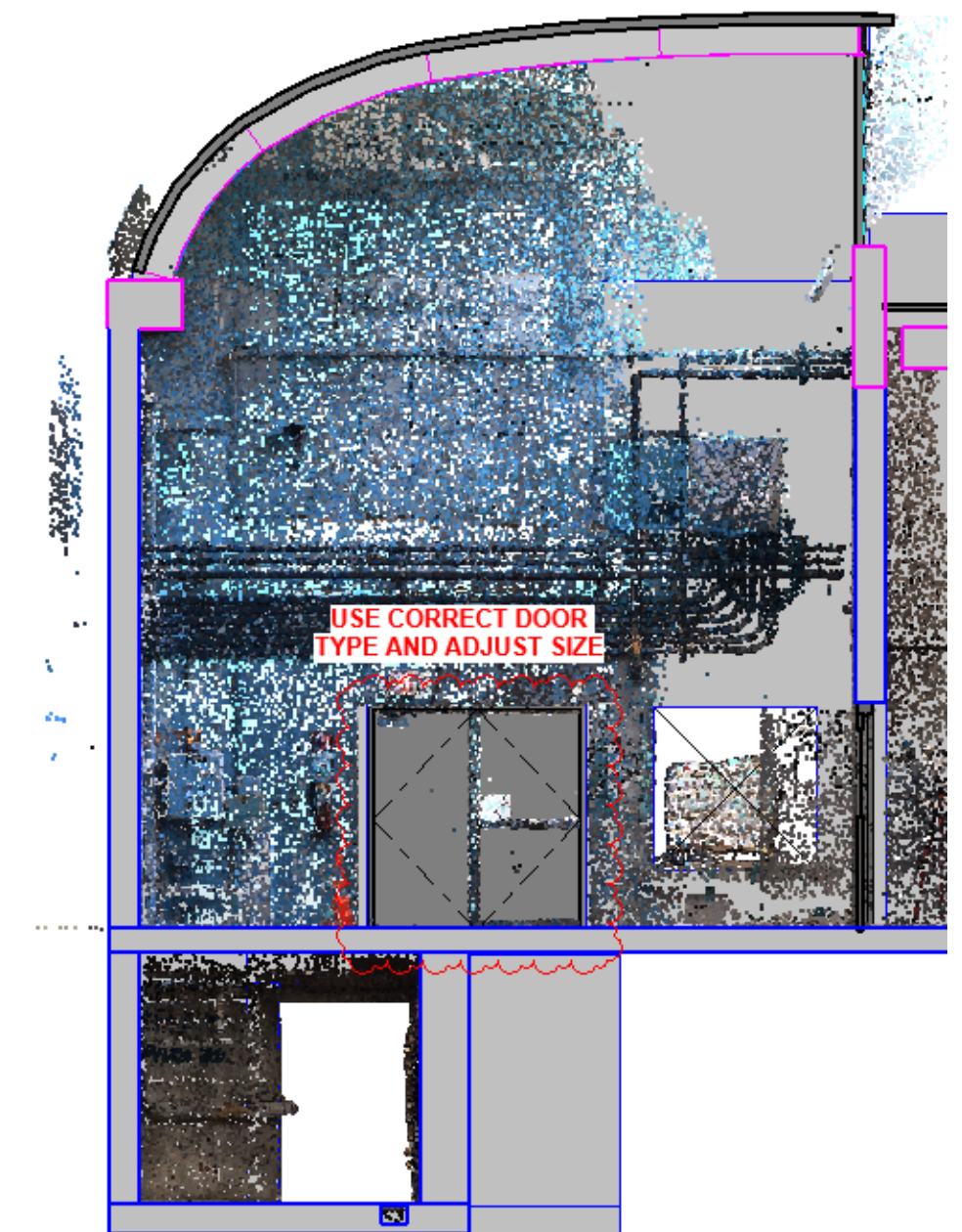
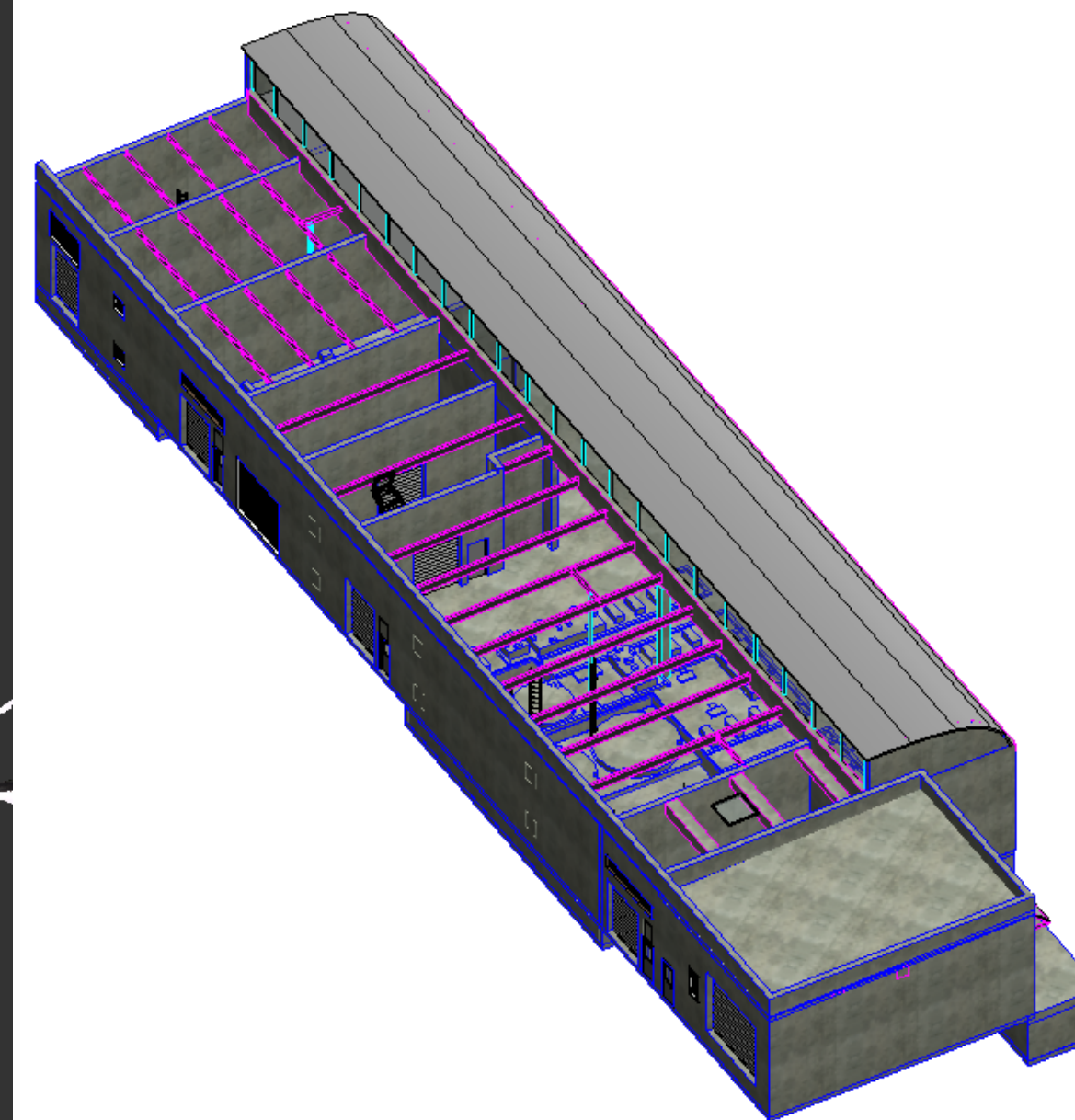
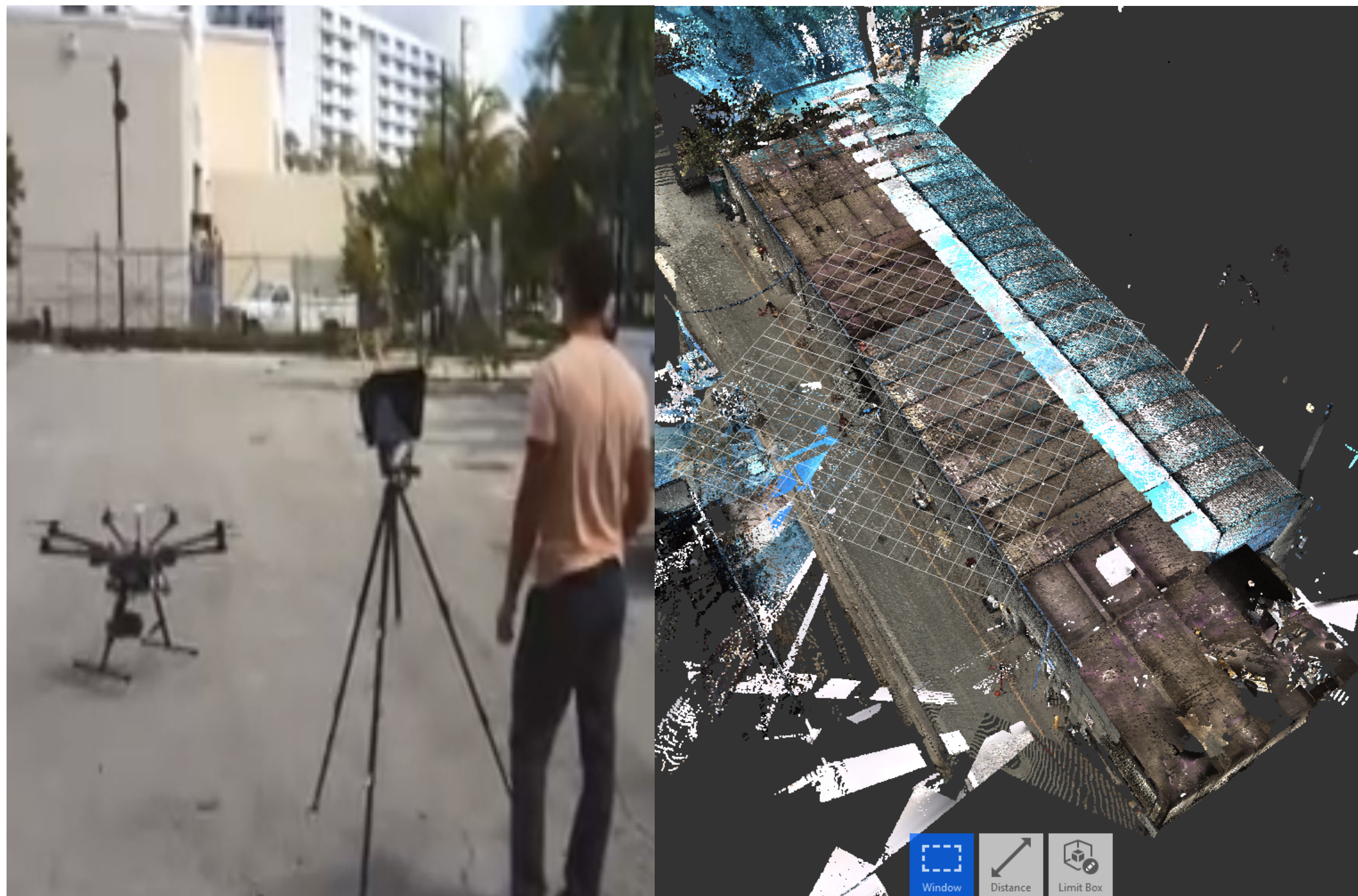
# SCAN TO BIM – HIGH LEVEL WORKFLOW

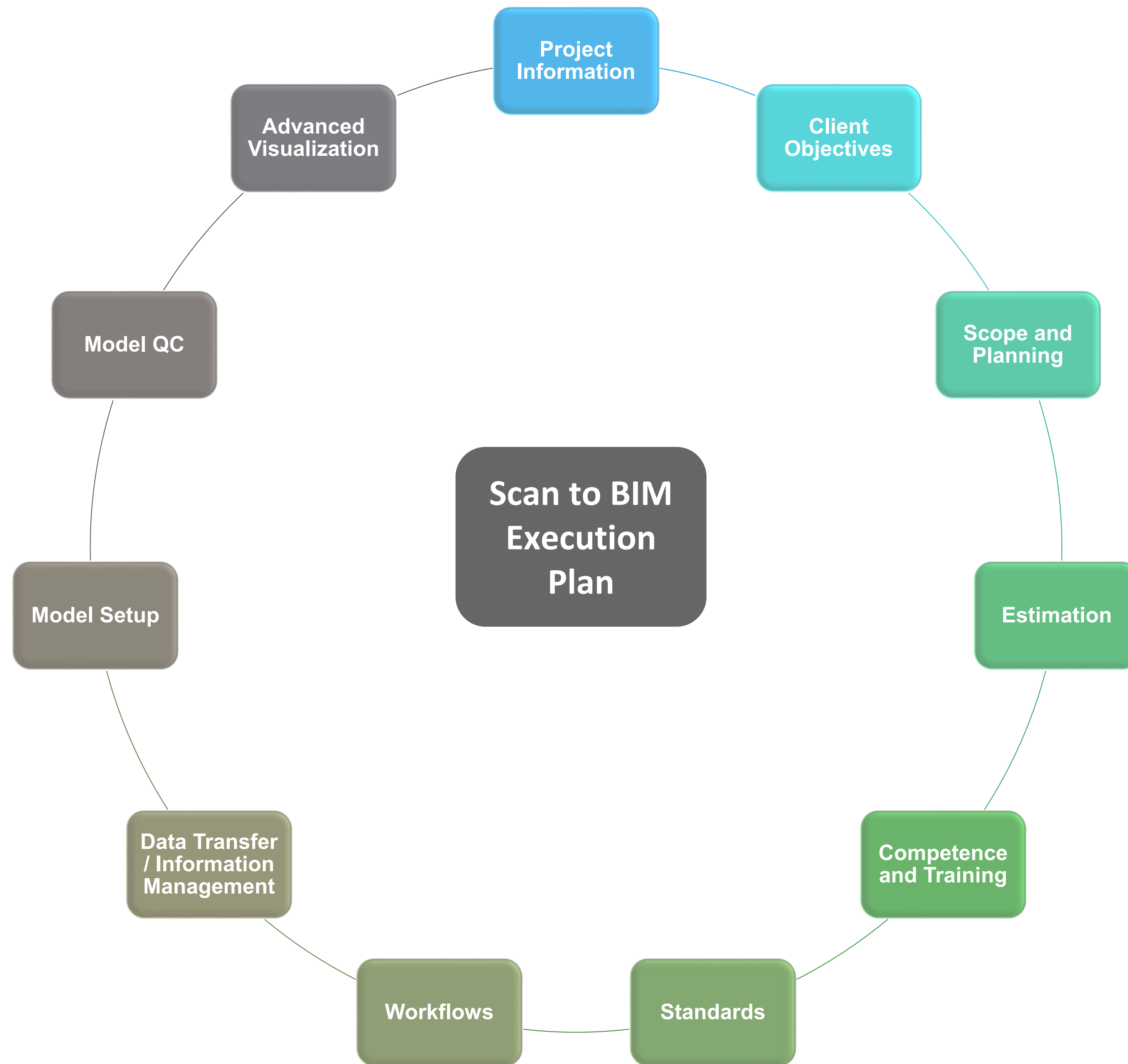
Capture

Process

Modeling

Quality Control





# Taking Down Requirements - Essentials

Client Requirements  
**You Need**

Team Requirements  
**We Need**

EIR -Employer's Information Requirements



**"Beginning with the end in mind"**

# Client Need - Define Purpose & help understand the intended use

## An As-Built Scan model

- Site/Area of interest highlighted on a
  - PDF
  - Google Earth Image
  - Site Photos
  - Recap Comments
- Level of Detail Required for each area
  - Highlight using different marker for AOI based on the Level of detail you want it to be modelled.
- Intended use of model
  - Refurbishment
  - Quantity Take Off
  - Develop As-Built Drawings
  - Site Verification

# Client Requirements & Setting Expectations

## Client

- Workflow
- Tools
- Deliverables
- LOD



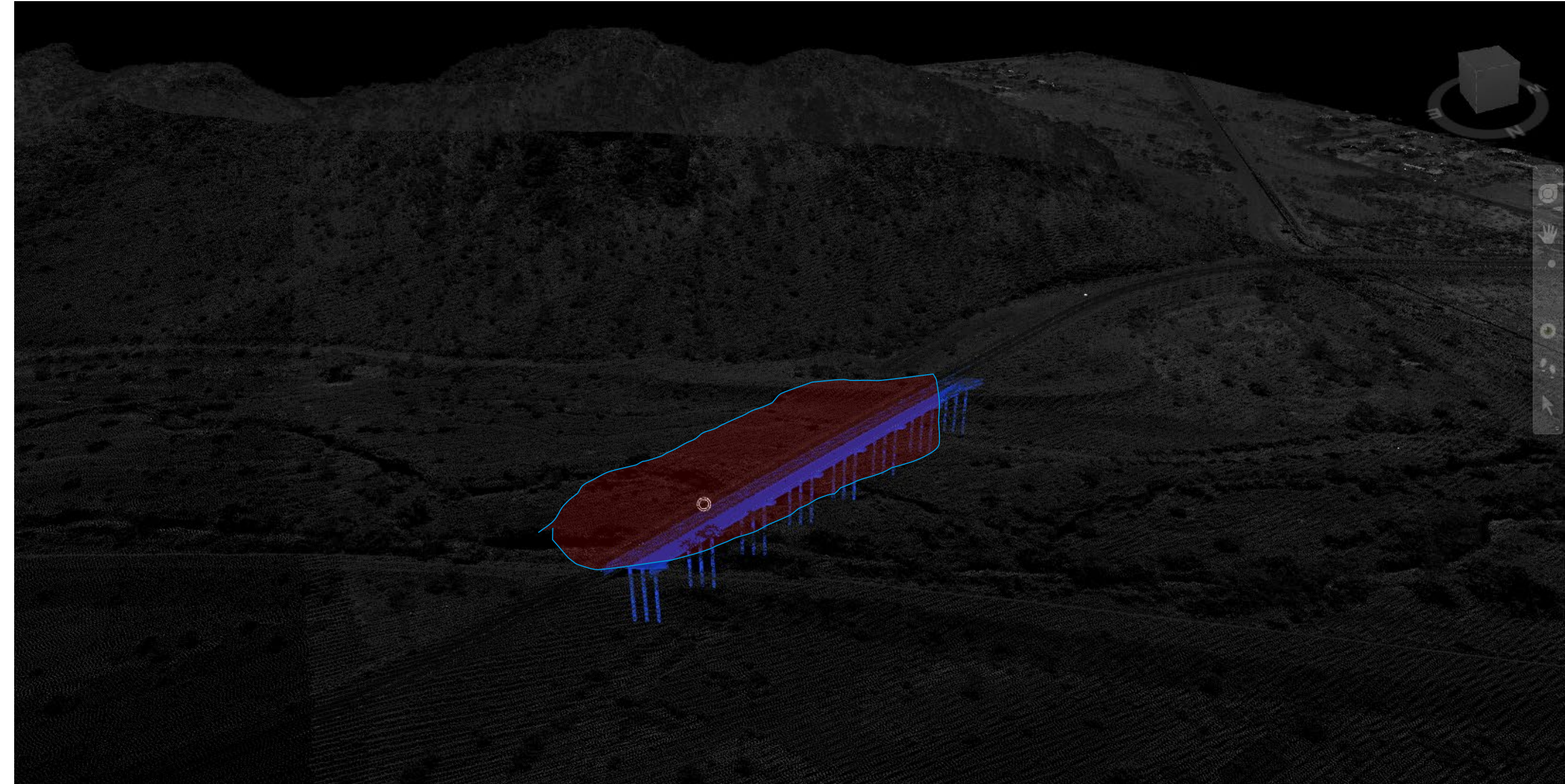
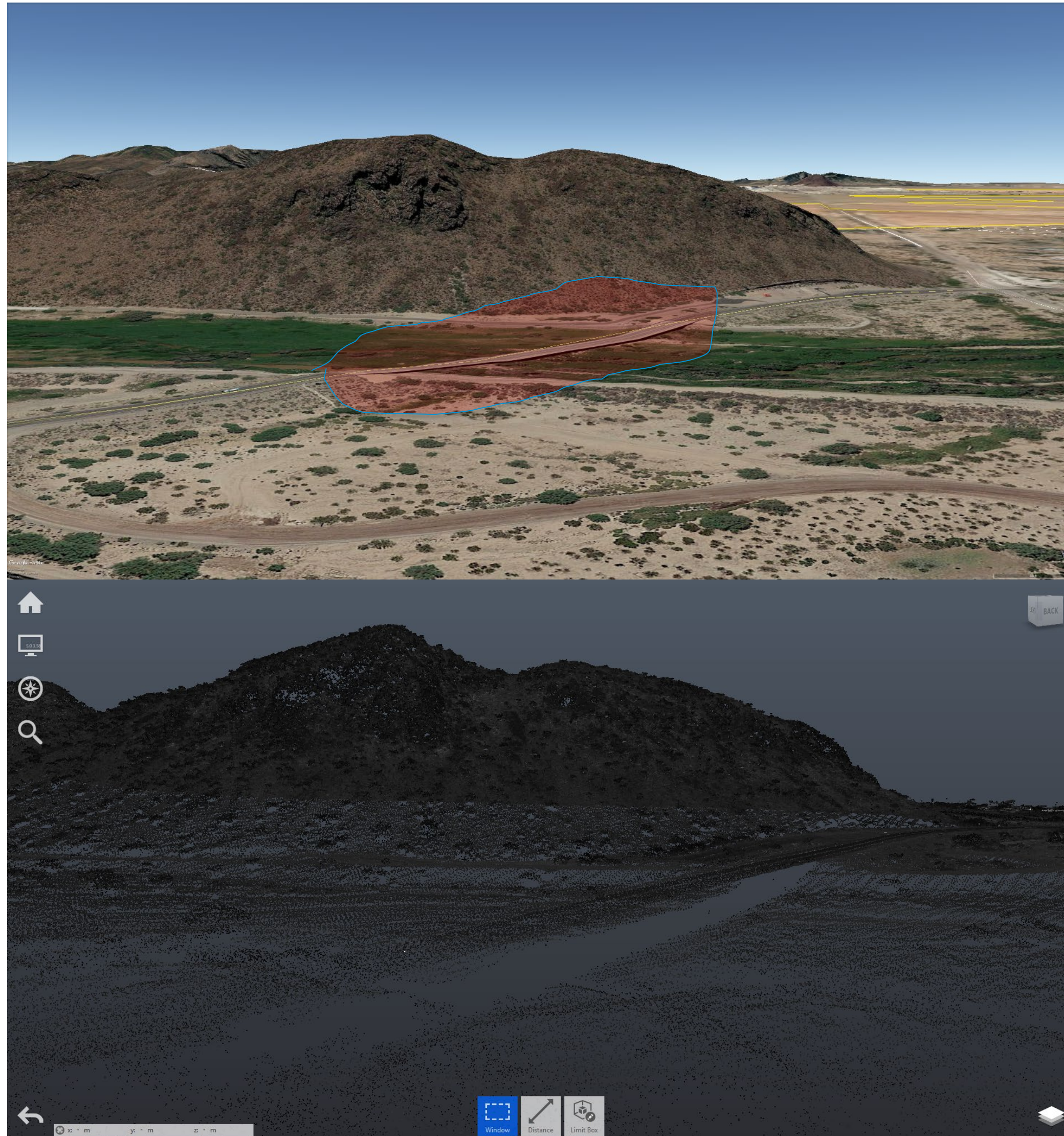
## Team

- Workflow
- Tools
- Deliverables
- LOD
- QC Workflows

**Communication is the Key**

# Effect of Poor Information

## Uncoordinated Information & Geospatially Incorrect Information



- Lack of clearly communicated survey information required.
- Lack of good density scan.
- Lack of coordinates registration cross verification.

# Requirement Sheet to Surveyor – Need's to contain

Scanner	XXX
Scan density	XXX
RGB values registered	Yes, Required.
Scan's Geo located to Coordinate system	Having all the independent scans geo located is very essential.
Scan Formats Required	E57, RCS/RCP (2 formats required)
Scan Cleanups	Any points captured far off from the Area of Interest need to be deleted.  If there are scans of trees and plantation in the background captured (not in Area of Interest), would need to have them cleaned up and not included in the final format being submitted.
Embed 360 Real views	It is essential to have the 360 Real Views embedded with the scans.
SOP (Setout points)	Request to obtain few setout points with X,Y,Z information. Will be very valuable Just in case need to orient/verify/position the model.

SCANNER REQUEST FORM

To avoid any delay in processing this information please complete ALL boxes.  
Please delete as appropriate YES / NO NOT/APPLICABLE.  
A Quote will be given after this form is submitted

1) Client / Dept

Southern Water

Notification Email List

Site Address

Burham

Postal Code

XXXX

Site Authorisation attached or to be given at Site - Please state

To be agreed

Contact Name

Burham WTW

Contact No.

XXXXXX

Site Contact Name (if different to above)

Y/N N/A

Site Contact No (if different to above)

Y/N N/A

Will Client / Contact be on site during visit?

Y

Site Induction Required?

Y

Is Site Welfare available?

Y

MWH Site Job No

XXXXXX

Site Access available between

0:00

hrs &

0:00

hrs

Additional Access requirements

N/A

2) Objective

of the HLP's/Generator room and Transformer building. Previous scan/modelling works completed on the LLP's and

Site Information Attached (Y/N or N/A)

Site plan

Y

Hazardous Areas

N

Working at Heights

Y

Service Location Plan

N

Confined Spaces

Y

Photographs (No.)

Y

Adjacent Structures

Y

Traffic Management

N

Aerial View

Y

Asbestos Register

TBC

Video Route(s) - Plan

Y

Section

N

Other (Please State)

N

List of attached document No's, or state details

JT.629383.0M2901

Y/N N/A

Y/N N/A

Y/N N/A

Y/N N/A

3) Type of Survey

Internal / External / Both

Both

Partial or Complete Site Scan Required

Y/N N/A

Please indicate on attached plan the Partial Scan area

Walkover -

Line of sight scans from normal access routes through site.

Y

Intrusive -

Access to chambers, kiosks or cabinets will be required. Additional permits may be required.

Y

Confined Space -

Access in rooms, chambers, and all areas designated a confined space

Y

Isolations -

Where isolations are required to gain access or empty chambers, channels etc.

N

Please state below any Isolations required

1

Y/N N/A

hrs

2

Y/N N/A

hrs

3

Y/N N/A

hrs

4

Y/N N/A

hrs

5

Y/N N/A

hrs

All isolations are to be carried out by the client / representative. Where there is a requirement to drain tanks or chambers this should be completed prior to arrival where practicable. Note: Additional charges may apply if delays are incurred.

4) Output File - Please state the format of the Point Cloud file to be produced. This will depend on what software is to be used for conversion and future use. The Default exported point cloud file will be in mm unless otherwise stated.

EST

N/A

.fls

N/A

POD

N/A

VRML

N/A

DXF

N/A

Other

N/A

5) Additional Information

N

Site Phone Signal (For Lone Working purposes)

Good, Adequate, Poor, Little or None, Unknown.

Good

Preferred Site Start Date

X

/

5

/

2018

6) Referencing

Does the Scan require placing onto a local coordinate grid

Y

If Yes, please provide X, Y & Z co-ordinates for 3 points

I confirm that the information provided is correct at the time of request

See Notes in the Process Guides for more information.

Signed

Name

Point 1

X

0.000

Y

Point 2

X

0.000

Y

Point 3

X

0.000

Y

Once complete attach this form along with supporting documents to the coleshill3Dscanner calendar page or email to coleshill3Dscanner@mwglobal.com and await date confirmation

SCANNER REQUEST FORM

Please see Terms and Conditions below

Please be aware of the following Terms and Conditions:

If suitable survey information is not available, then additional cost may be incurred in obtaining additional information

An allowance of 1hr per site survey has been allowed for the MWH Operator to undergo site inductions

MWH Operator has free and uninterrupted access to the agreed scanning area

The MWH Operator is not responsible for isolating flows and/or supplies. Where practicable all isolations and "lock offs" should be undertaken prior to arrival.

No allowance has been made for standing time which will be charged at an hourly rate

No allowance has been made for specialist equipment required to access site which will be charged at an hourly rate

No allowance has been made for specialist PPE, which if required, will require an additional charge

No allowance for specialist lifting equipment, which if required, will require an additional charge

Traffic management can be provided at additional cost

Hire of confined space equipment shall be at cost

Additional resources for confined space entry can be provided at additional cost

All permits are to be issued by the client and/or their representative

The MWH Operator is not responsible for cleaning access covers and freeing stuck covers.

Any damaged caused to frame and surround as a result of lifting a cover is the responsibility of the client.

A Survey day is defined as a maximum of 8hrs on site.

Time on site duration in excess of 8hrs will incur an additional day

Travel in excess of 1hr, will be charged at an additional rate

Alternative travel (train, plane) will be charged at cost +

Cost Estimates and Quotations are based upon a minimum 4 scans per hour.

The MWH Survey Team shall endeavour to programme site visits to avoid inclement weather conditions

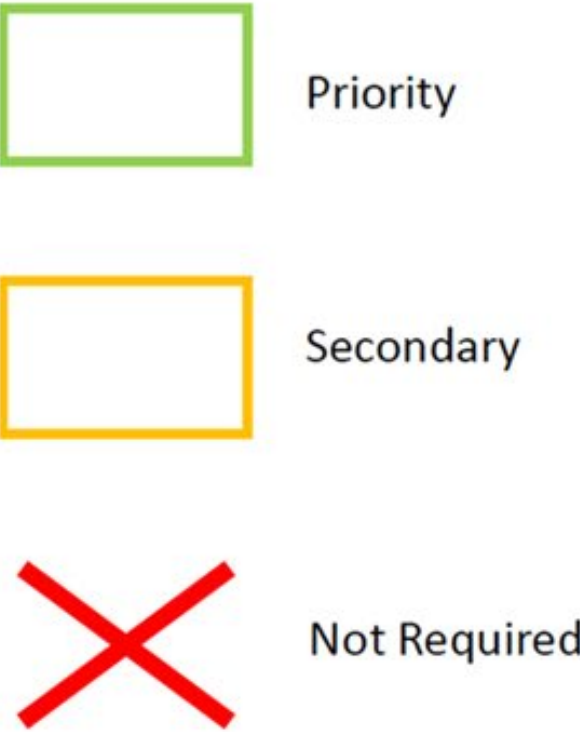
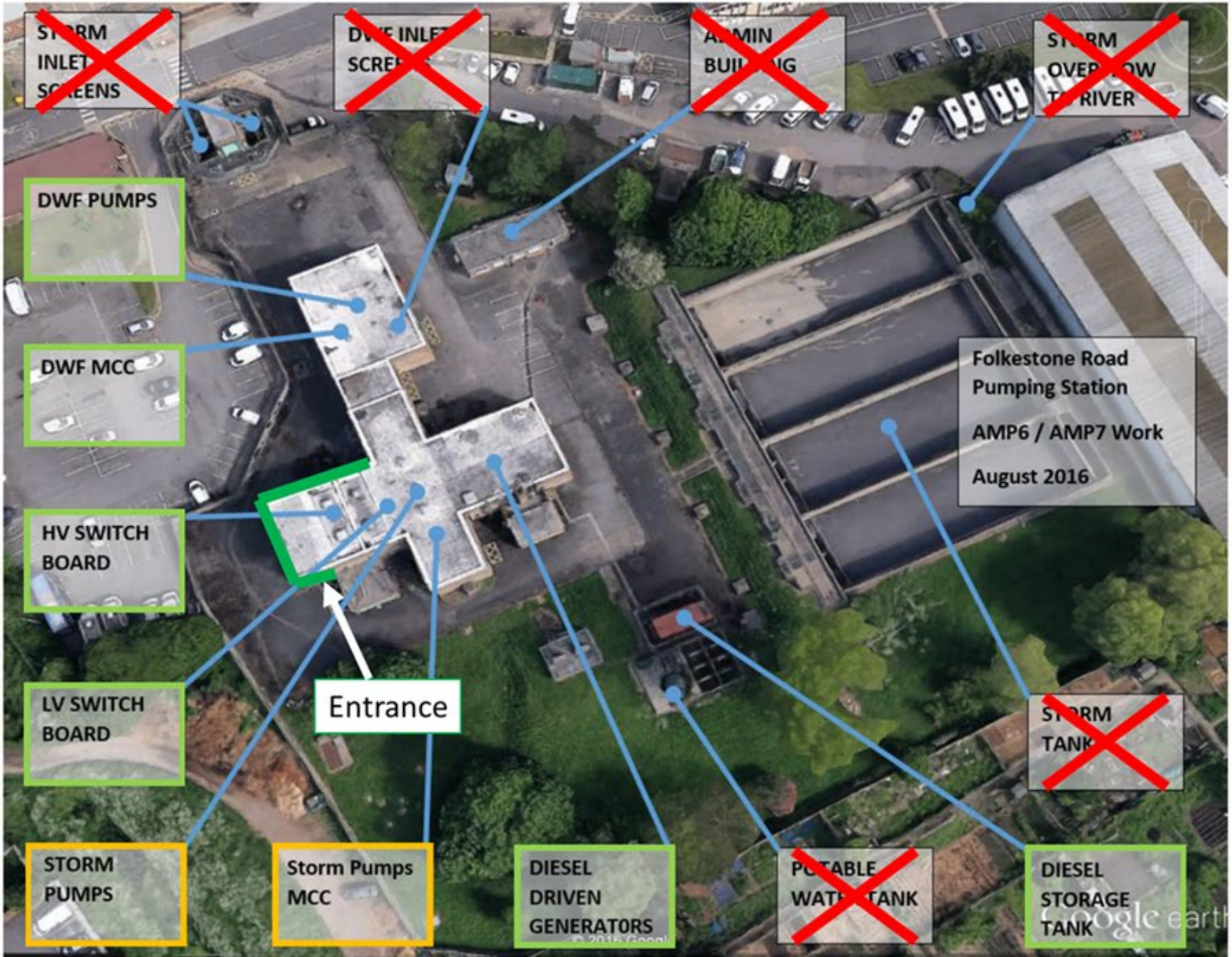
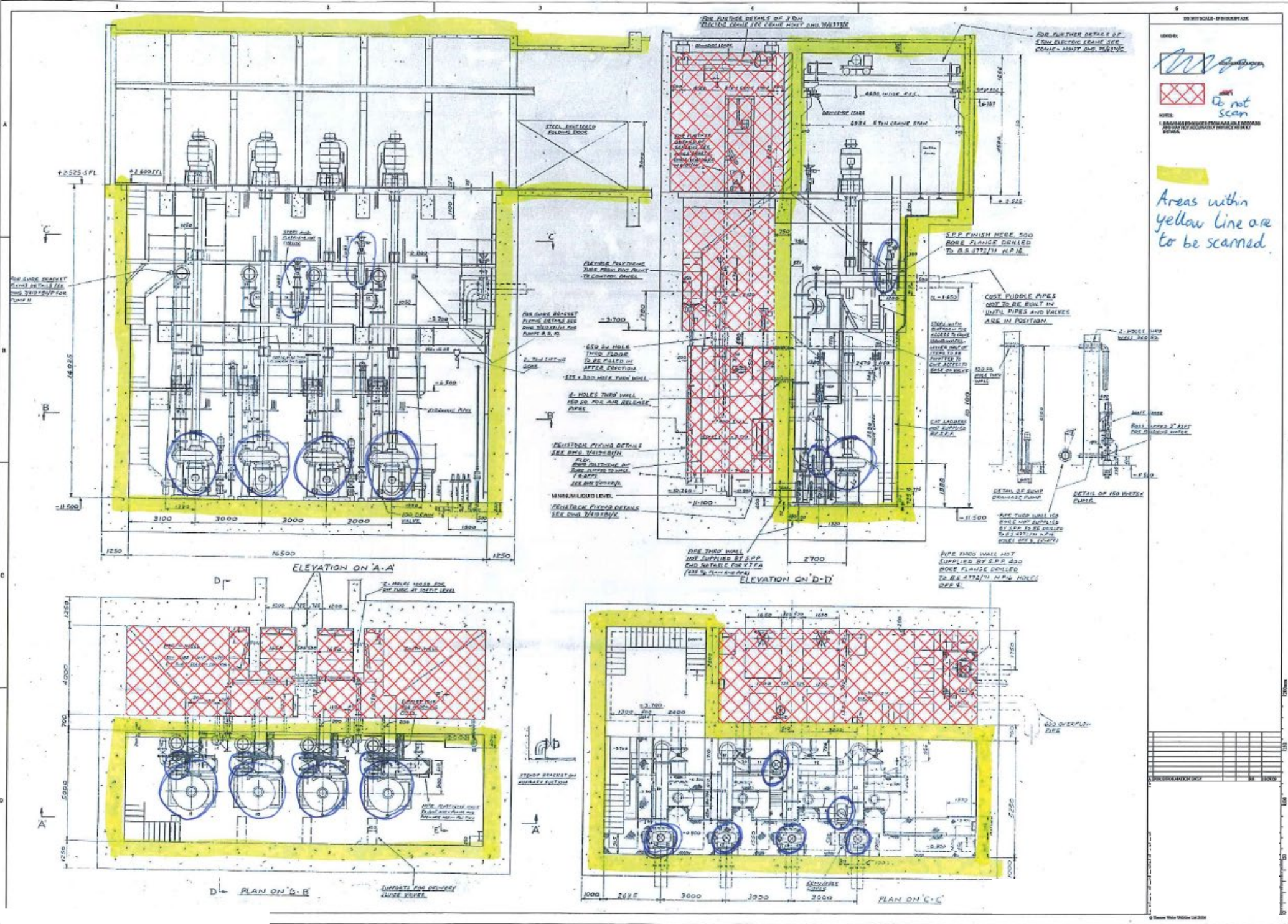
The client is responsible for any additional payment where, inclement weather has delayed or abandoned a survey if the MWH Survey Team have made the client aware of the potential risk.

In addition, any accommodation as the result of the aforementioned weather delay shall incur additional cost.

Procurement of additional software and/or licences to produce data in a format of the client request (where available) will incur additional cost

Cancellation due to the client within 24hrs of a site visit shall incur a full day cost.

# Examples of Prioritizing Scan Work



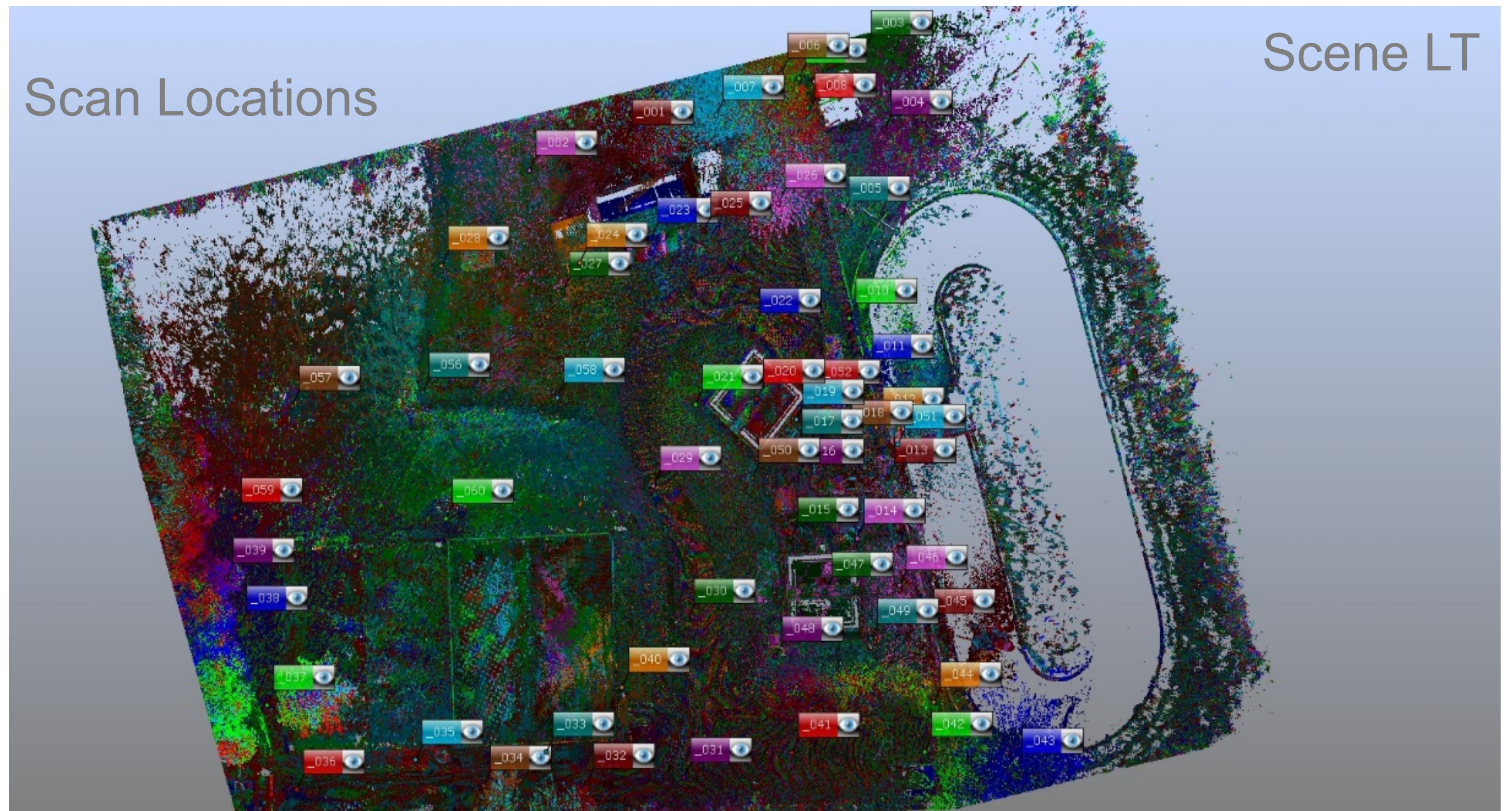
# Setout Points – From Surveyor



	A	B	C	D	E
1	SOP1	359710.422	677960.702	14.358	
2	SOP2	359701.790	677929.706	11.477	
3	SOP3	359668.450	677913.524	11.032	
4					
5					

Scan Locations

Scene LT



# Check Using Map Overlay



The screenshot displays the Autodesk AutoCAD Civil 3D 2017 interface. The main viewport shows a 3D point cloud model of a building, with a map overlay visible in the background. The map overlay is a topographic map showing the building's location relative to the surrounding terrain. The map overlay is labeled "TOP" and "W" (West) and "E" (East). The map overlay is also labeled "N" (North) and "S" (South).

The left-hand side of the interface shows the "PROPERTIES" panel, which is currently set to "No selection". The "General" section shows the "Color" set to "ByLayer", "Layer" set to "C-ANNO-MATC-PATT", "Linetype" set to "ByLayer", "Linetype scale" set to "1.0000", "Lineweight" set to "ByLayer", "Transparency" set to "ByLayer", and "Thickness" set to "0.0000". The "3D Visualization" section shows the "Material" set to "ByLayer". The "Plot style" section shows the "Plot style" set to "ByColor", "Plot style table" set to "None", "Plot table attached..." set to "Model", and "Plot table type" set to "Not available". The "View" section shows the "Center X" set to "6068259.4434", "Center Y" set to "2157103.1095", "Center Z" set to "0.0000", "Height" set to "217.6242", and "Width" set to "413.3526". The "Misc" section shows the "Annotation scale" set to "1" = 40'", "UCS icon On" set to "Yes", "UCS icon at origin" set to "No", "UCS per viewport" set to "Yes", "UCS Name" set to "\*TOP\*", and "Visual Style" set to "3dWireframe".

The right-hand side of the interface shows the "File References" panel, which lists the "Briones" point cloud. The "Briones" point cloud is listed with a status of "Loaded", a size of "1.26 MB", a type of "RCP", a date of "6/11/2019 9:07:11 AM", and a saved path of "\\inpun1d15006\Point Cloud Data\Briones\ReCap\_11th June 2019\Briones.rcp". The "Details" section shows the "Reference ..." set to "Briones", "Status" set to "Loaded", "Size" set to "1.26 MB", "Type" set to "RCP", "Date" set to "6/11/2019 9:07:11 AM", "Found At" set to "\\inpun1d15006\Point Cloud Data\Briones\ReCap\_11th June 2019\Briones.rcp", "Saved Path" set to "\\inpun1d15006\Point Cloud Data\Briones\ReCap\_11th June 2019\Briones.rcp", "Total Points" set to "101905954", and "Total Regions" set to "0".

The bottom of the interface shows the command line, which displays the command "Reload point cloud 'Briones': \\inpun1d15006\Point Cloud Data\Briones\ReCap\_11th June 2019\Briones.rcp" and the message "Briones" loaded and relinked.

# Geotag Photos

Photo in EBMUD- Orinda Chem... 37°53'32.1"N 122°12'09.8"W - G... Bing Maps - Directions, trip plan... BIM 360 Document Management

bing.com/maps

Apps Bookmarks Inbox (33,662) Home - Pune Proje... Suggested Sites Revit Server Admini... Europe-Africa & Mi... Share BIM, Construction a... Autodesk and FM:S... incometaxindiaefili... Directorate of Inco... Using FBX Files Other bookmarks

37.8922361,-122.2027194

Directions Traffic My Places More

190 Camino Pablo, Orinda, CA 94563

Aerial

United States - CA - Contra Costa Co. - Orinda

Manzanita Dr

Stanton Ave

Camino Pablo

Camino Pablo

Camino Pablo

190 Camino Pablo, Orinda, CA 94563

50 feet 20 m

© Vexxel Imaging, © 2019 HERE

© 2019 Microsoft

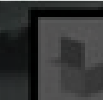
Privacy and Cookies Legal Advertise About our ads Help Feedback

IMG\_0759.JPG RECORDED WITH SCREENCAST MATIC

IMG\_0009.JPG

Show all

3:15 PM 11/3/2019

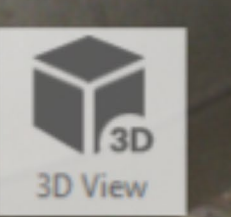
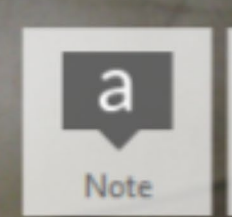
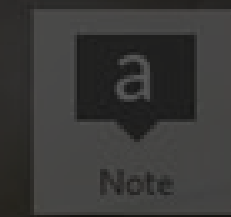


full plan view

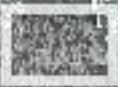
ReCap – Mark up  
Clearly identify what is  
required and what is not.

Demolition

Required



x: 345591.722 m y: 627617.819 m z: 123.157 m



View States

Scans

Scan Locations

Annotations

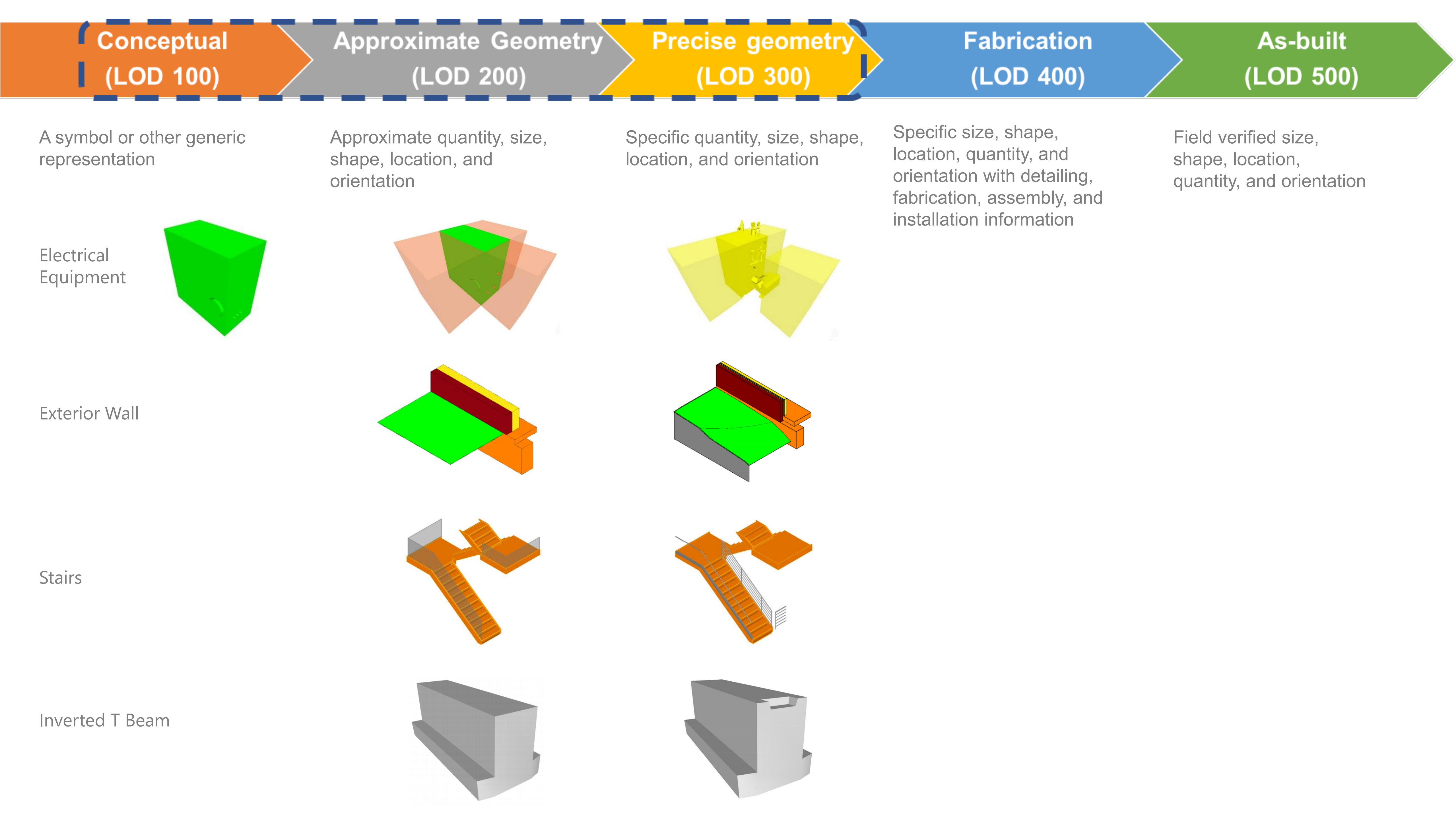
Required

Demolition

Attached Projects BETA



# Scan to BIM - LOD Definition / Requirements



# Non-Geometric Attributes

	Required LOD (Accuracy)	Non-geometric Attributes
Floors	Approximate geometry ( >2", Shape Size and Location )	Material
Roof	Approximate geometry ( >2", Shape Size and Location )	Material
Structural Framing	Approximate geometry ( Shape Size and Location )	Material
Mechanical Equipment's	Approximate geometry ( Shape Size and Location )	Manufacture / Capacity
Electrical Equipment's	Approximate geometry ( Shape Size and Location )	Manufacture / Capacity
Pipes	Approximate geometry ( Shape Size and Location )	Material
Pipe Accessories	Approximate geometry ( Shape Size and Location )	Material
Pipe Fittings	Approximate geometry ( Shape Size and Location )	Material
Walls (Masonry/Concrete)	Approximate geometry ( Shape Size and Location )	Fire rating / Material
Doors & Windows	Approximate geometry ( Shape Size and Location )	Type / Material / Swing Directions
Openings	Approximate geometry ( Shape Size and Location )	Type

# Level of Accuracy (LOA)



**USIBD**<sup>TM</sup>

U.S. Institute of  
BUILDING DOCUMENTATION

## Precision and Correctness



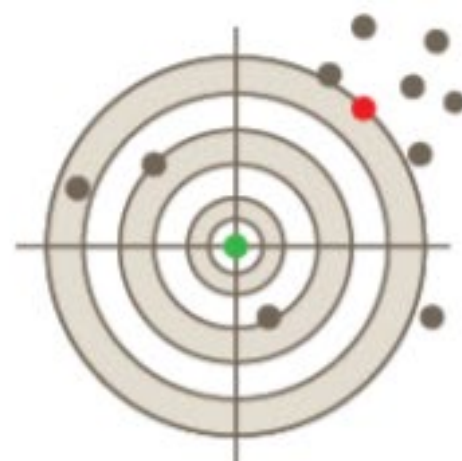
**A**

Precision: Bad  
Correctness: Good  
Accuracy: Medium



**B**

Precision: Good  
Correctness: Bad  
Accuracy: Bad



**C**

Precision: Bad  
Correctness: Bad  
Accuracy: Bad



**D**

Precision: Good  
Correctness: Good  
Accuracy: Good

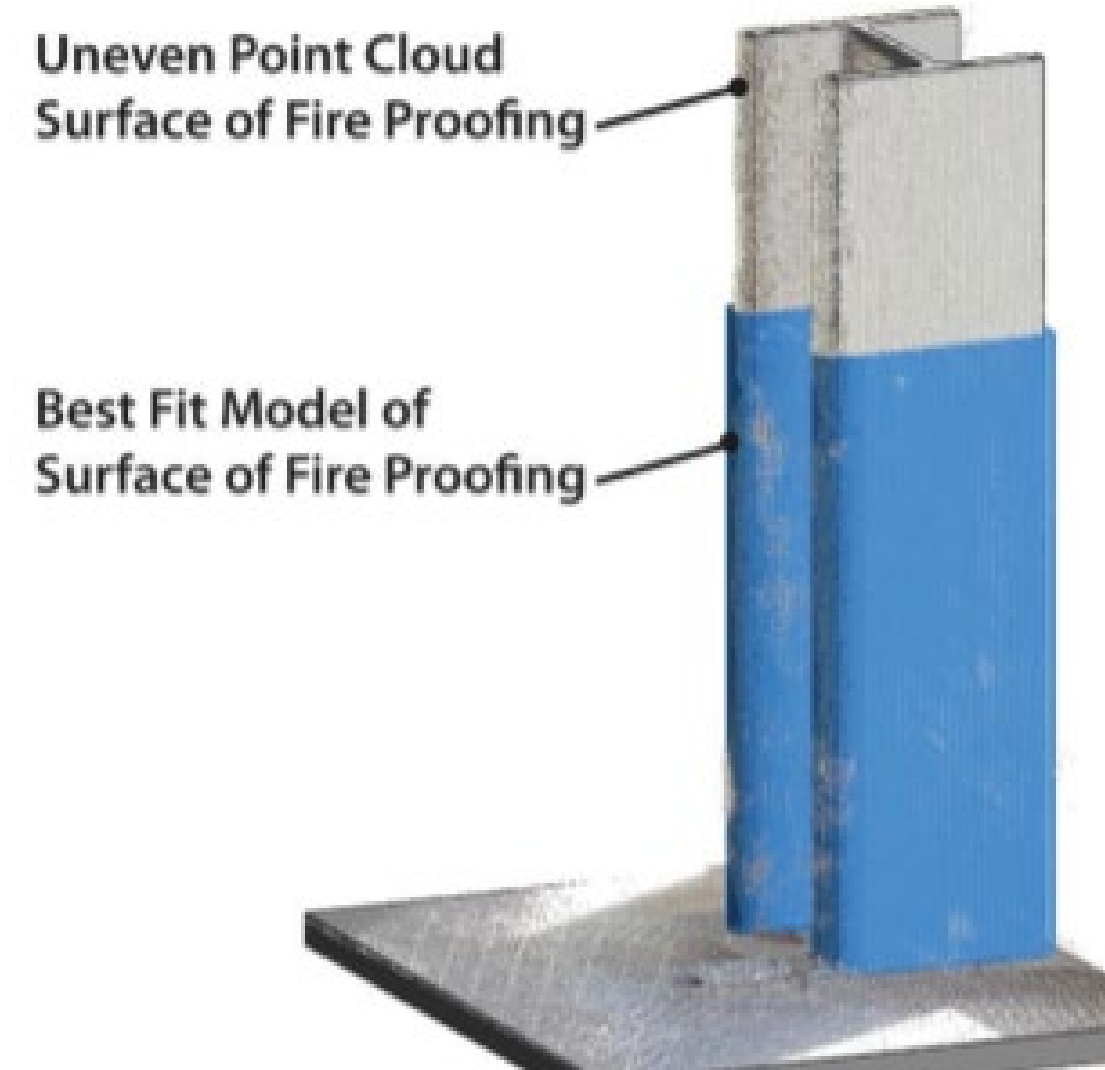
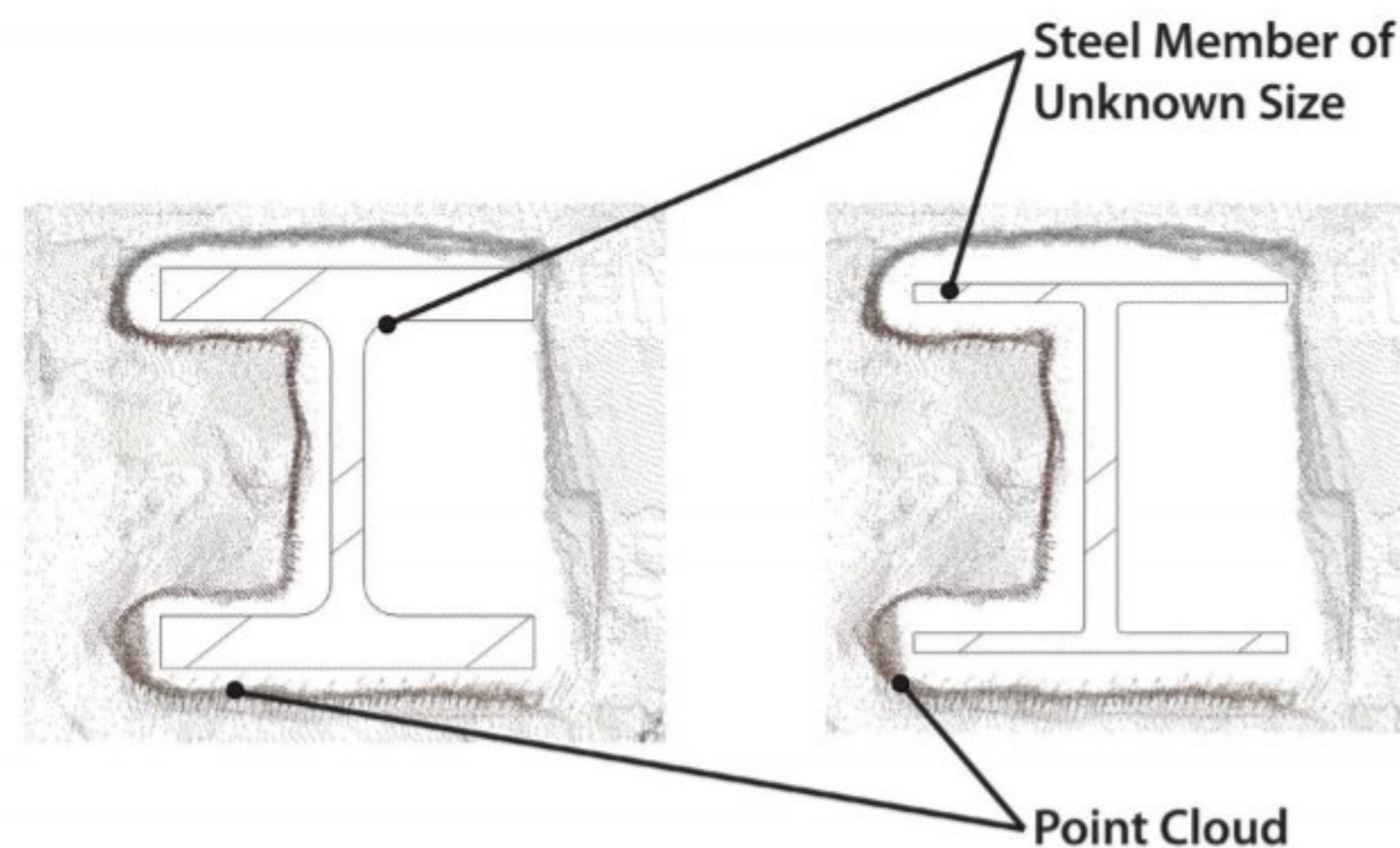
### LEGEND

- True Value
- Mean of the Individual Values
- Individual Values

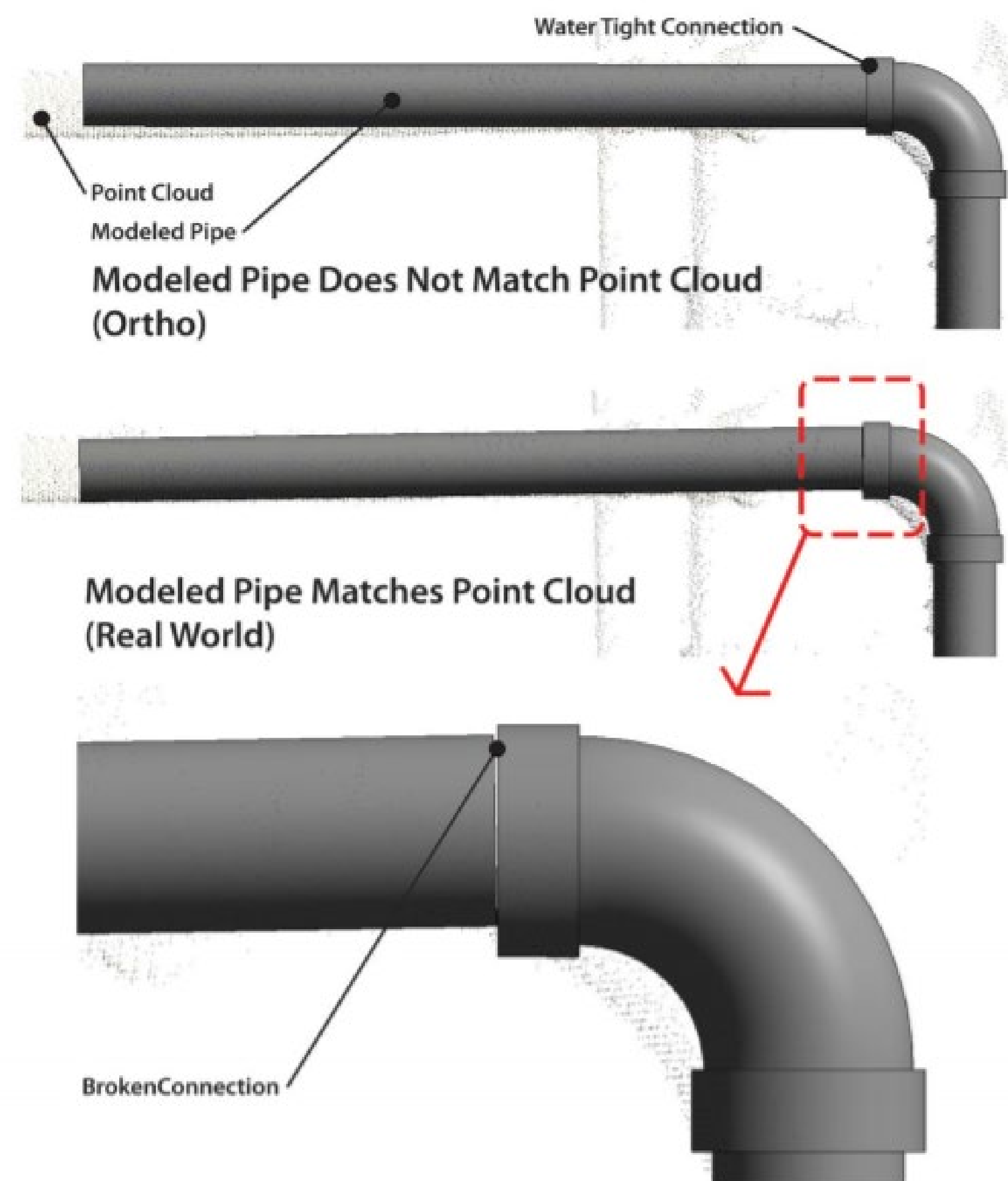
	Level Of Accuracy				
Upper Range (Imperial)	-	2"	5/8"	1/4"	1/16"
Lower Range (Imperial)	2"	5/8"	1/4"	1/16"	0
Upper Range (Metric)	-	5cm	15mm	5mm	1mm
Lower Range (Metric)	5cm	15mm	5mm	1mm	0
	LOA10	LOA20	LOA30	LOA40	LOA50

Level of Accuracy (LOA) is a scale developed by USIBD for setting the accuracy of data gathering and for elements modeled based off of gathered data. For example, a laser scan could be done to meet LOA 20, and the elements modeled off of it could meet LOA 30.

# Concealed Conditions & Best Fit



# Orthogonal vs. Real World



# Document before and after modeling

FW: Buffalo pound



Bhat, Raghavendra

To: [Redacted]  
Cc: [Redacted]

Retention Policy Full Mailbox - Never Delete (Never)

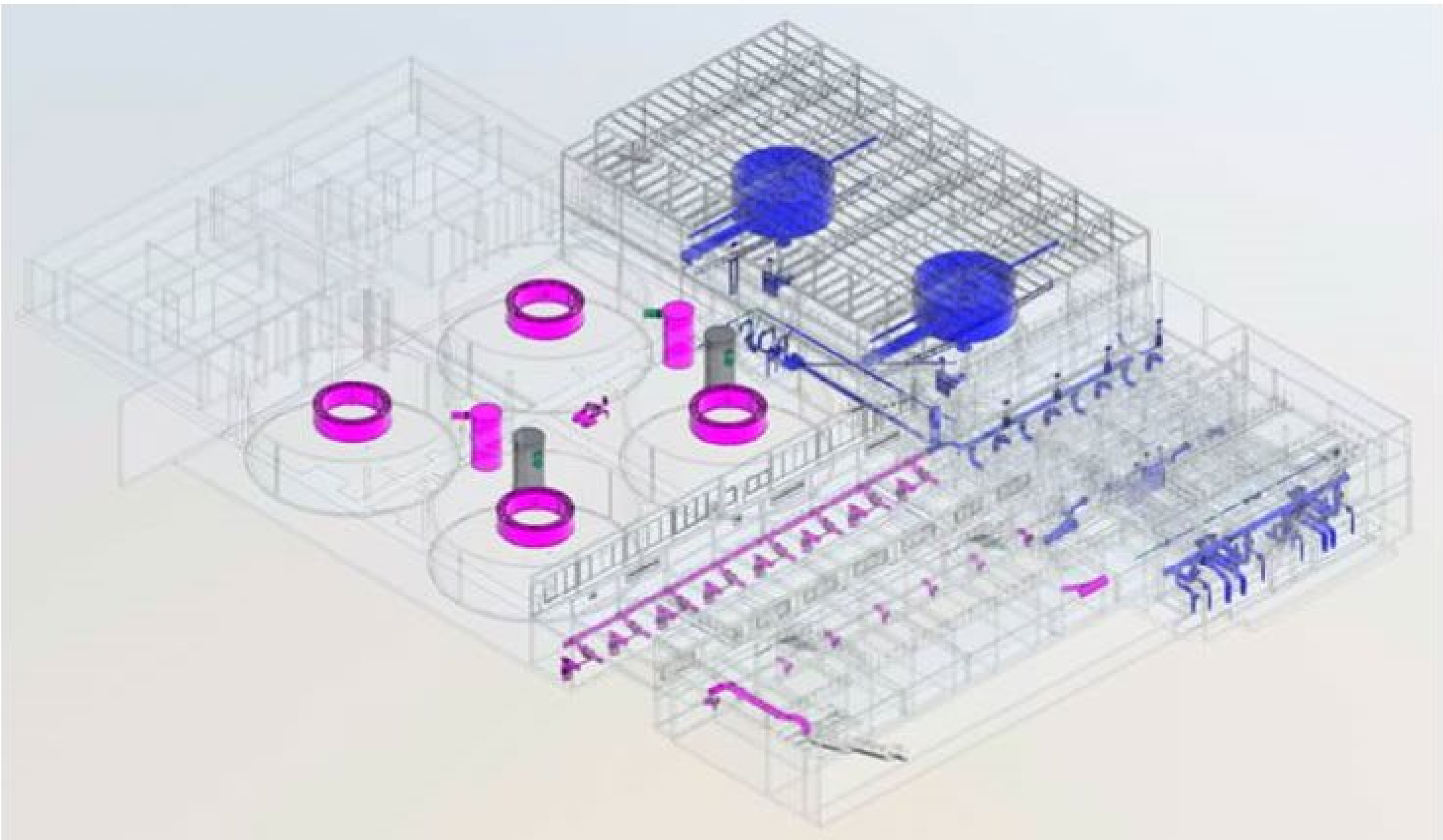
Expires Never

[Redacted]

[Redacted]

Also, because we have the model partially developed based on as-builts and partially by scans we have added a comment on every element to differentiate them.

	Model developed based on Scans
	Model developed based on As-Builts



[Redacted]

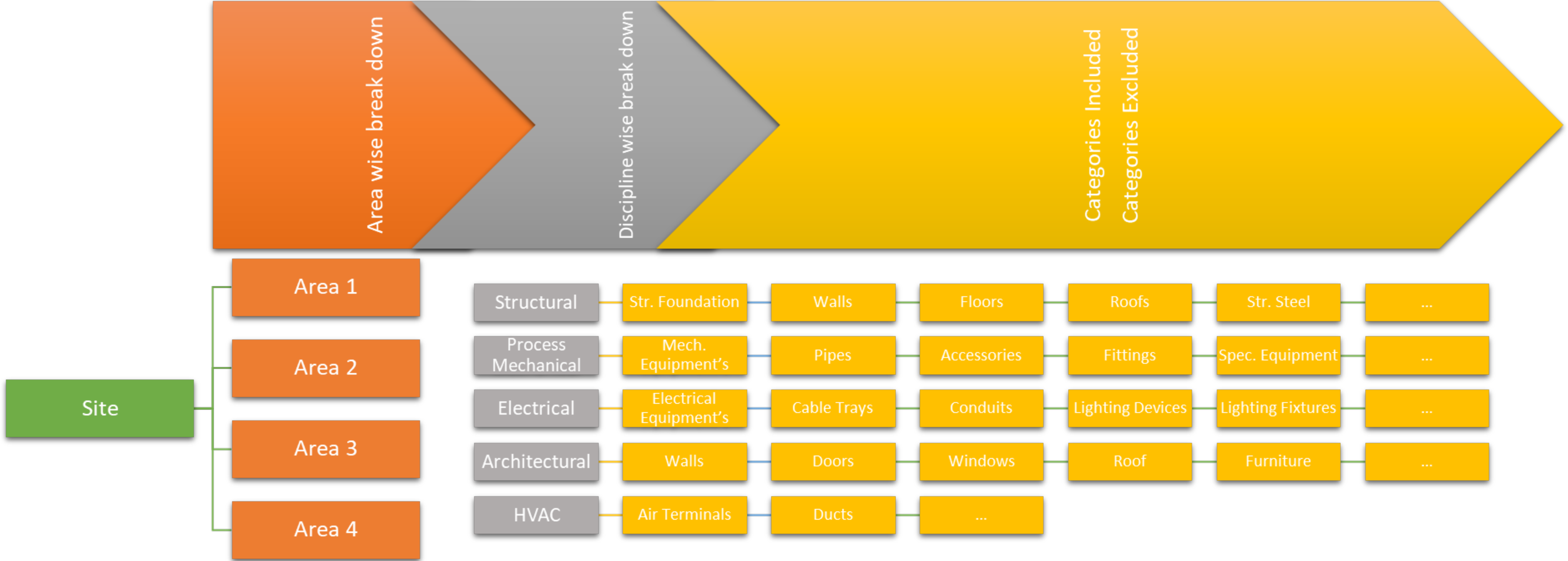
Thank you!

**Raghavendra Bhat**  
BIM Leader

## Level of Effort – What to include and what not to



# Determine - Level of Effort (LOE)



Level of Effort Estimate		
Areas	Budget	
	Process	Civil/Structural
Model Setup		
• Existing building and tanks		
• Existing storm tanks		
• Existing chemical dosing plant		
• Existing pumping station (including internal elements)		
• Existing inlet and flow control area		
• Existing PST's (4 Nos)		
• Existing tertiary plant		
• Tertiary pump station		
• Tertiary pump station inlet channel		
• Terrain (excluding below ground services)		
Model Coordination		
Total		
Inclusions		
<ul style="list-style-type: none"> <li>Steel Elements – steel columns, framing and bracing members (in AOI) – LOD200</li> <li>Concrete Elements – Concrete walls, Floors, Framings, Corbel, Bund Walls (in AOI) – LOD200</li> <li>Pipes &amp; Fittings – pipework, pipe fittings, accessories, major supports (in AOI) - LOD200-250</li> <li>Pipes with Dia 150 and larger. (If needed in AOI will need to discuss and make provision)</li> <li>Cable Trays – outline of cable tray (in AOI) - LOD150/200</li> <li>Electrical Elements – PVC pipes, switches, lights, devices (in AOI) - LOD150/200</li> </ul>		
Exclusion		
<ul style="list-style-type: none"> <li>Temporary elements will not be added</li> <li>Pipes in AOI will be added based on point cloud data. Default pipes and fittings will be used for modeling. Pipe material will not specified in model.</li> <li>Pipe dia will be considered based on scans. Pipe insulation/cover will not be considered.</li> <li>Default cable trays will be added, we may not have exact shape of cable trays in model.</li> <li>Steel connections (bolts, gusset plate) will not added.</li> <li>Sizes for steel columns, beams and bracings will be assumed to match with scans.</li> <li>Concrete curbs along roads will not be included.</li> <li>Below ground utilities will not be picked up.</li> </ul>		

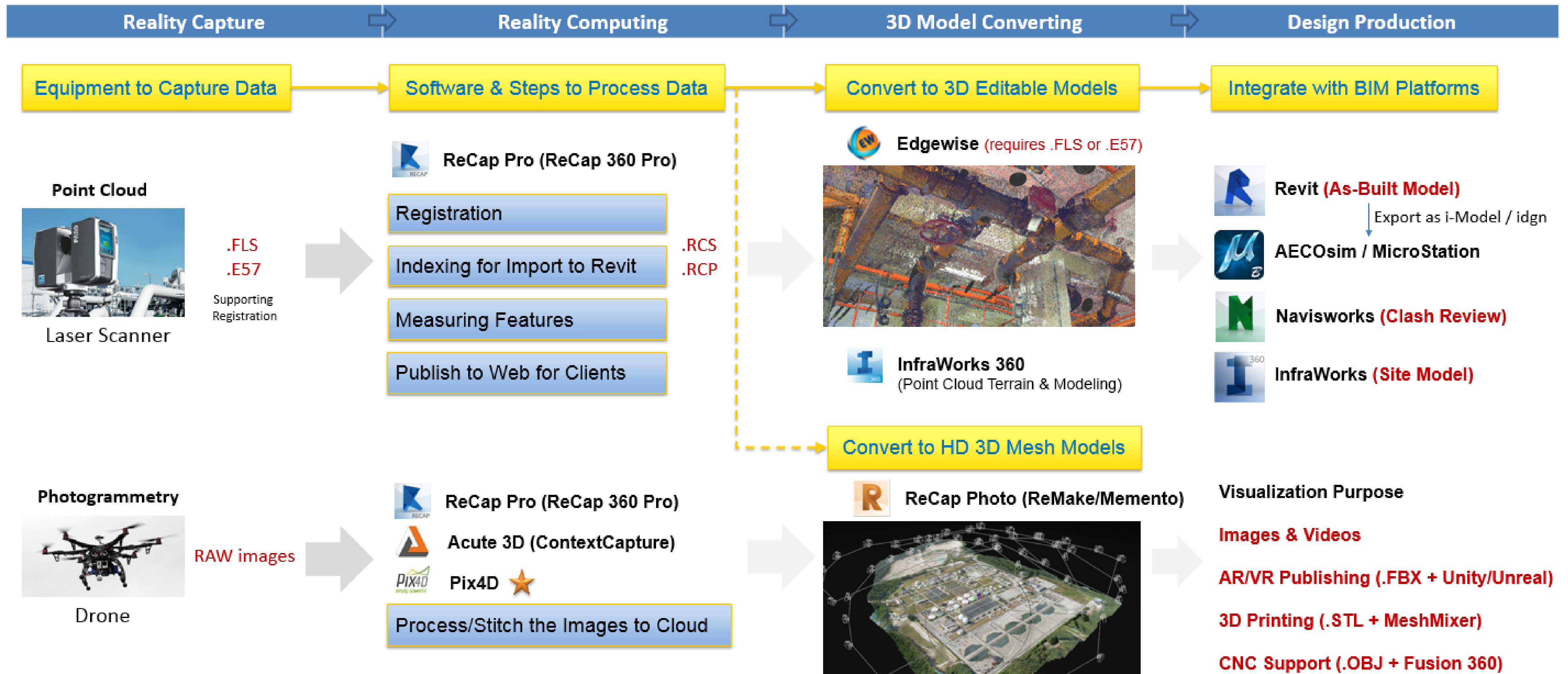
# Identifying Risks

- Verify if the coordinates are appropriate
- Verify if RGB values have been registered.
- Verify if the panoramic spears appear in Recap.
- Verify if As-builts are available.
- Verify the total size of scans & format in which it will be available.
- Verify the output format and the tools that will be used, agree on the workflow.
- Verify the Common Data Environment (CDE).
- Verify project schedule.
- Verify the Priority Areas.
- Estimation based on As-built scan PDF.

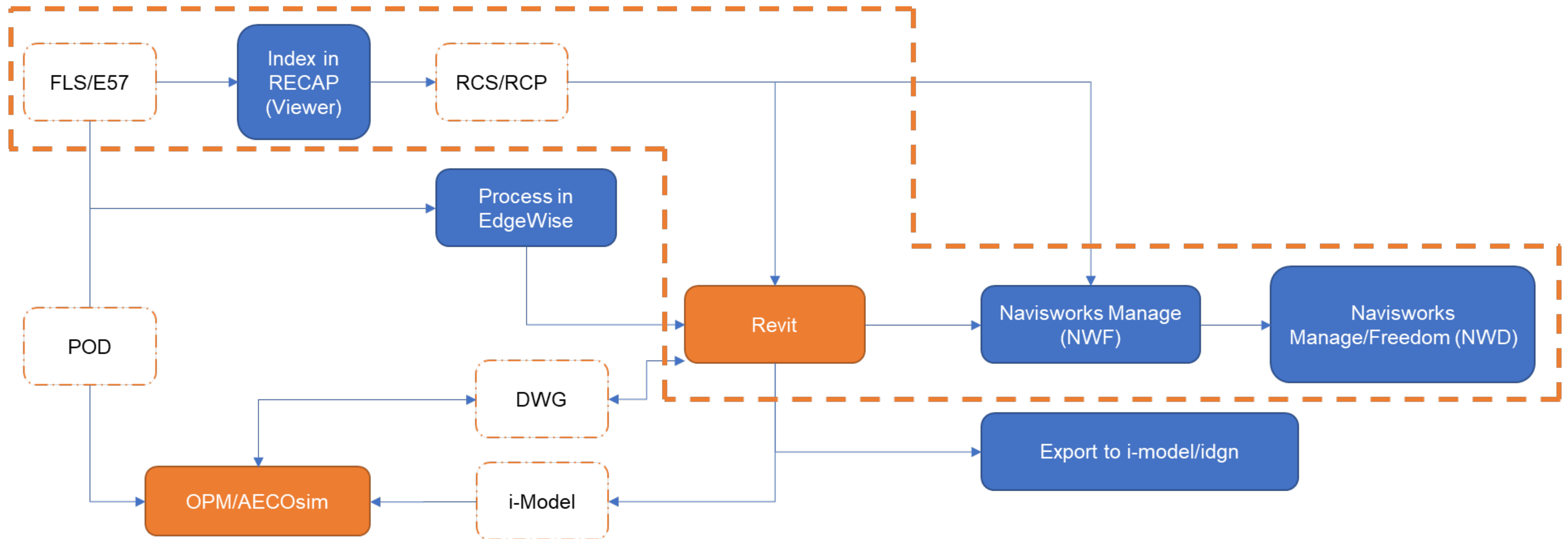
# Identifying Tools



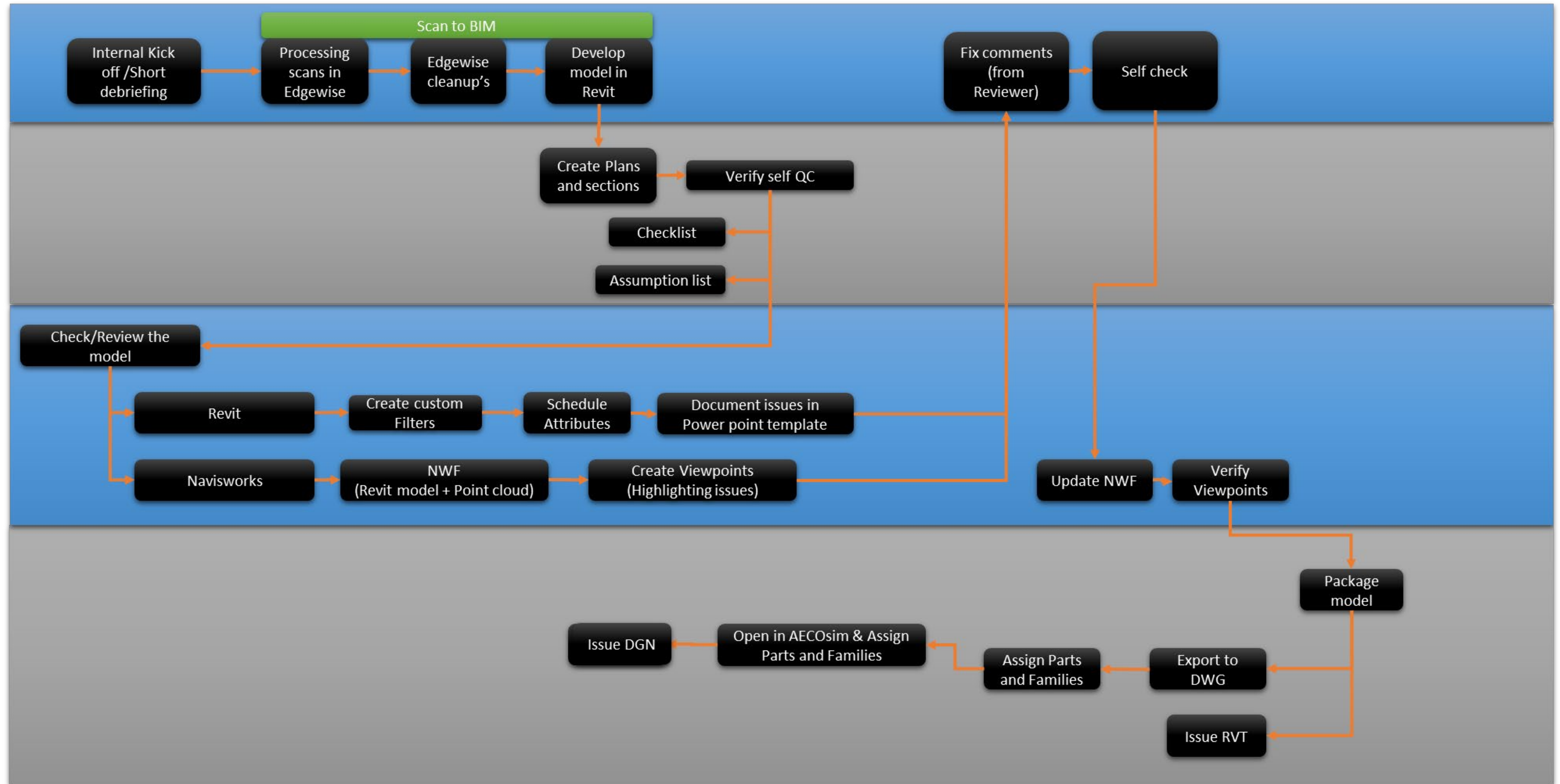
# Standardized Workflows – For Easy Implementation



# Standardized Workflows – For Easy Implementation



# Customized Workflows – For Each Project



# Automation to Copy Large Sets of Data

```
Sample.bat - Notepad
File Edit Format View Help
@echo off

SET Source="\\Source folder path"
SET Destination="C:\Local folder path"

IF NOT EXIST %Destination% md %Destination%

robocopy %Source% %Destination% /E|
PAUSE
```

```
C:\WINDOWS\system32\cmd.exe
Started : Tuesday, April 16, 2019 9:41:35 AM
Source : \\inpun1d15006\Point Cloud Data\Walnutcreek_rework\ReCap\
Dest : C:\Point Cloud Data\Walnutcreek_rework\ReCap\

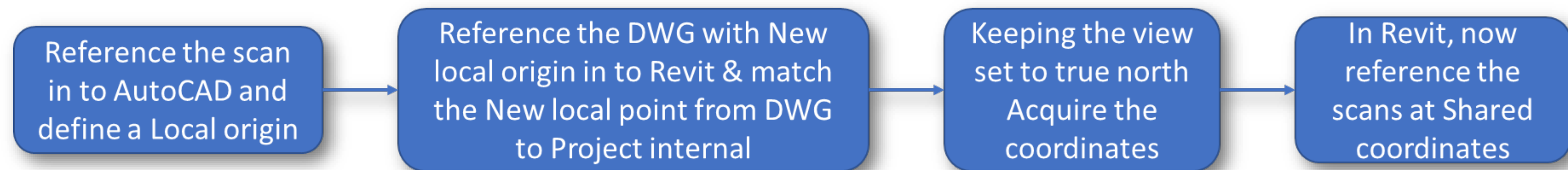
Files : *.*

Options : *.* /S /E /DCOPY:DA /COPY:DAT /R:1000000 /W:30

-----
100%      New File           1  \\inpun1d15006\Point Cloud Data\Walnutcreek_rework\ReCap\
      New Dir              245  Walnutcreek.bat
100%      New File           2  \\inpun1d15006\Point Cloud Data\Walnutcreek_rework\ReCap\Recap\
      New File              0  AutodeskReCap.log
100%      New File          785301  Walnutcreek_rework.rcp
      New Dir              3  \\inpun1d15006\Point Cloud Data\Walnutcreek_rework\ReCap\Recap\Walnutcreek_rework Support
t\
100%      New File          1734  Walnutcreek_rework.rcp.bk1
100%      New File         104144  Walnutcreek_rework.rcp.bk2
100%      New File          774223  Walnutcreek_rework.rcp.bk3
      New Dir              0  \\inpun1d15006\Point Cloud Data\Walnutcreek_rework\ReCap\Recap\Walnutcreek_rework Support
t\Temporary Cache Files\
      New Dir            112  \\inpun1d15006\Point Cloud Data\Walnutcreek_rework\ReCap\Walnut creek Support\
100%      New File          188.1 m  walnut creek registration_1-0.rcs
100%      New File          193.4 m  walnut creek registration_1-1.rcs
100%      New File          205.5 m  walnut creek registration_1-10.rcs
100%      New File           48.7 m  walnut creek registration_1-100.rcs
100%      New File           36.9 m  walnut creek registration_1-101.rcs
100%      New File           45.5 m  walnut creek registration_1-102.rcs
46.8%     New File           46.9 m  walnut creek registration_1-103.rcs
```

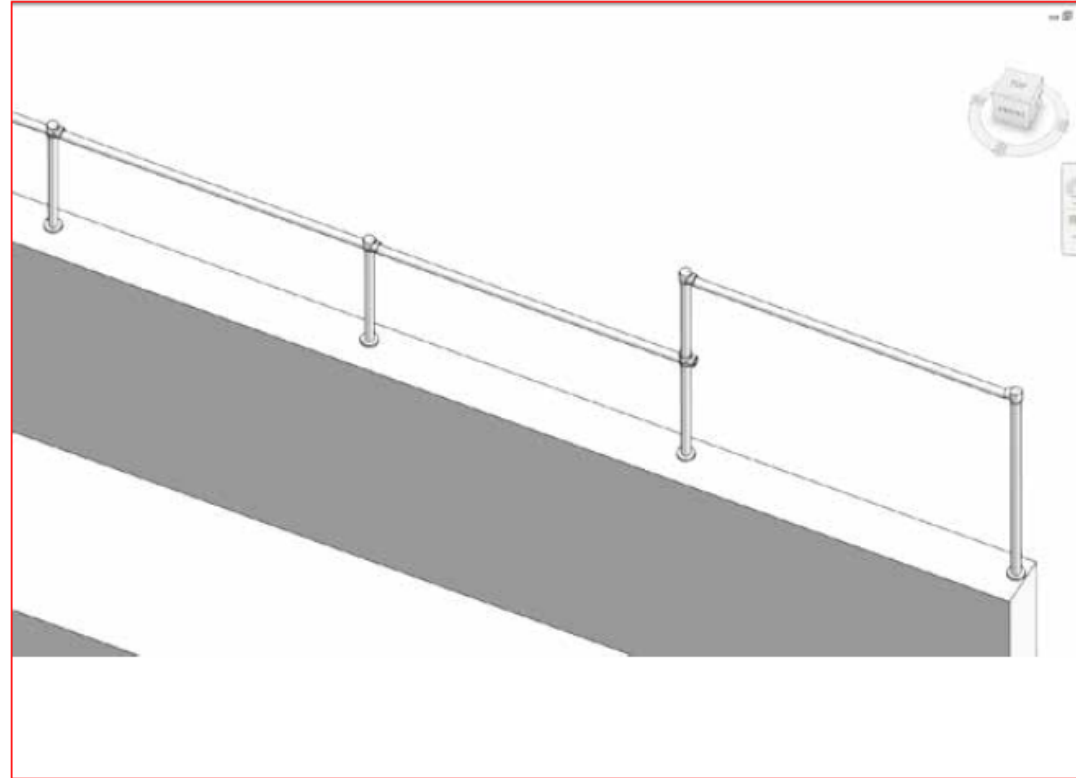
# Model Setup (Guideline)

- Always use the point cloud scan coordinates to setup the shared coordinates in Revit – in that way it will help align your model to it when exported to world coordinate.
- Have an independent Revit model with scans loaded into it. Beneficial when there are more than one discipline working on independent As-built Revit models.



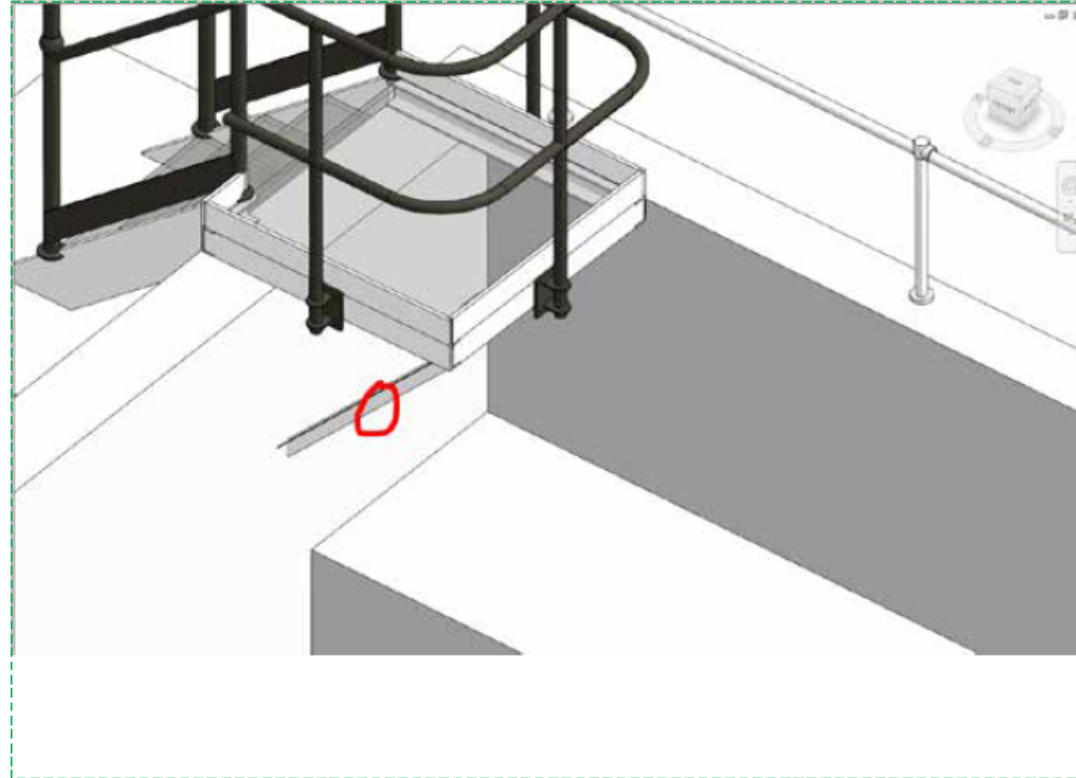
# Document the Discrepancies / Assumptions

Assumptions



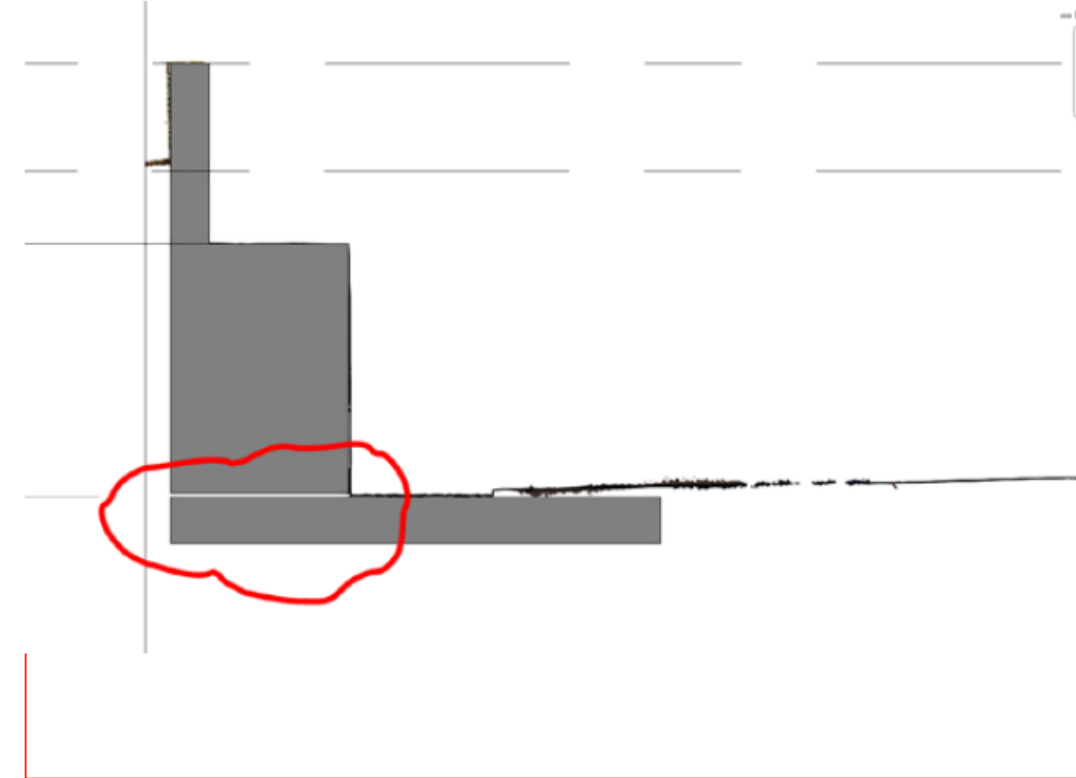
Railing types are used from OTB library. We have matched post locations to scans and post type is shown identical.

Assumptions



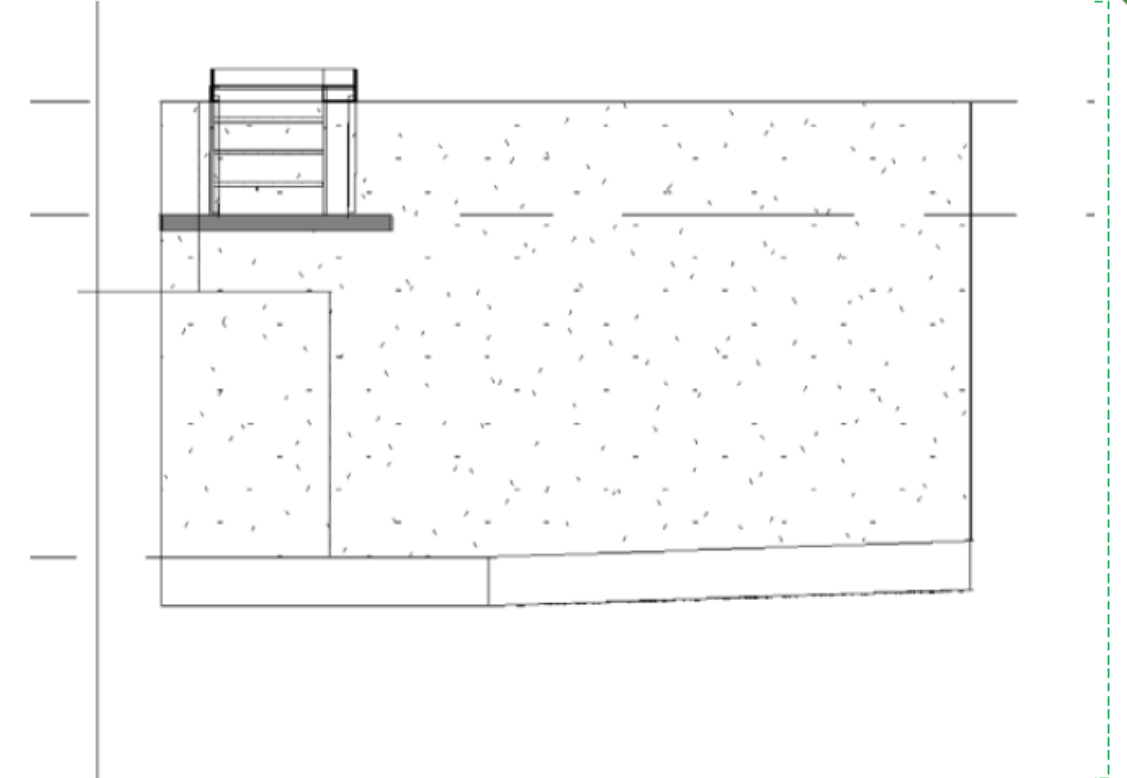
Default railing type is used which might not match with existing condition.

Reviewer observation



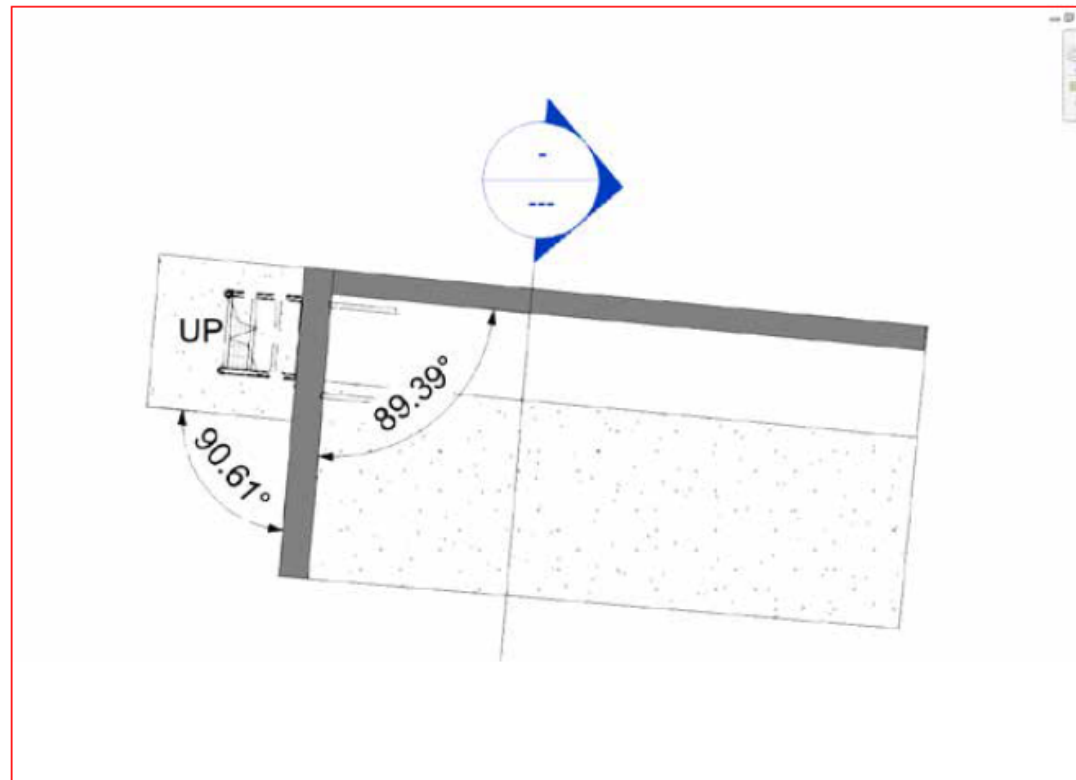
Remove this gap, attach bottom of the wall to top of slab.

Snap from updated model



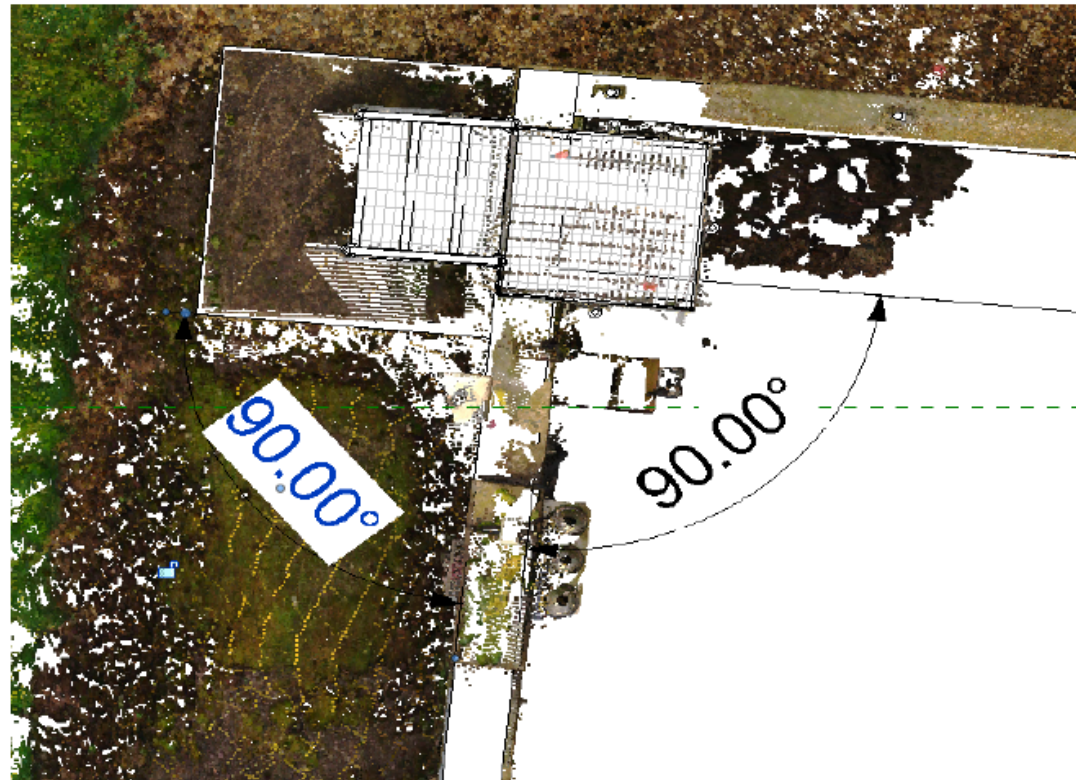
Gap is removed and slope in bottom slab is incorporated.

Reviewer observation



Make corner of walls with 90 degree.

Snap from updated model



Update model as per comments.

Reviewer observation



Add this chamber, you can assume depth.

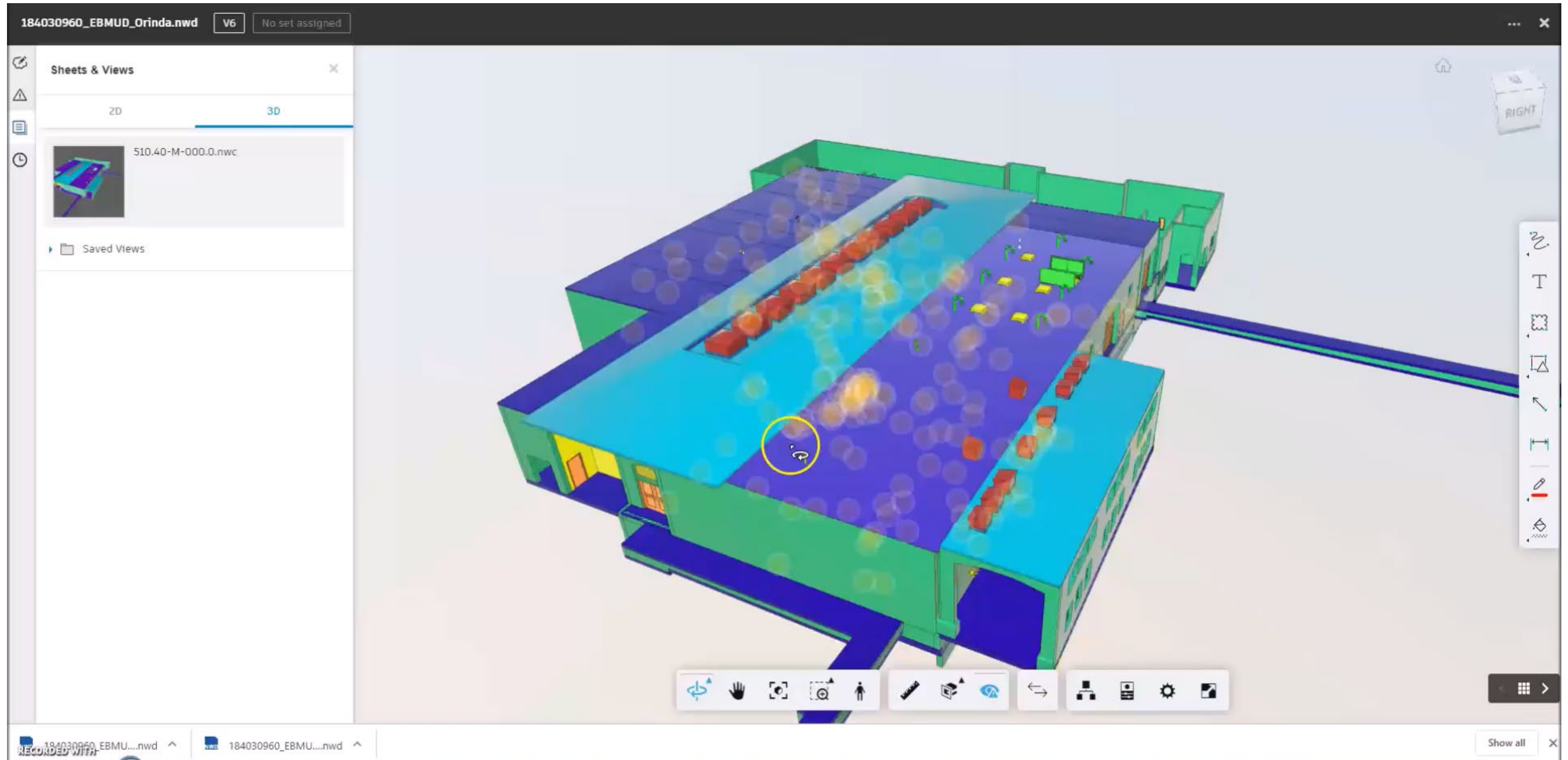
Snap from updated model



Location of chambers traced from scans. We are not sure what will be the depth of these chambers, hence depth is assumed.

"Perfect 90 degree angles do not exist."

# Progressive Review using BIM 360



# Quality Control (QC)

## Checklist for Scan to BIM team – Structural and Architectural

- ☐ Verify if, correct levels/Grids established & appropriately named in model?
- ☐ Verify if, all wall corners are aligned at 90 degree (typically)
- ☐ Verify if, All internal dimensions have a round off values? (should be in multiples of 25mm, avoid decimals)
- ☐ Verify if, walls are positioned parallel ?
- ☐ Verify if, appropriate material are assigned to elements? (Need to use OTB textures, if using new textures need to make sure you inform everyone in the project, esp. who are working with the models )
- ☐ Is there are any in-place elements added in model, verify to have correct category and material assigned to these?
- ☐ Verify if all as-built elements modelled are in existing phase? (use default phasing do not create new phases unless instructed)
- ☐ Verify if, all elements are placed in right category? (specifically for mechanical, electrical Equipment's, specialty equipment's)
- ☐ Is there view created in project browser for Navisworks export/Glue export? If Yes then verify below points
  - ☐ Turn off all annotation categories from visibility settings.
  - ☐ Turn off all analytical categories from visibility settings.
  - ☐ Turn off all imported categories if not required.
  - ☐ Turn off unwanted Revit links if not required to export
  - ☐ Switch off building pads, Mass, project base point, survey point and line category from visibility graphics.
  - ☐ Set correct phase and phase filter for views from property pallet.
  - ☐ Set correct detail level (Fine view) and part visibility (if used divide parts to show construction joint or precast wall panels)
  - ☐ Lock view orientation and turn off section box, uncheck crop/crop box option from property pallet if not required.
  - ☐ Is required view exported by Shared coordinates?
  - ☐ If view exported in any format, open it and check everything looks ok then publish to glue
  - ☐
- ☐ Link all Revit or CAD files from same common data environment

## Checklist for Scan to BIM team – Process mechanical/HVAC

- ☐ Are all Grids/Levels copied (copy monitored) from origin model?
- ☐ Is origin model is attached for reference as shared coordinates? (Link reference models from common data environment)
- ☐ Are all elements are covered based on SOW?
- ☐ Are all elements modelled with correct LOD?
- ☐ Are all pipe fittings and accessories hosted with pipes and connected with pipe systems?
- ☐ Are all equipment families added in right category? (like pumps, mechanical equipment, electrical equipment, specialty equipment etc..)
- ☐ Are all pipes/cable trays parallel to the structural walls/elements?
- ☐ Is there pipe penetrations provided in structural model? (will be depends on LOD requirement)
- ☐ Refer above listed points for view setup and common checks (shown in RED)

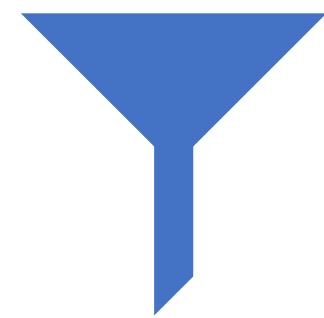
## Initial Checklist at Kickoff

- ☐ Has the scan data copied/replicated with correct file size on replication server & includes all supporting files?
- ☐ Has the scan data registered RGB values?
- ☐ Does the scan data include the spears?
- ☐ Does the Scan have ghosting appearance where multiple areas overlap?
- ☐ Does the scans have the right world coordinates registered? Verify by referencing it into C3D? (verify with historical data if available)
- ☐ Verify who owns the Project/model setup?
- ☐ Verify if appropriate template has been used for project/model setup?
- ☐ Verify which version of the application is to be used for the defined project
- ☐ Verify if the coordinate have been set in the base template?
- ☐ Verify you have reviewed the SOW document to read through the LOD requirements.
- ☐ Verify the CDE requirements.
- ☐ Verify if the SOW has the final deliverables formats specified, also need to have the workflow defined in the SOW document.
- ☐ Verify if the project has BIM 360 Glue project set up.

# Revit QC Process



Create Plan and Sections  
for Self Check Plots



Use of Filters

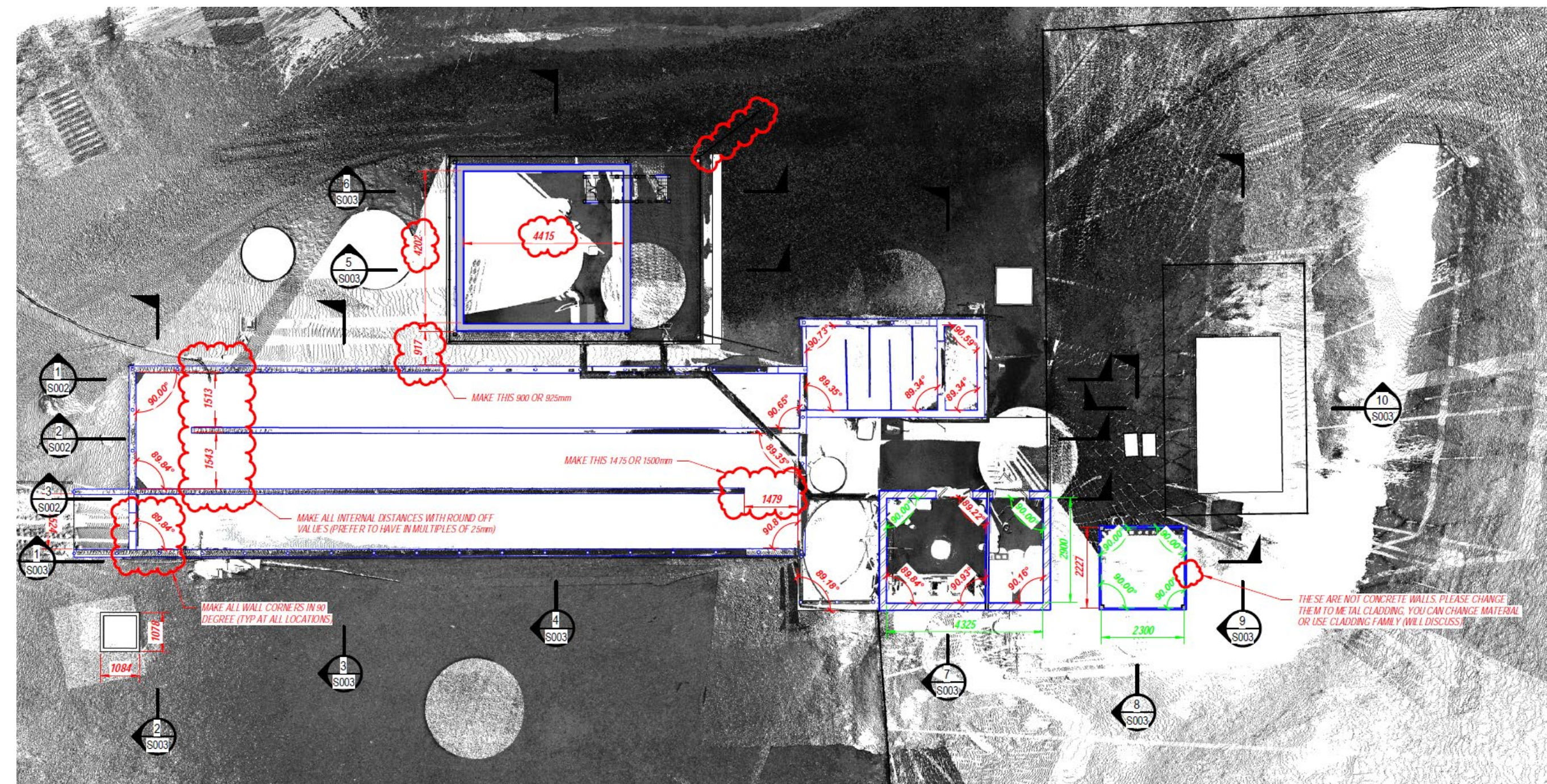
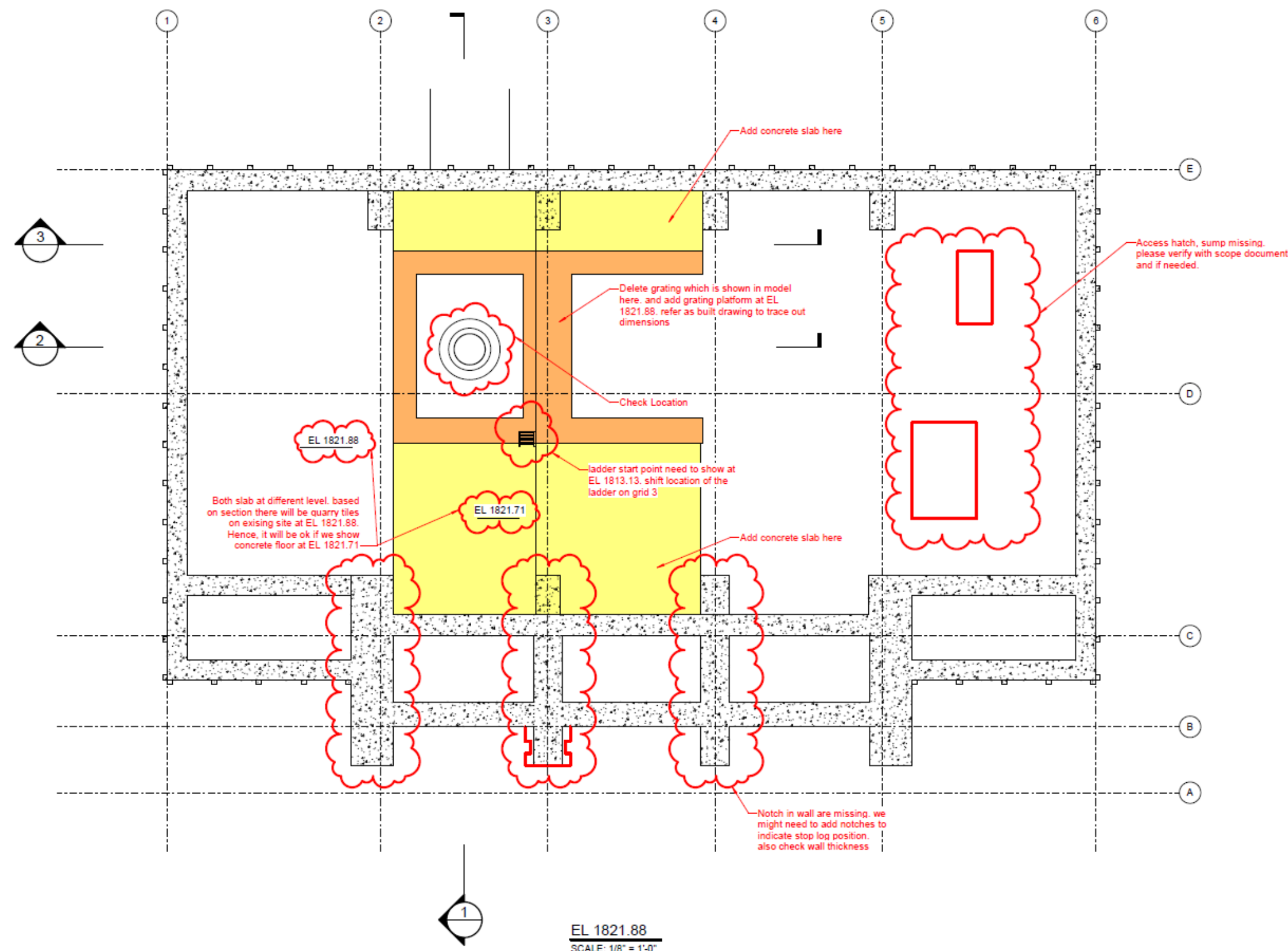


Templates

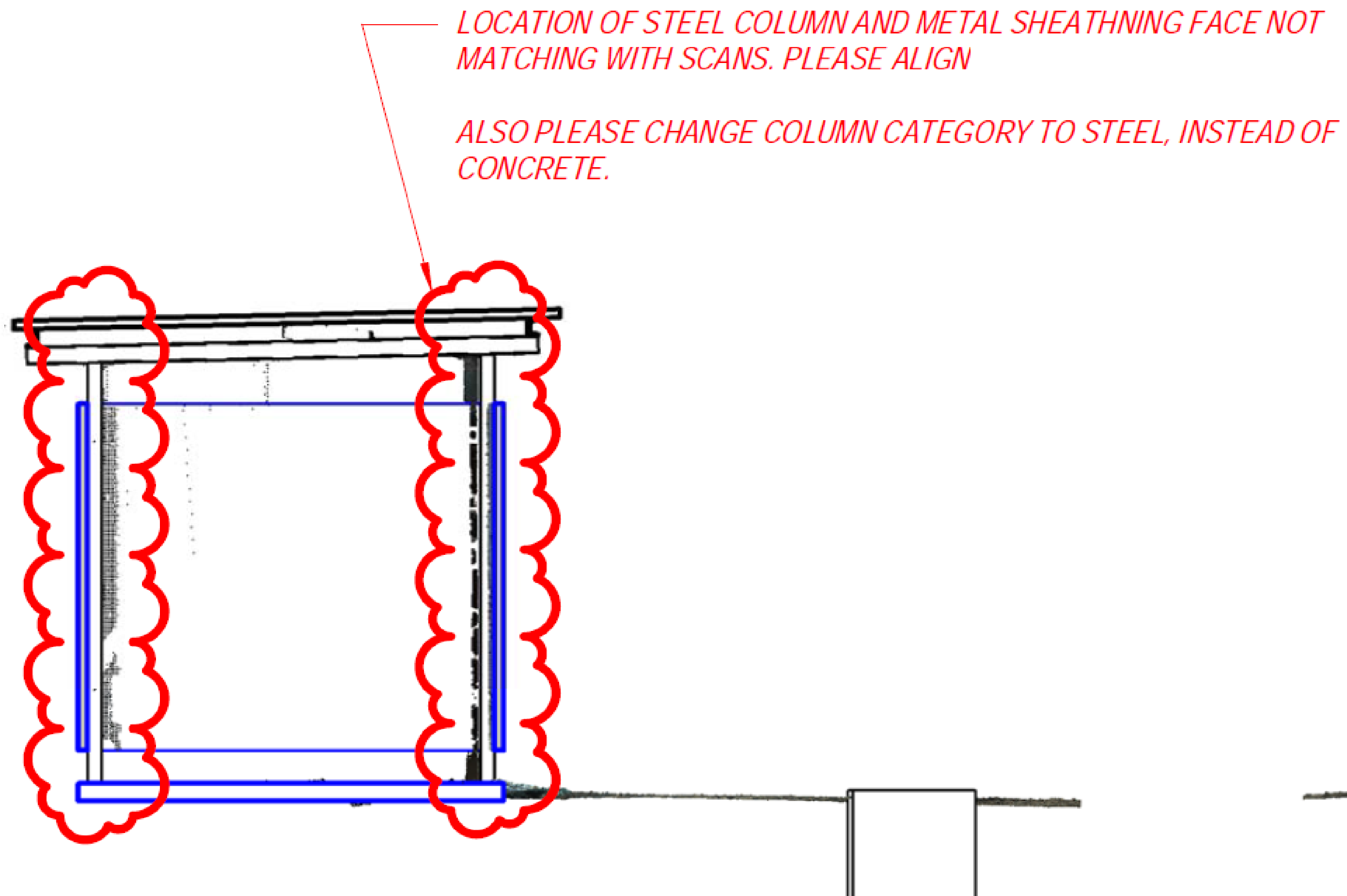


Purge and clean

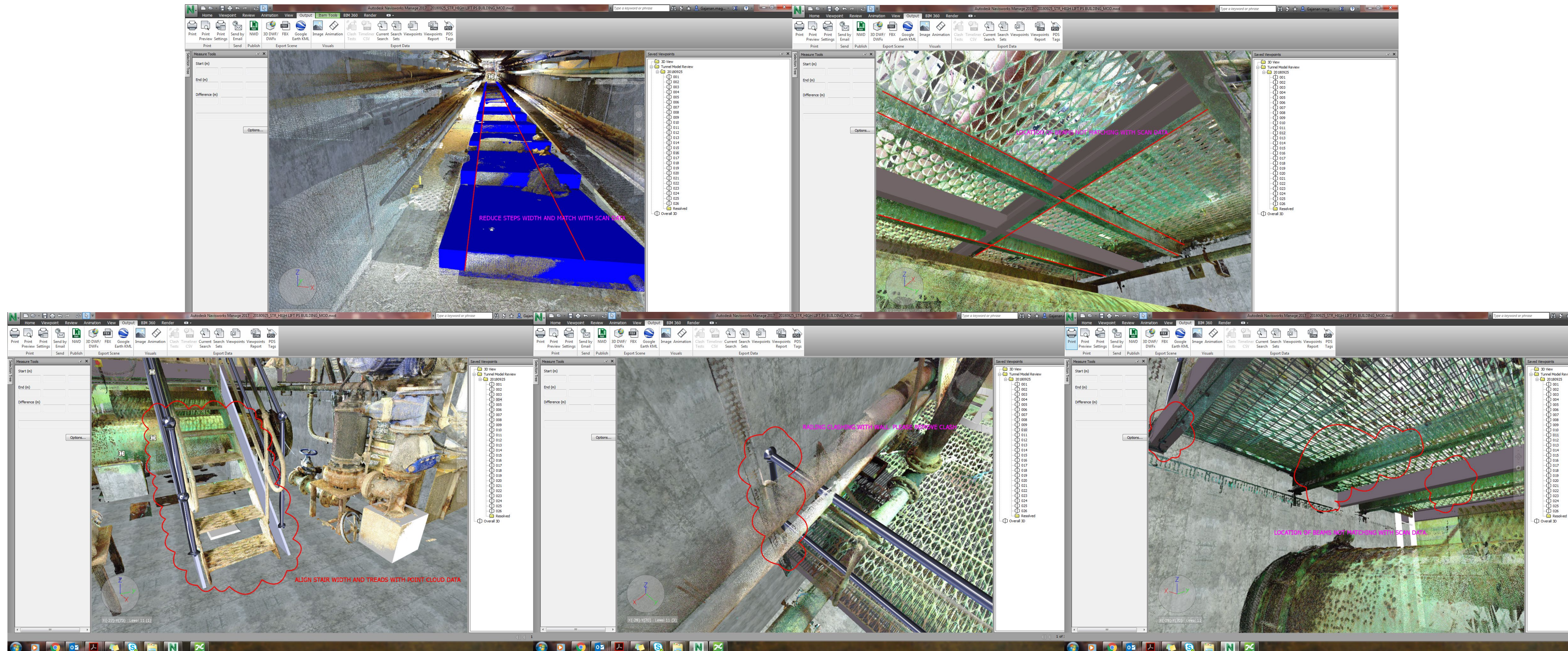
# Revit QC Process – Plans and Sections for Self Check

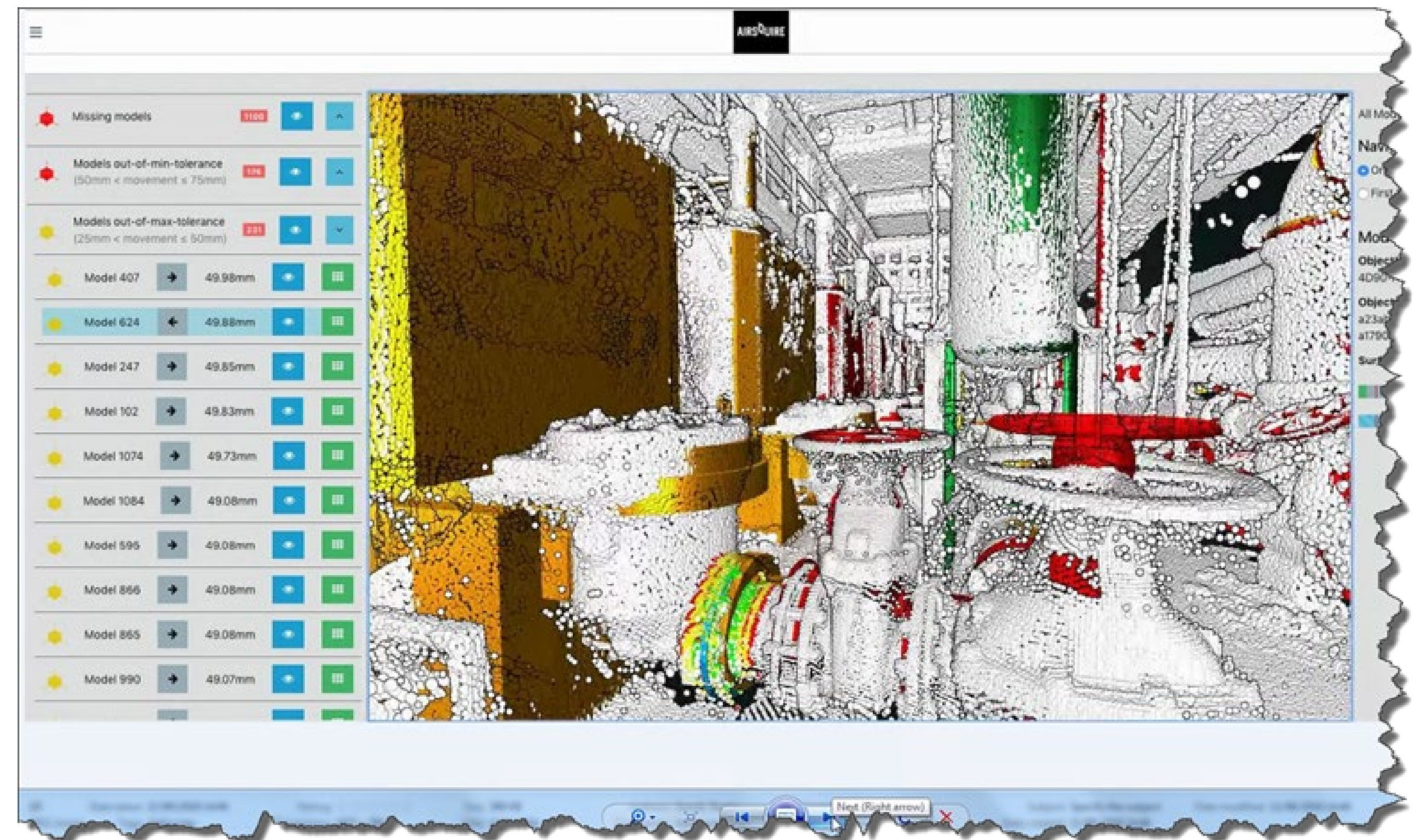
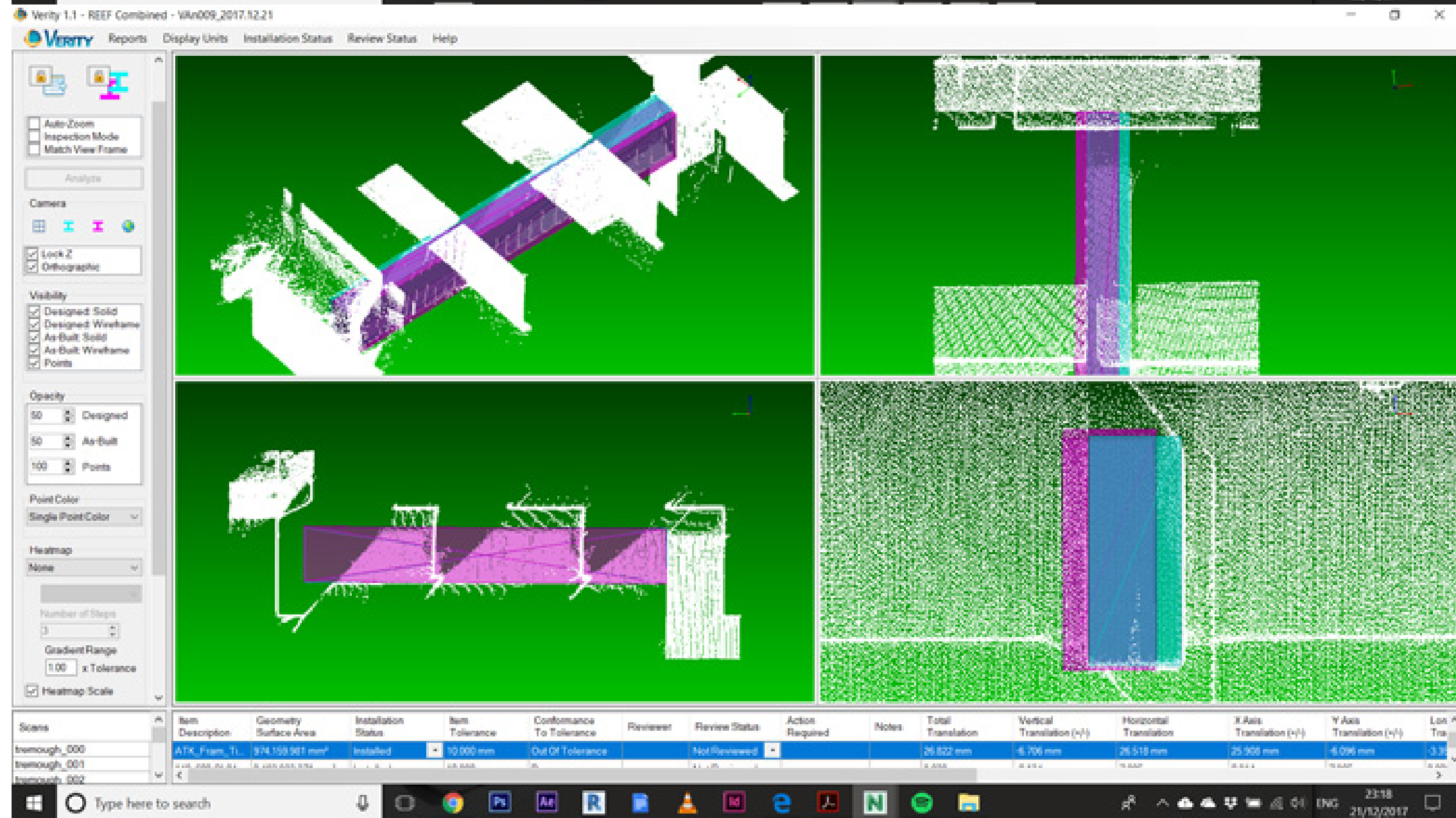
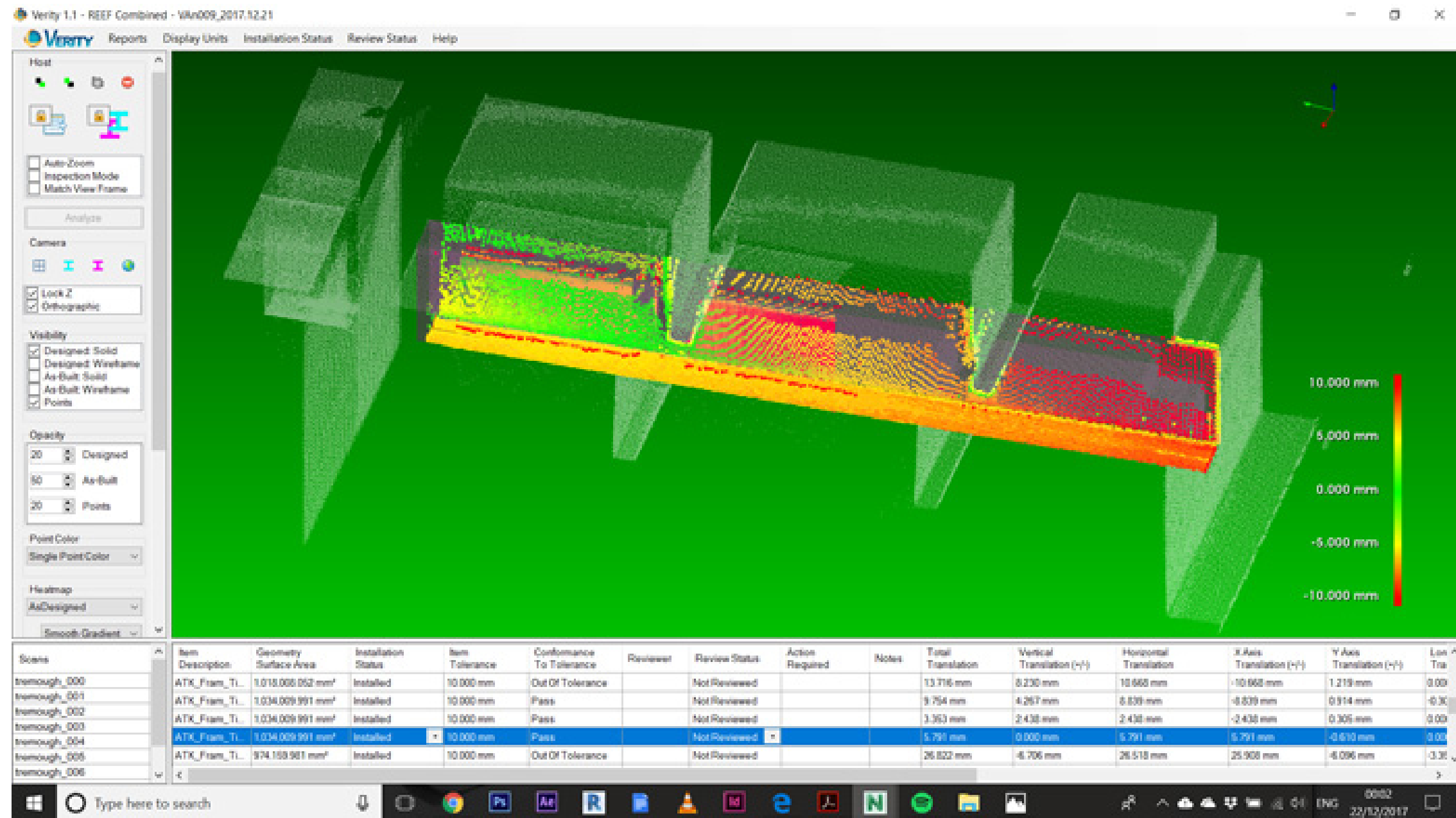


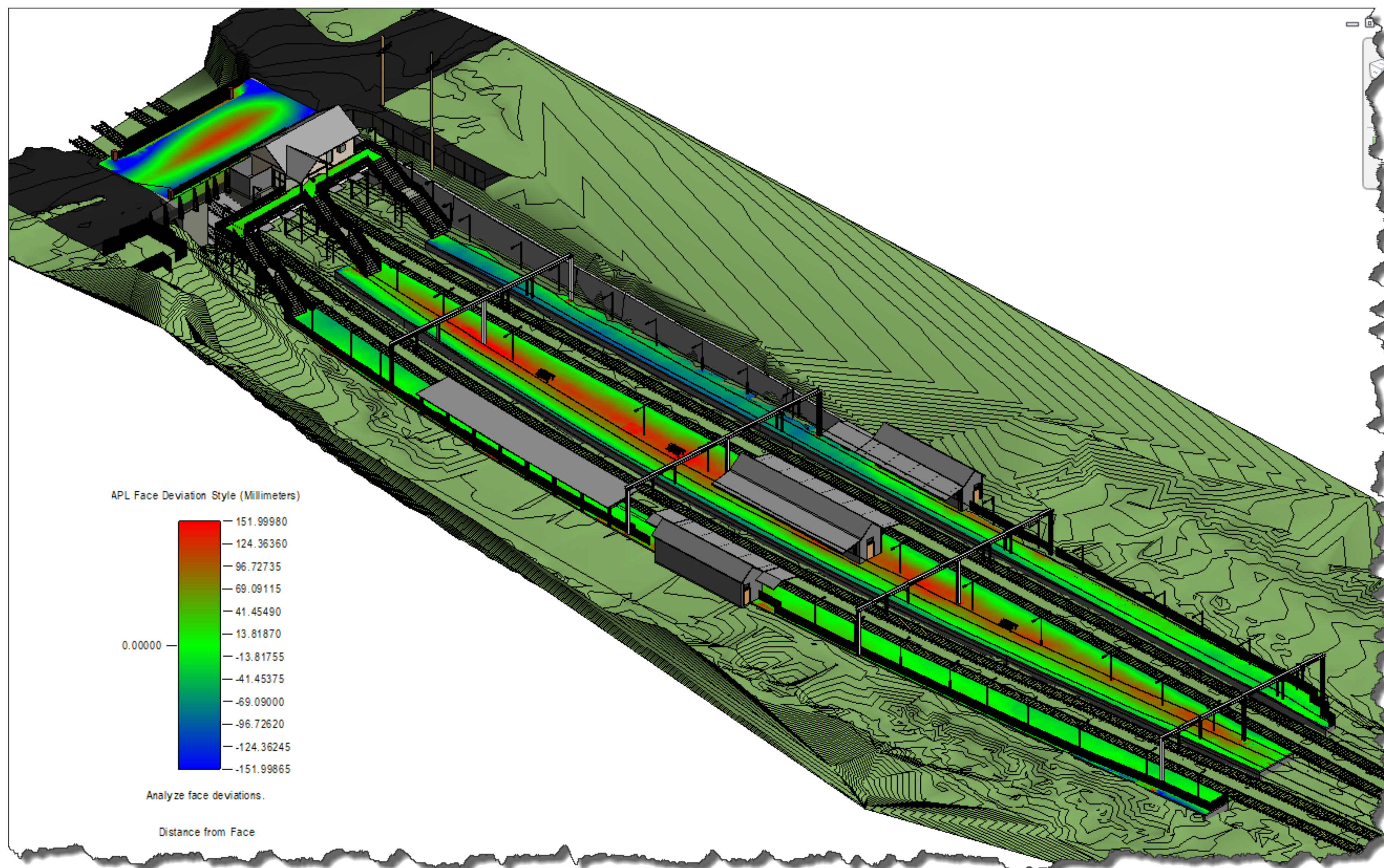
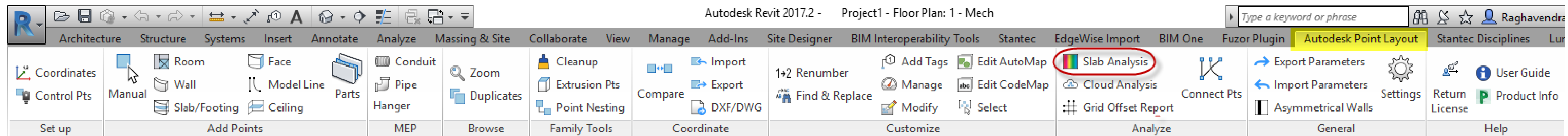
# Revit QC Process – Use of Filters



# Navisworks QC Process







# Model Health Checkup

Credits: Autodesk BIM Interoperability Tools

Download and install the ["Autodesk Model Checker"](#)



Batch run the Checker in Revit



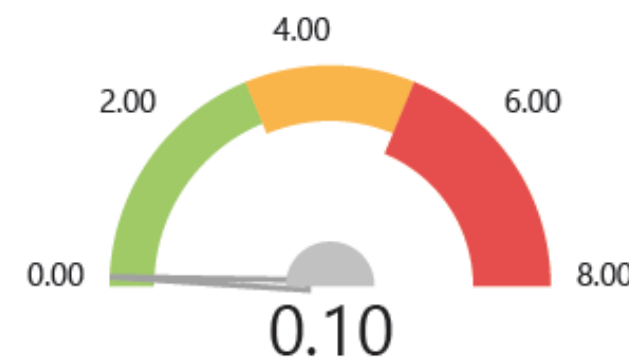
Export the report to an Excel file



Use the [Microsoft PowerBI template](#), to read the results from the exported Excel and graphically display as below.

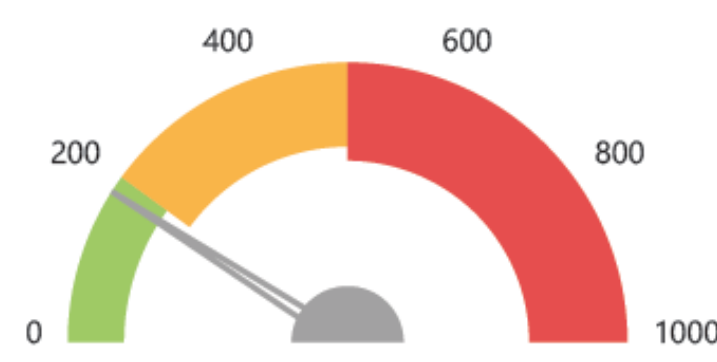
BWTP\_M  
Model Health Latest Dashboard

Warnings Per MB



19

Total Warnings

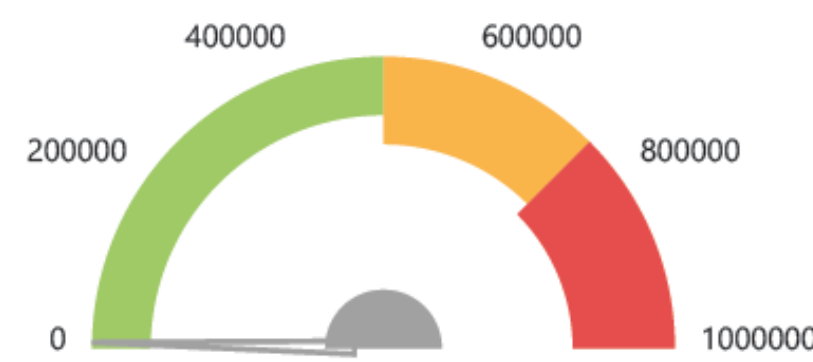


181

File Size in MB

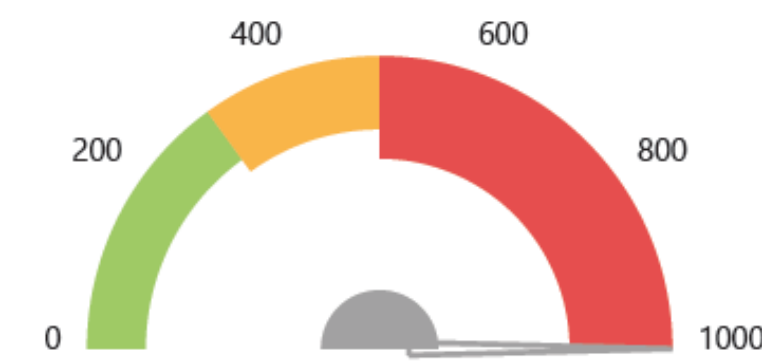
Last run report

Friday, September 13, 2019



6377

Total Elements



1812

Purgable Elements

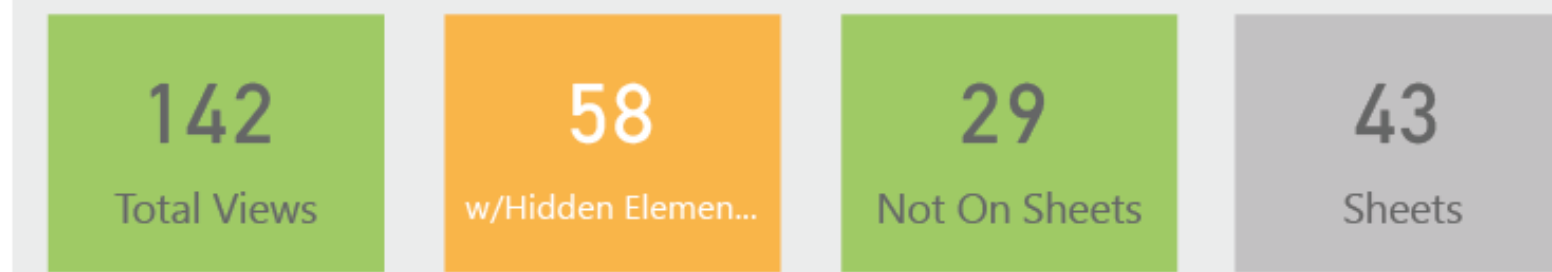
## Elements Performance



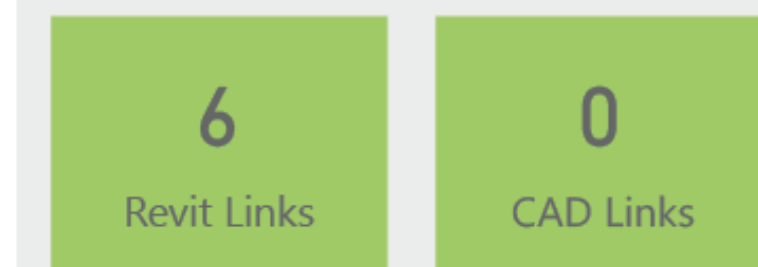
## Imports



## Views



## Links



## Worksets and Options

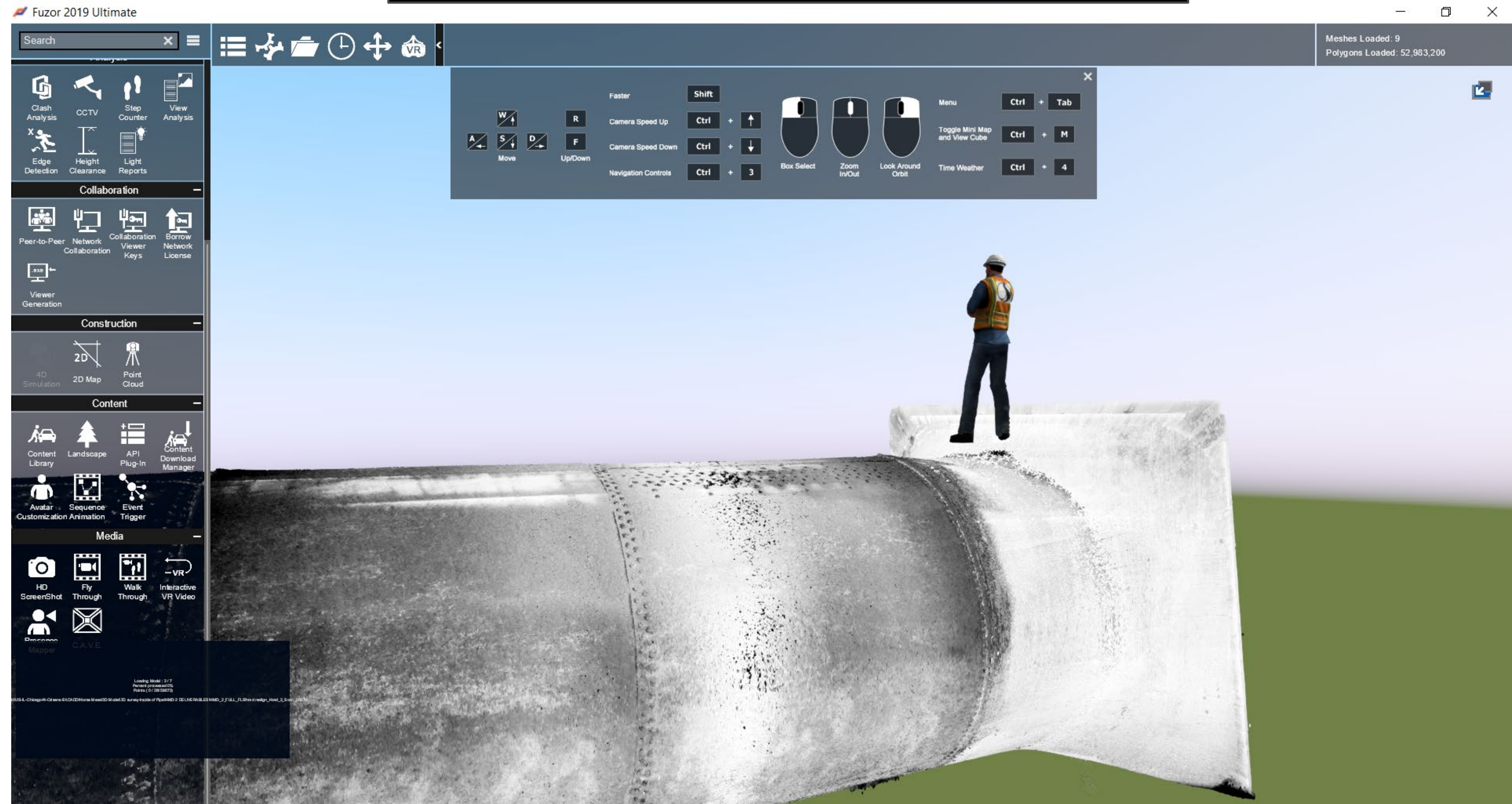


# Integrating XR with Point Cloud



# Viewing Point Cloud from VR

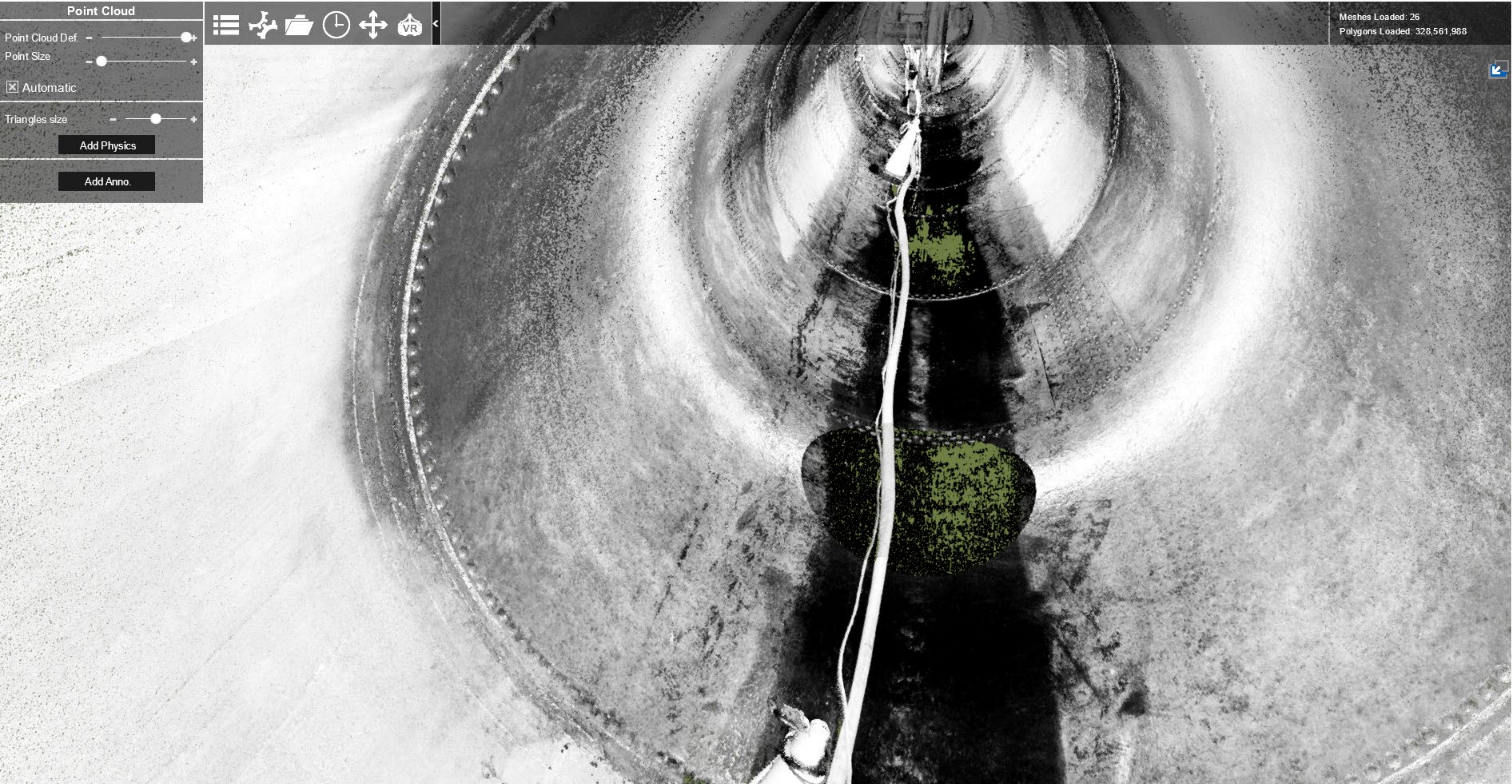
(1) FLS or PTS > Fuzor > VR Headset





Meshes Loaded: 17  
Polygons Loaded: 208,583,330





Point Cloud

Point Cloud Def. 

-

+

Point Size 

-

+

☒ Automatic

Triangles size 

-

+

Add Physics

Add Anno.



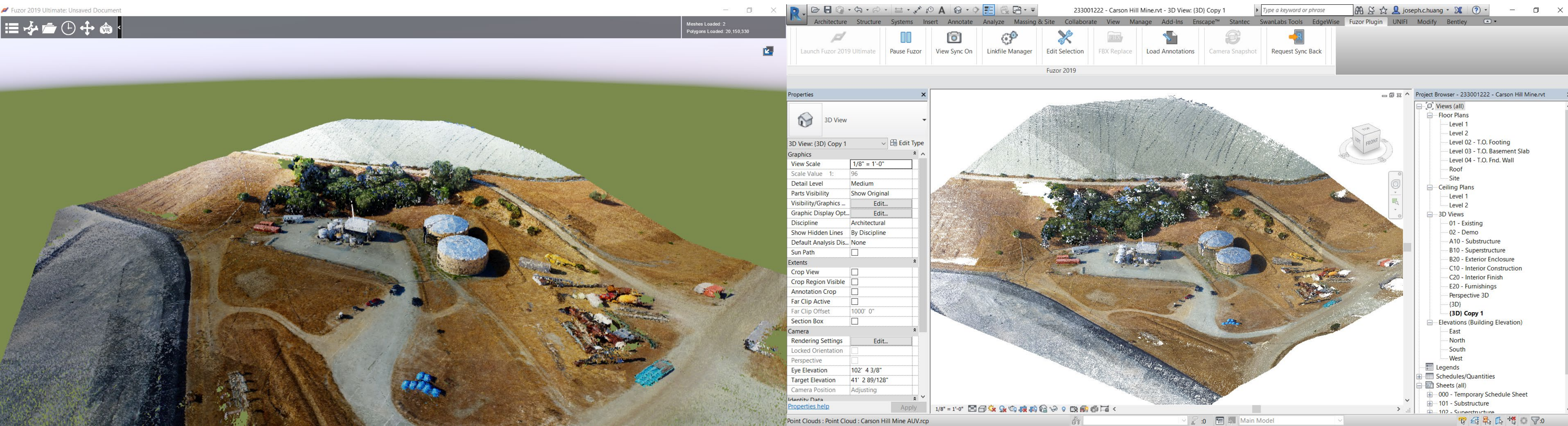
Meshes Loaded: 26

Polygons Loaded: 328,561,988

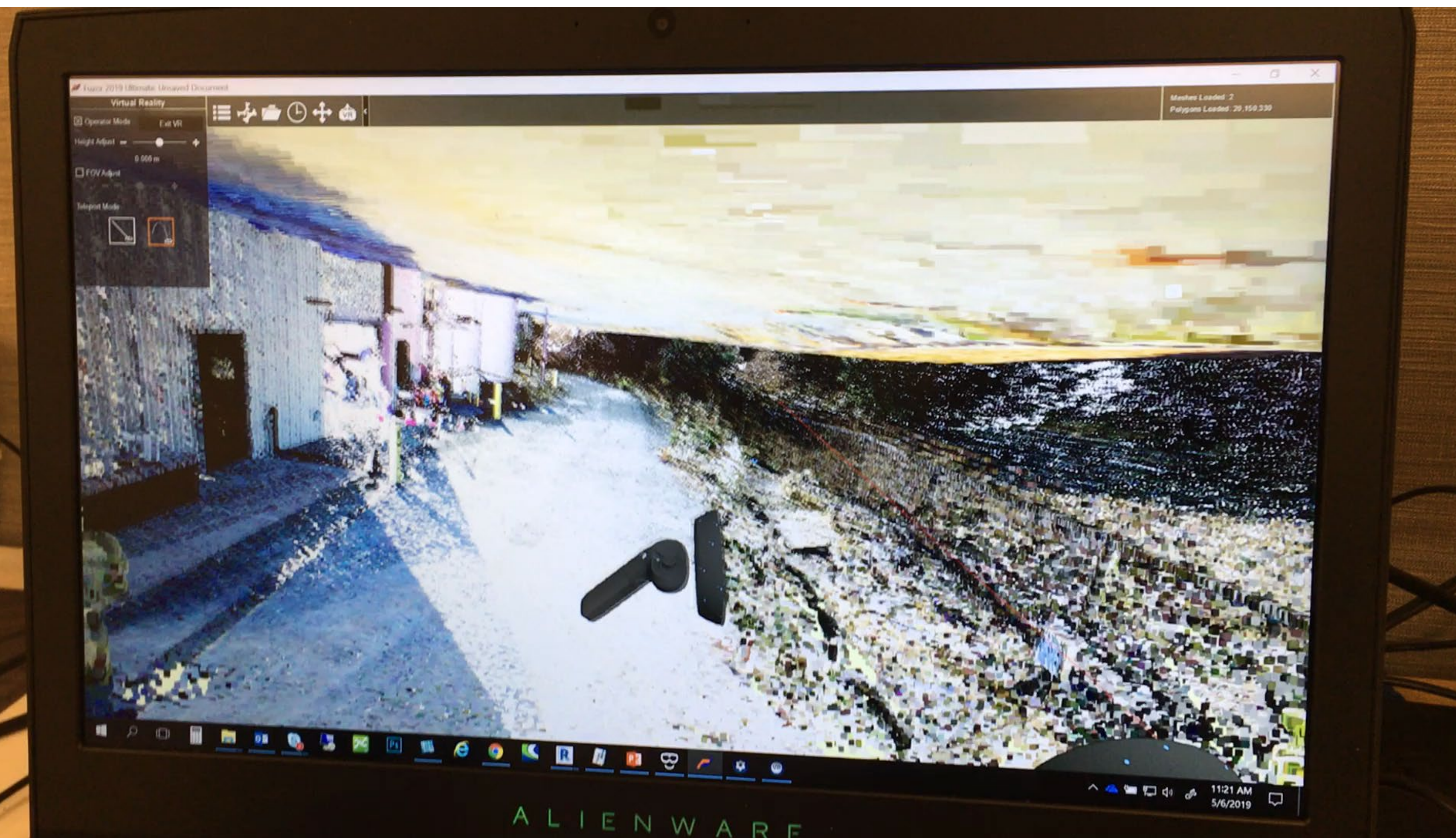


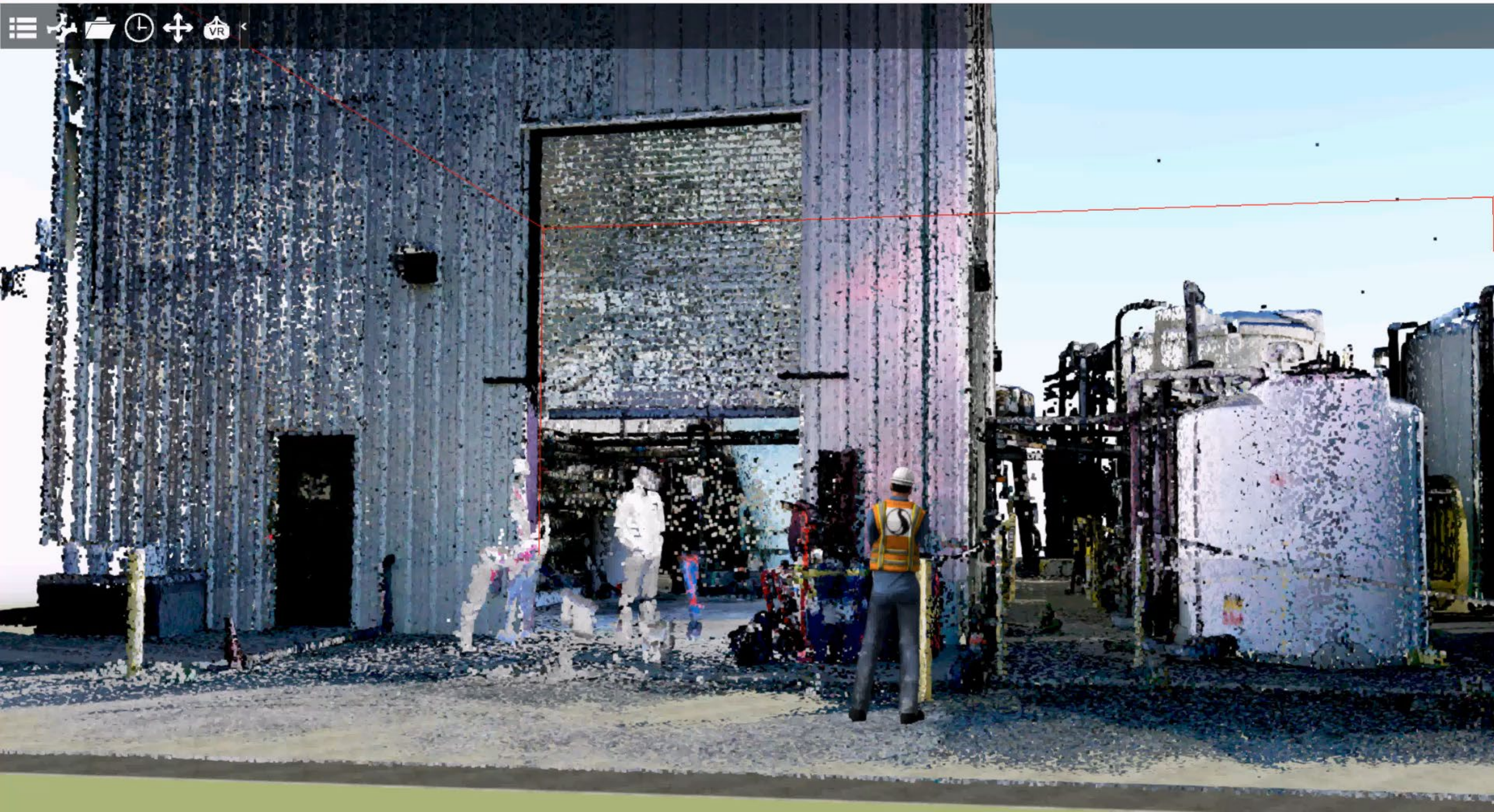
# Viewing Point Cloud from VR

(2) RCP/RCS > Revit > Fuzor > VR Headset



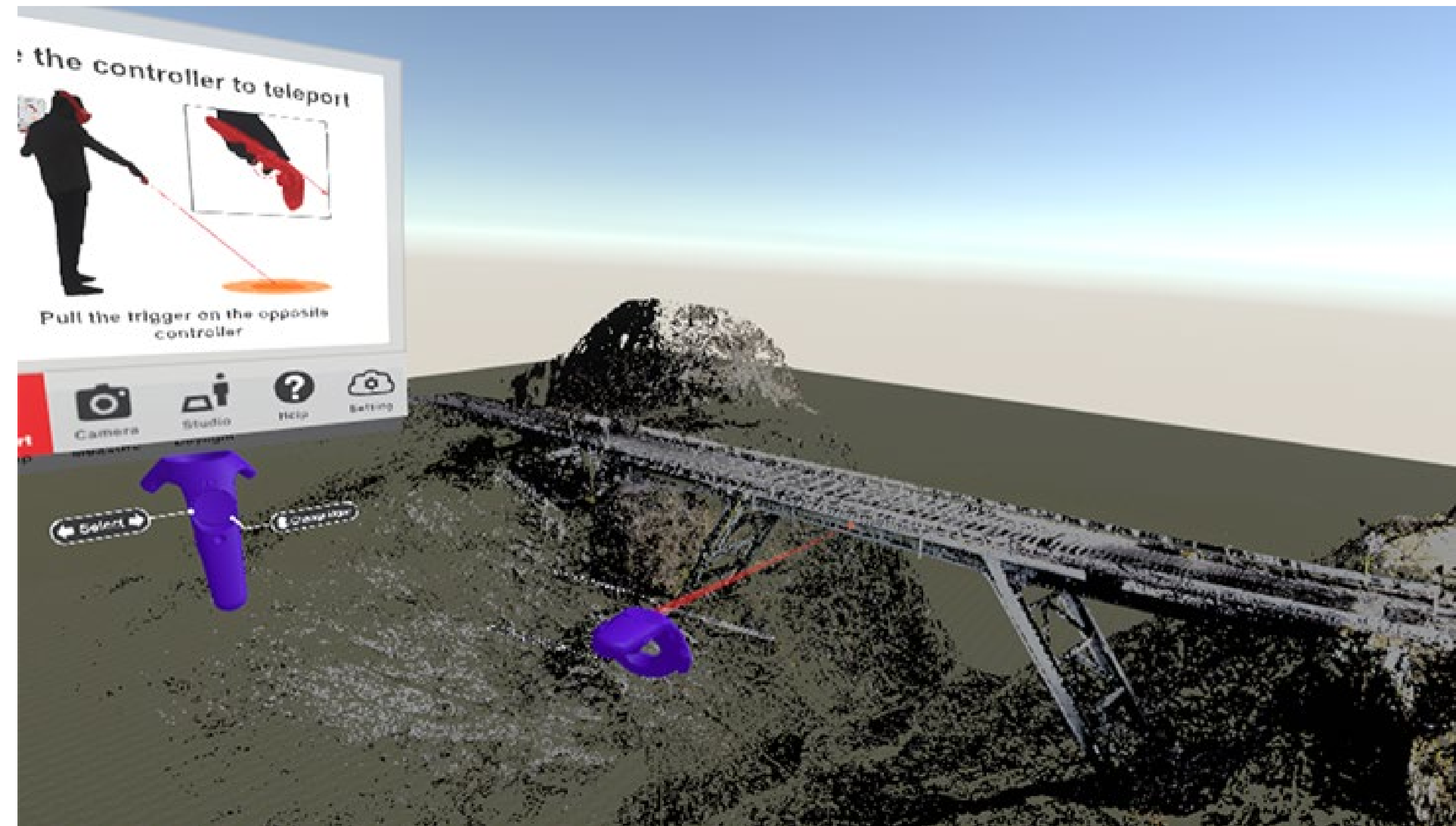
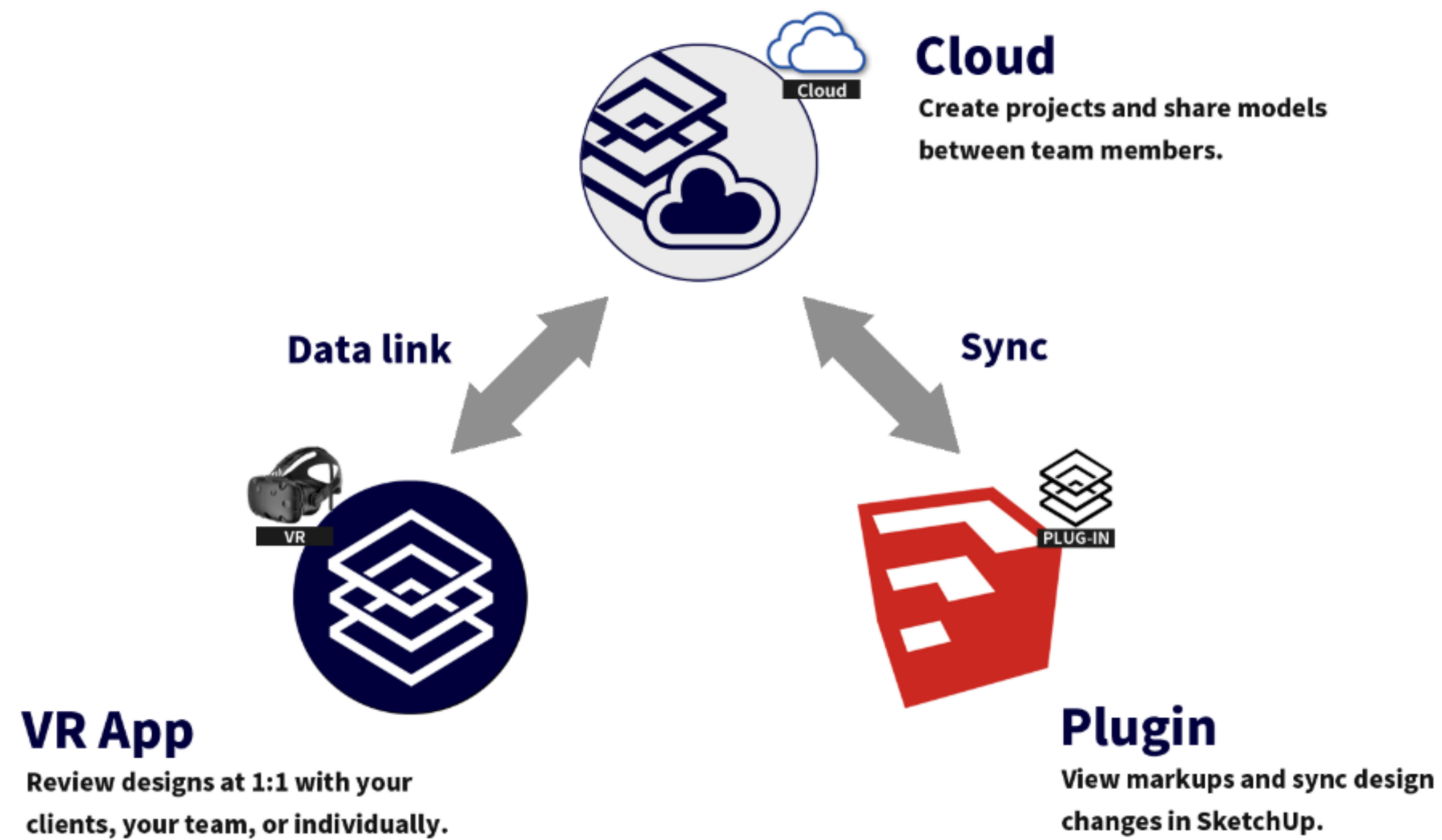
# Viewing Point Cloud from VR






# Viewing Point Cloud from VR

(3) LAS/LAZ > SketchUp > Symmetry > VR Headset



# Viewing Point Cloud from VR & AR



(4) LAS > Sketchfab > AR & VR from Mobile Devices


 Sketchfab


EXPLORE ▾


BUY 3D MODELS ▾

FOR BUSINESS ▾

Upgrade  

 UPLOAD





StatusPublished

PrivacyPublic [edit](#)

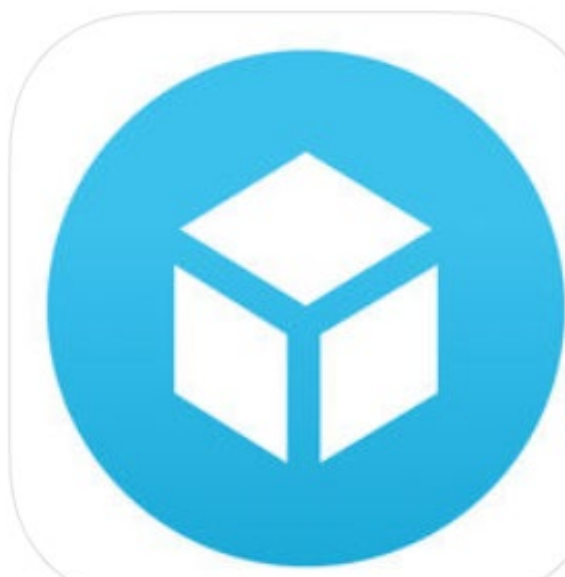
Download

No

Free

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PROPERTIES3D SETTINGSMORE ▾



Sketchfab

Sketchfab Inc

★★★★★ 3.6, 86 Ratings

Free

Point Cloud Demo: Natural History Museum, London  
3D Model

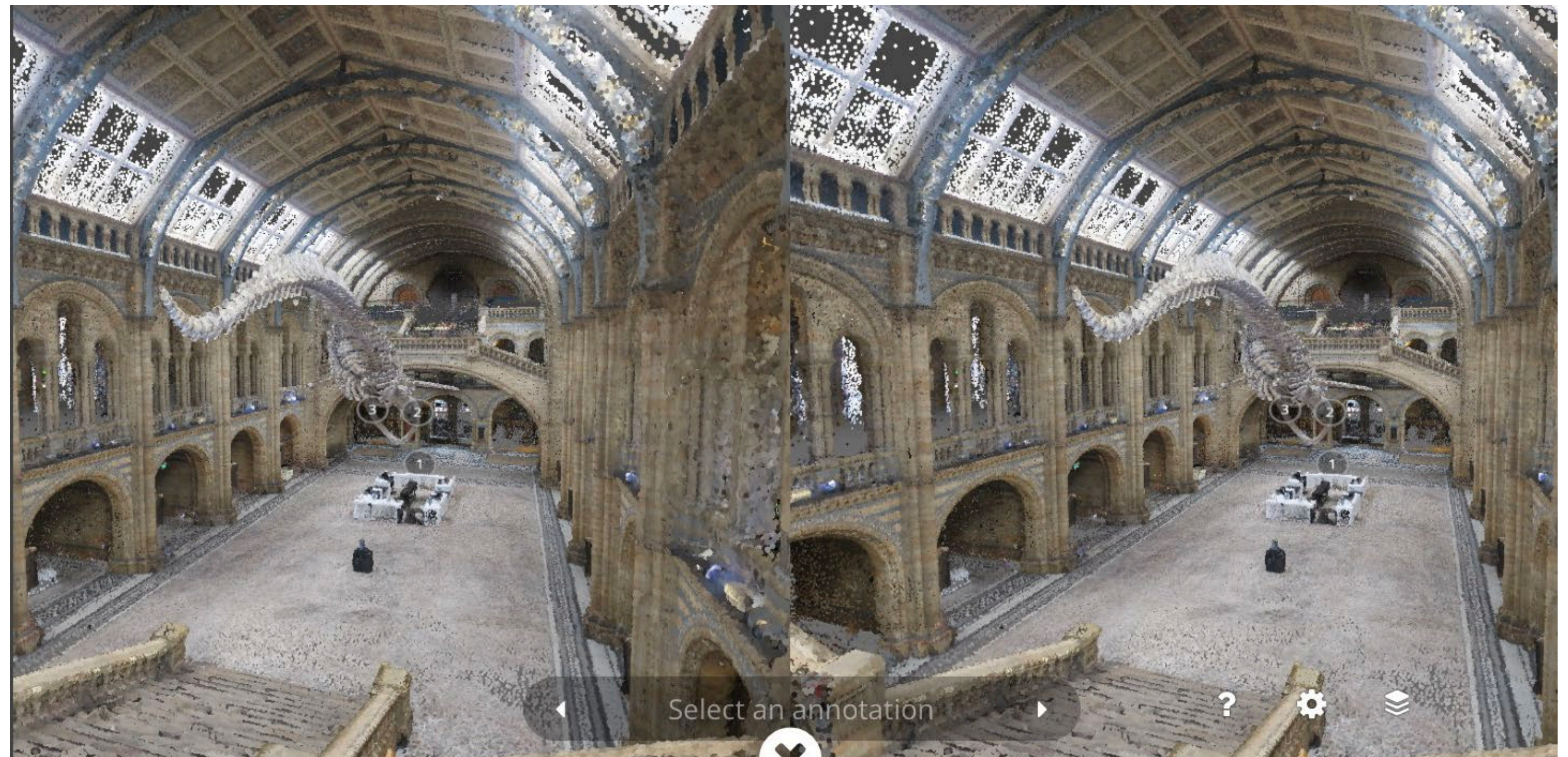
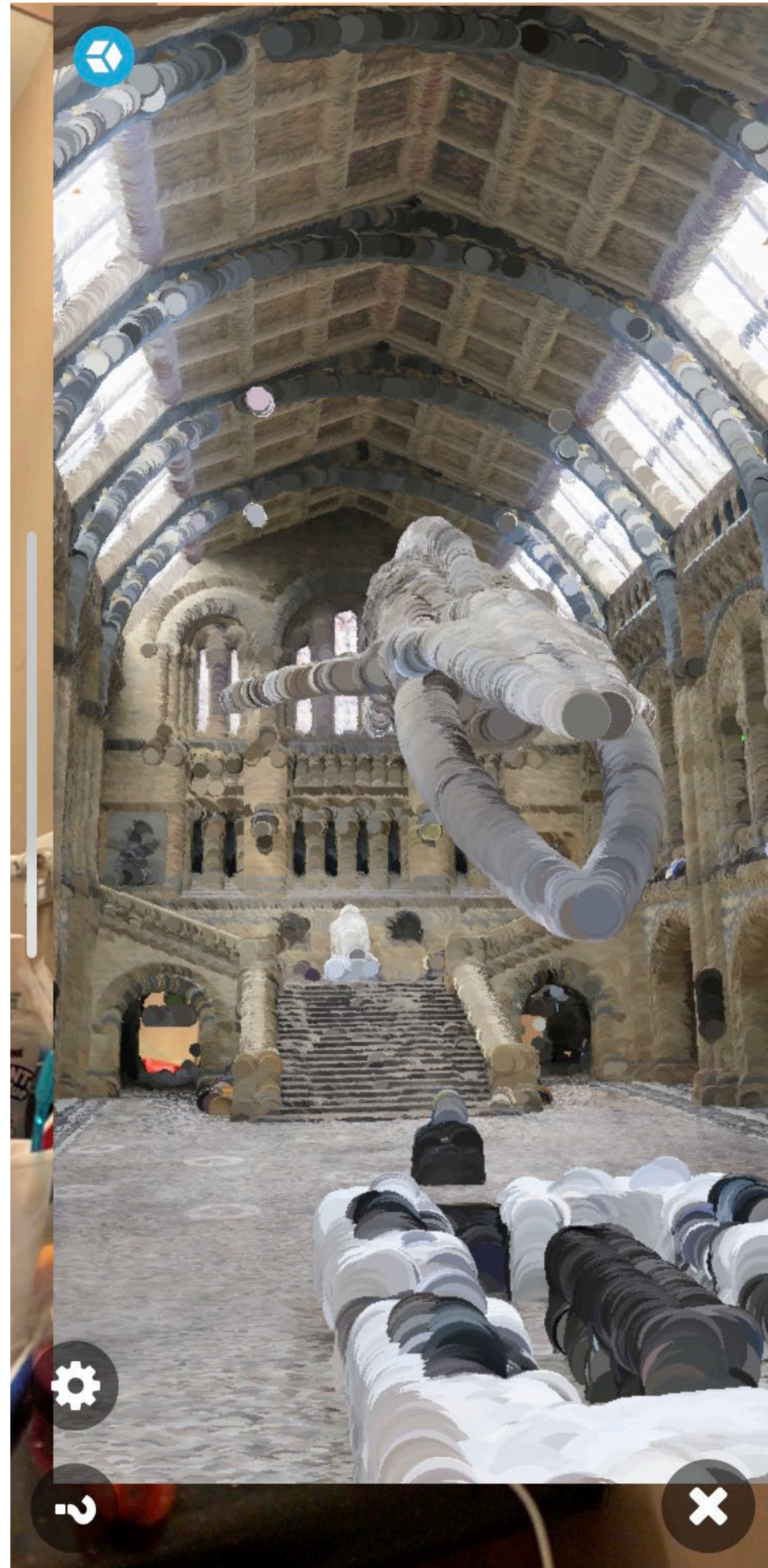
# Viewing Point Cloud from VR/AR

(4) LAS > Sketchfab > AR & VR from Mobile Devices

View in VR

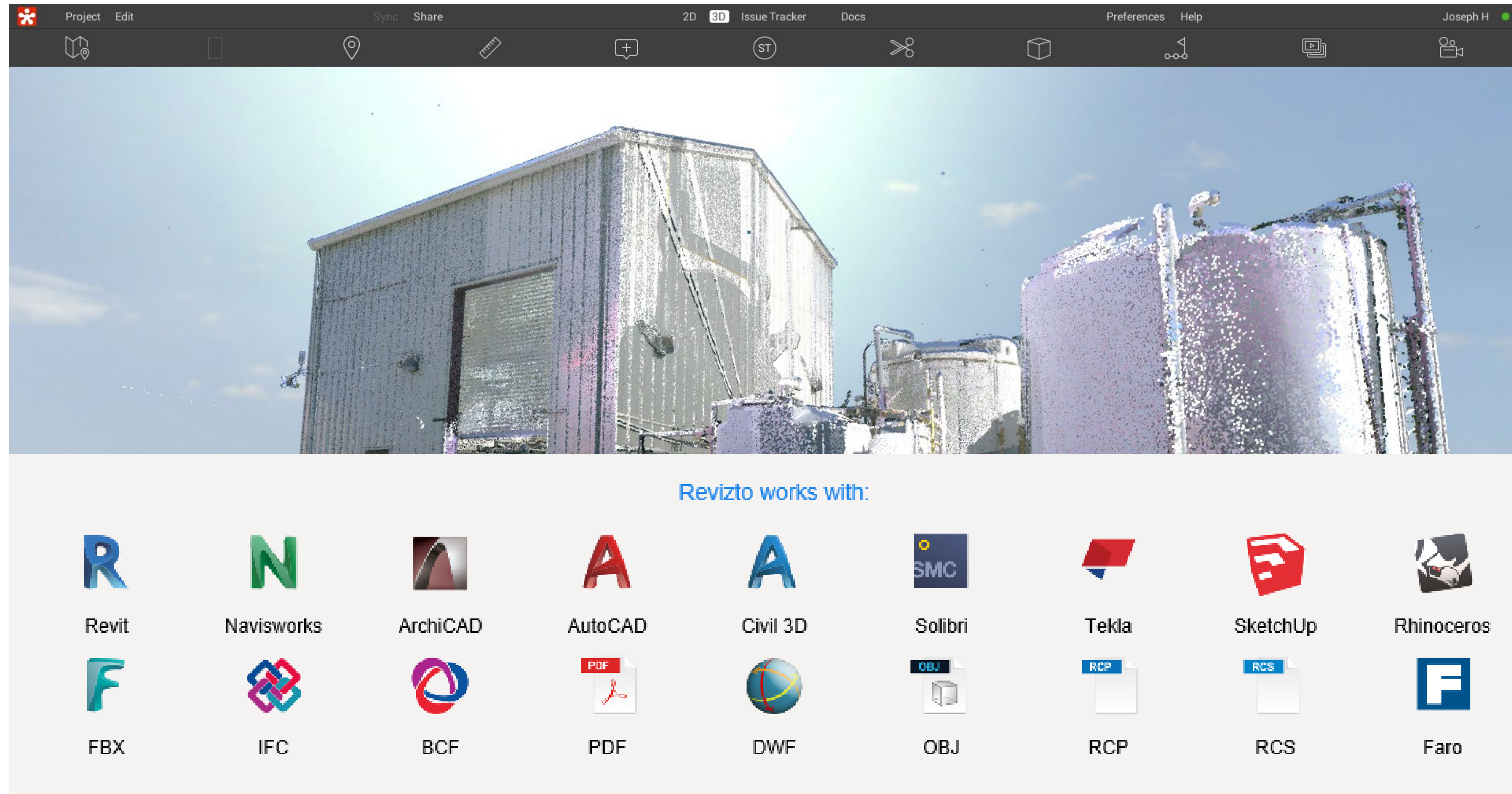


View in AR



# Viewing Point Cloud from VR

(5) RCP/RCS > Revit > Revizto > VR Headsets and Mobile Devices



# Potree: Rendering Large Point Clouds in Web Browsers

potree.org - github - twitter 1.6  
EN - FR - DE - JP

**Appearance**

Point budget: 10,000,000  
Field of view: 60

**Eye-Dome-Lighting**

☒ Enable  
Radius: 1.4  
Strength: 0.4

**Background**

Skybox Gradient Black White None

**Other**

Splat Quality  
Standard High Quality  
Min node size: 50  
☐ Box  
☐ Lock view

**Tools**

**Measurement**

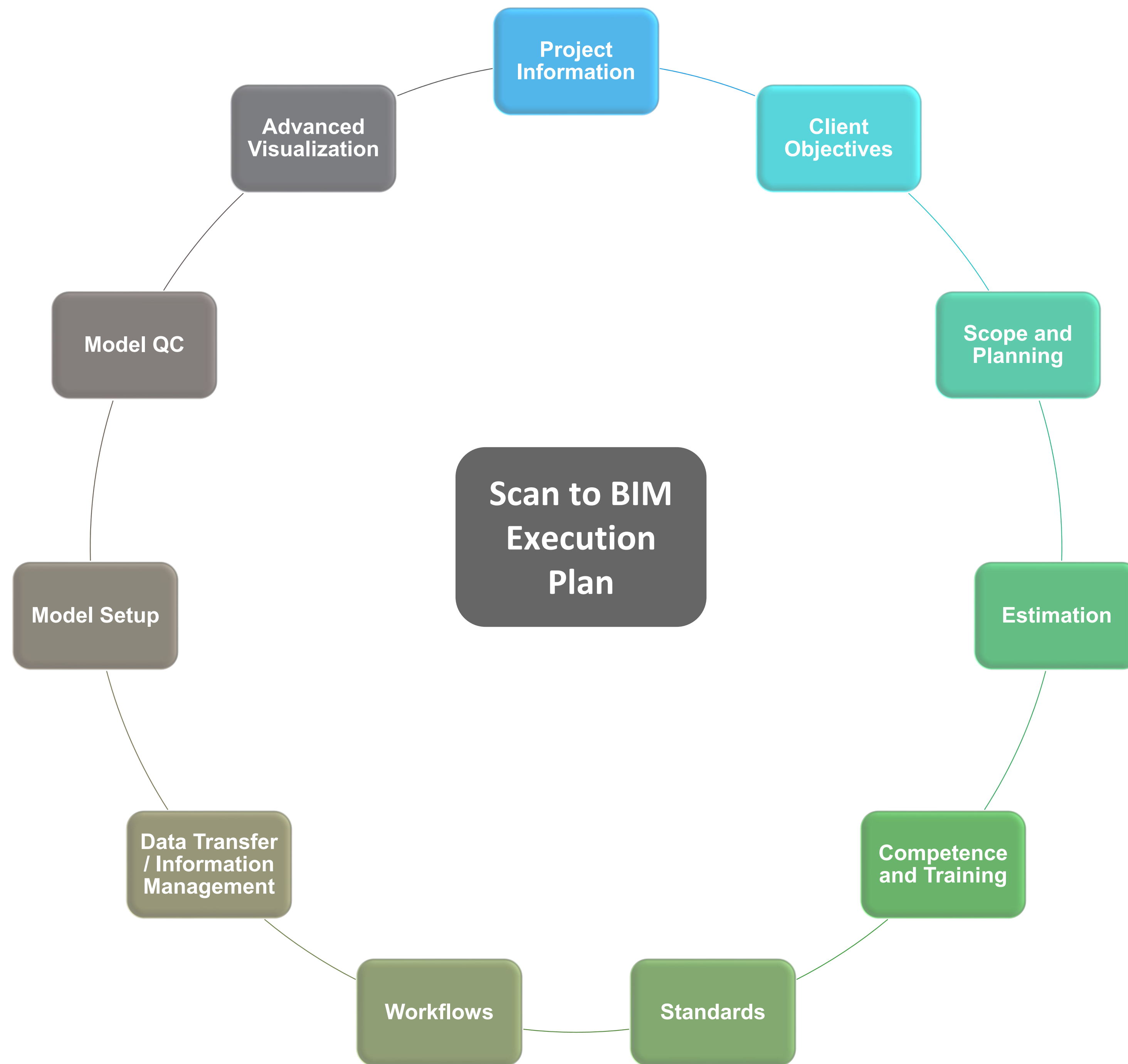
**Clipping**

Clip Task



# Potree: Rendering Large Point Clouds in Web Browsers

The screenshot shows the Potree application interface. On the left is a dark sidebar with various controls. At the top, it says 'potree.org - github - twitter' and '1.6'. Below that are language options 'EN - FR - DE - JP'. The 'Appearance' section includes a 'Point budget' slider set to 5,299,000 and a 'Field of view' slider set to 60. The 'Eye-Dome-Lighting' section has a checked 'Enable' checkbox, a 'Radius' slider set to 1.4, and a 'Strength' slider set to 0.4. The 'Background' section has buttons for 'Skybox', 'Gradient', 'Black', 'White', and 'None'. The 'Other' section includes 'Splat Quality' buttons for 'Standard' and 'High Quality', a 'Min node size' slider set to 50, and checkboxes for 'Box' and 'Lock view'. The 'Tools' section contains a 'Measurement' row with icons for distance, area, volume, and other measurements, and a 'Clipping' row with icons for different clipping methods. The main 3D view shows a dark, textured point cloud of a train station, labeled 'AttTrainStation' with a small icon. Below the point cloud is a semi-transparent globe showing the African continent. At the bottom left, the Cesium logo and text 'Cesium, Mapbox, Open Street Map and contributors. CC BY SA' are visible.



# Questions?

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raghavendra.bhat@stantec.com



Joseph Huang  
joseph.huang@stantec.com

*Kindly take the class survey in the app. Thank you!*



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