

Laser Scanning: Enhancing Productivity and Quality in Construction Management

Bimal Patwari

CEO

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Project Manager



Speakers Info



Bimal Patwari
President



Bimal Patwari is the 1st generation Entrepreneur and founder of Pinnacle Infotech Solutions, the acknowledged Global leader in providing innovative BIM solutions. Bimal is recognized for his contribution to the innovative use of BIM technology to improve efficiency and quality, reduce costs and wastages .

He has received several awards and recognition from Government and other industry associations for his entrepreneurship and pioneering contribution to the construction industry.

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Speakers Info



Leonidas I. Tzevelekas
Senior BIM Project Manager



Leonidas is responsible for developing, implementing and delivering prestigious world class BIM projects for general contractors in the Middle East. Previously, he worked at one of the biggest contractors and was involved in the construction of major terminal buildings and bridge infrastructure of mega aviation projects.

Leonidas is currently working in one of the most prestigious project in Qatar in which he is extensively involved in usage of Laser Scanning for project monitoring.

Email : leonidas@





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Website: www.pinnaclecad.com | Email: bim@pinnaclecad.com



Key Learnings

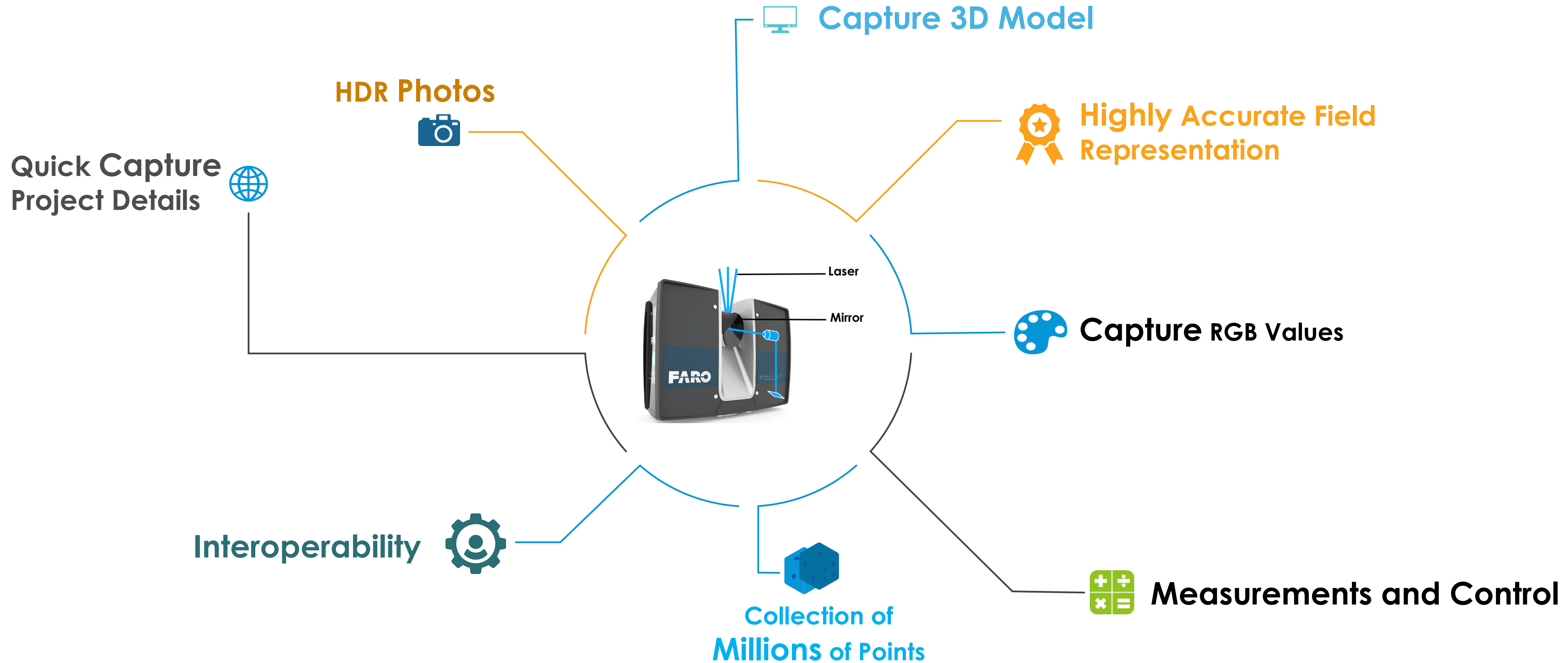
- ❖ **Innovative use of laser scanning for**
 - ❖ Improving construction quality
 - ❖ Improve site safety
 - ❖ Getting ahead of schedule
- ❖ **Laser scanning for construction progress management**
- ❖ **Laser scanning for inspection and approvals**
- ❖ **Laser scanning for quantity estimation and contractor bill approval**

Send your questions or write to us at bpatwari@pinnaclecad.com

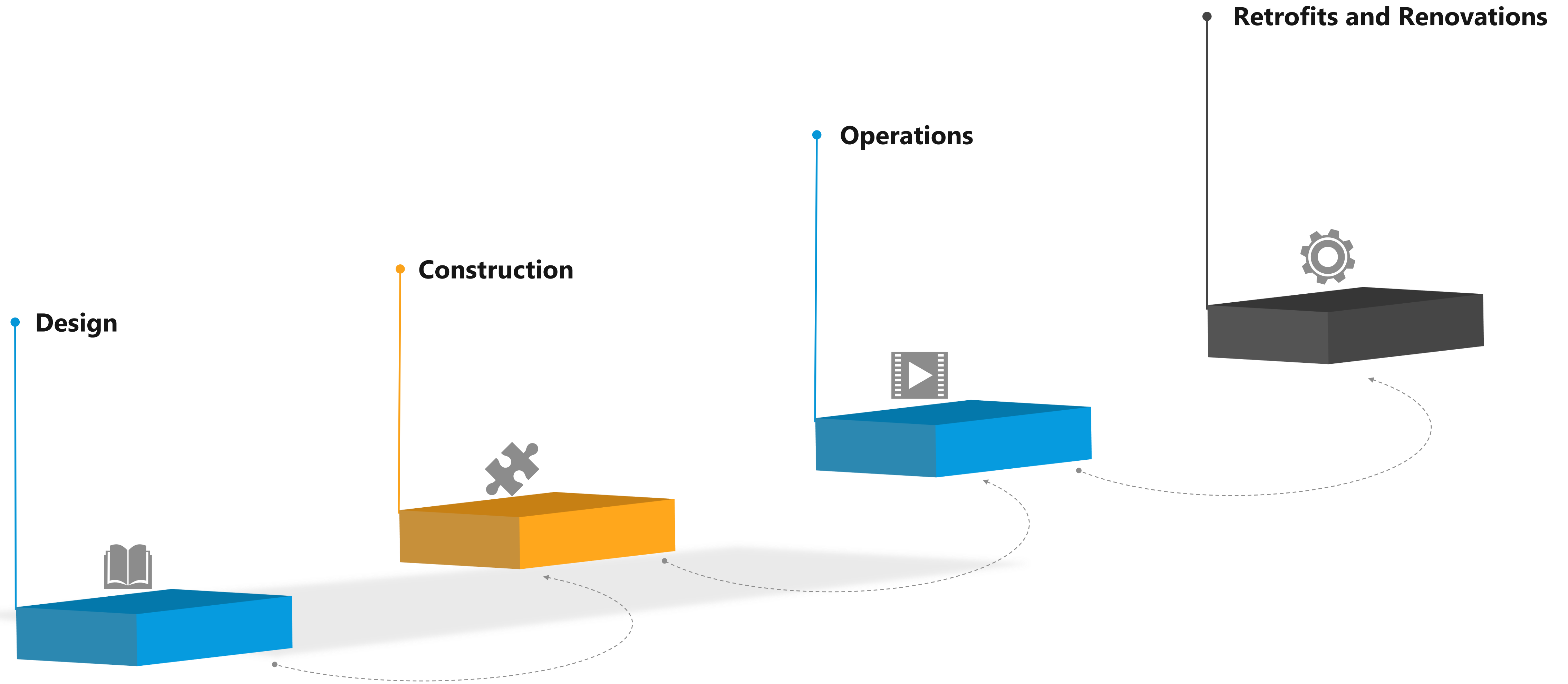


Laser scanning

Non-Contact, Non destructive , Digital Capture of exact size and shape in 3-Dimension



Laser Scanning Across A Project's Lifecycle






Benefits

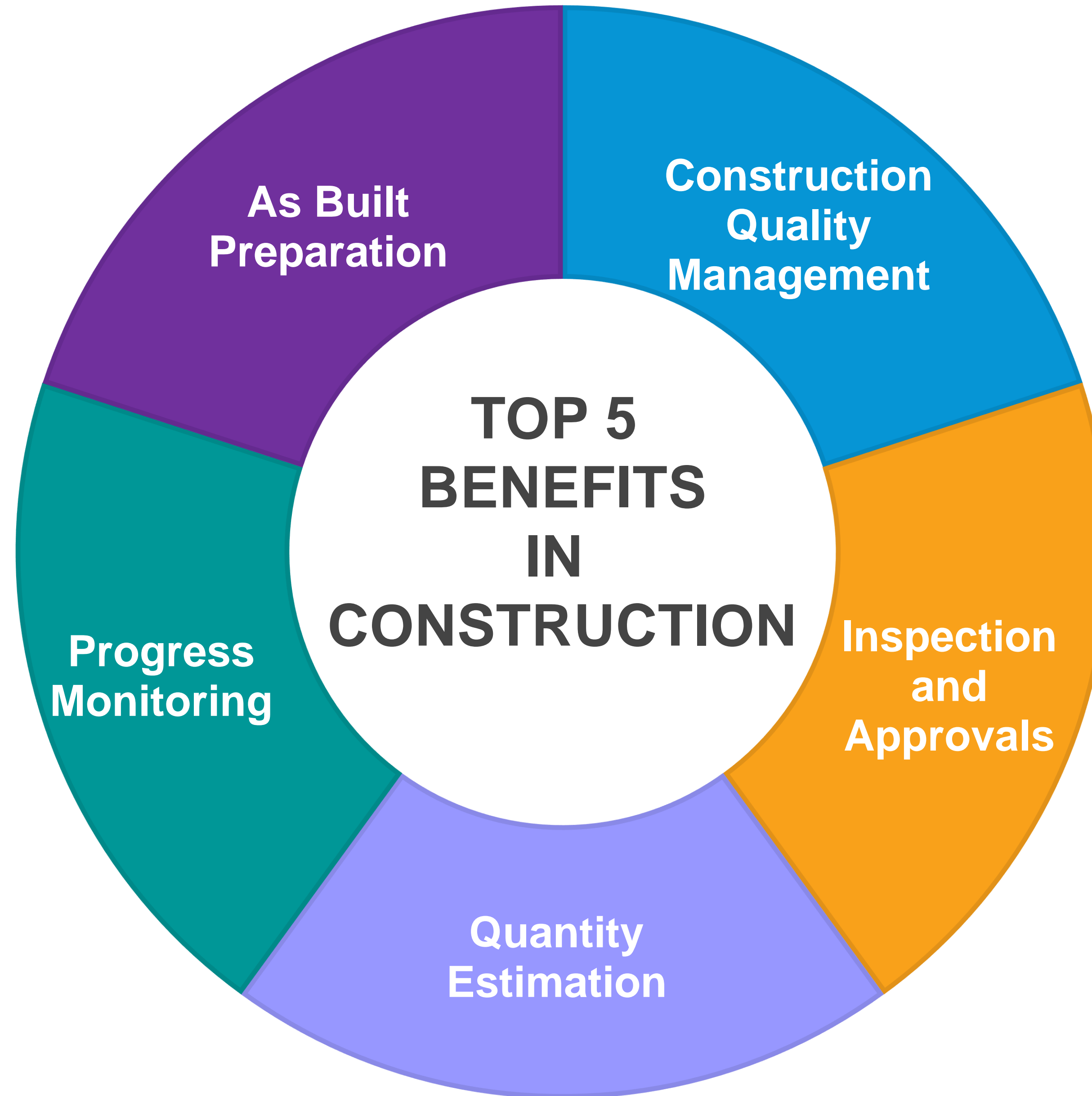


Traditional Method vs. 3D Laser Scanning





- ❑ laser scanning **±2mm accuracy**
- ❑ Laser Scanning takes **70-75% less** time
- ❑ Provides full evidence of the inspection by creating **error heat map on point cloud model**

Structure Members			Traditional Method (Total Station)			3D Laser Scanning			Manhours Savings
Image	Name	Total Members	Points Collected	Accuracy	Total Hours Taken	Points Collected	Accuracy	Total Hours Taken	
	Concrete Plinth	24	Points on vertices to create Geometry	1.Manually marked points create errors 2. Inspections on limited points	192 (8*24)	Millions of Points (Full Model)	1. minimize errors up to less then ±2mm 2. Inspections on every point with same accuracy	48 (2*24)	144 hr.
	Steel Frames	48			960 (20*48)			384 (8*48)	576 hr.
	Steel Truss	24			360 (16*24)			120 (5*24)	264 hr.





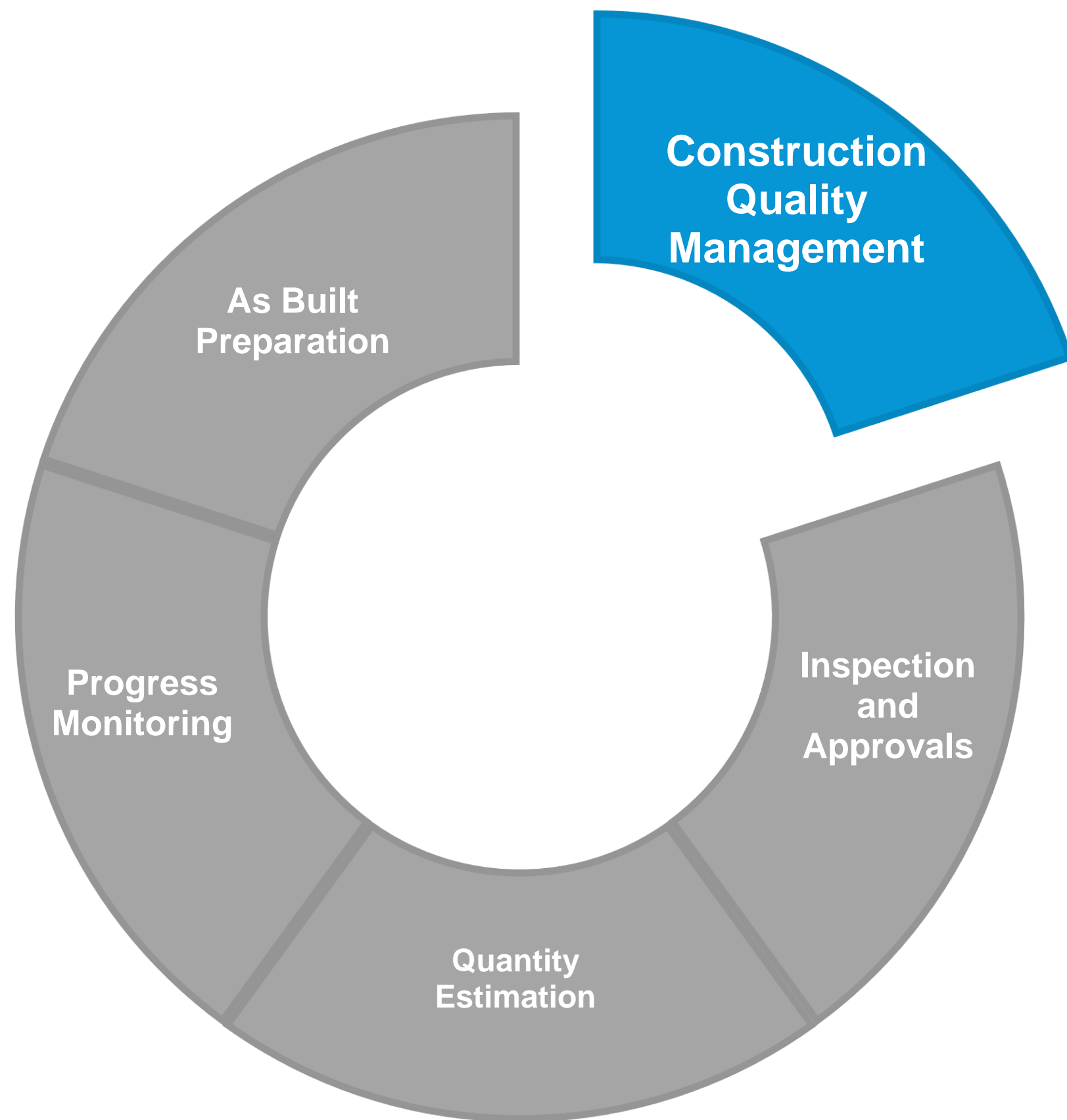
Types of Scanner

	Airborne Laser Scanner	Stationary Terrestrial Laser Scanner	Mobile Terrestrial Laser Scanner	Handheld (Industrial)
Ideal Usage	<ul style="list-style-type: none"> Exterior mapping Long/Linear Projects Large scale mapping 	<ul style="list-style-type: none"> Interior high-density high accuracy scans 	<ul style="list-style-type: none"> Exterior high accuracy longer range scans 	<ul style="list-style-type: none"> Top-quality, high-precision Suitable for indoor scans
Accuracy and Range	<ul style="list-style-type: none"> +/- 10 CM, depending on conditions Range 3.000 feet (typically flown at about 3,000 FT) 	<ul style="list-style-type: none"> +/-2MM Range 60 to 120 meters, depending on conditions 	<ul style="list-style-type: none"> +/-2MM Range 150 to 330 meters, depending on conditions 	<ul style="list-style-type: none"> +/-0.5mm Range up to 110 meters, depending on conditions
Scanners				



Laser Scanning Applications in Construction

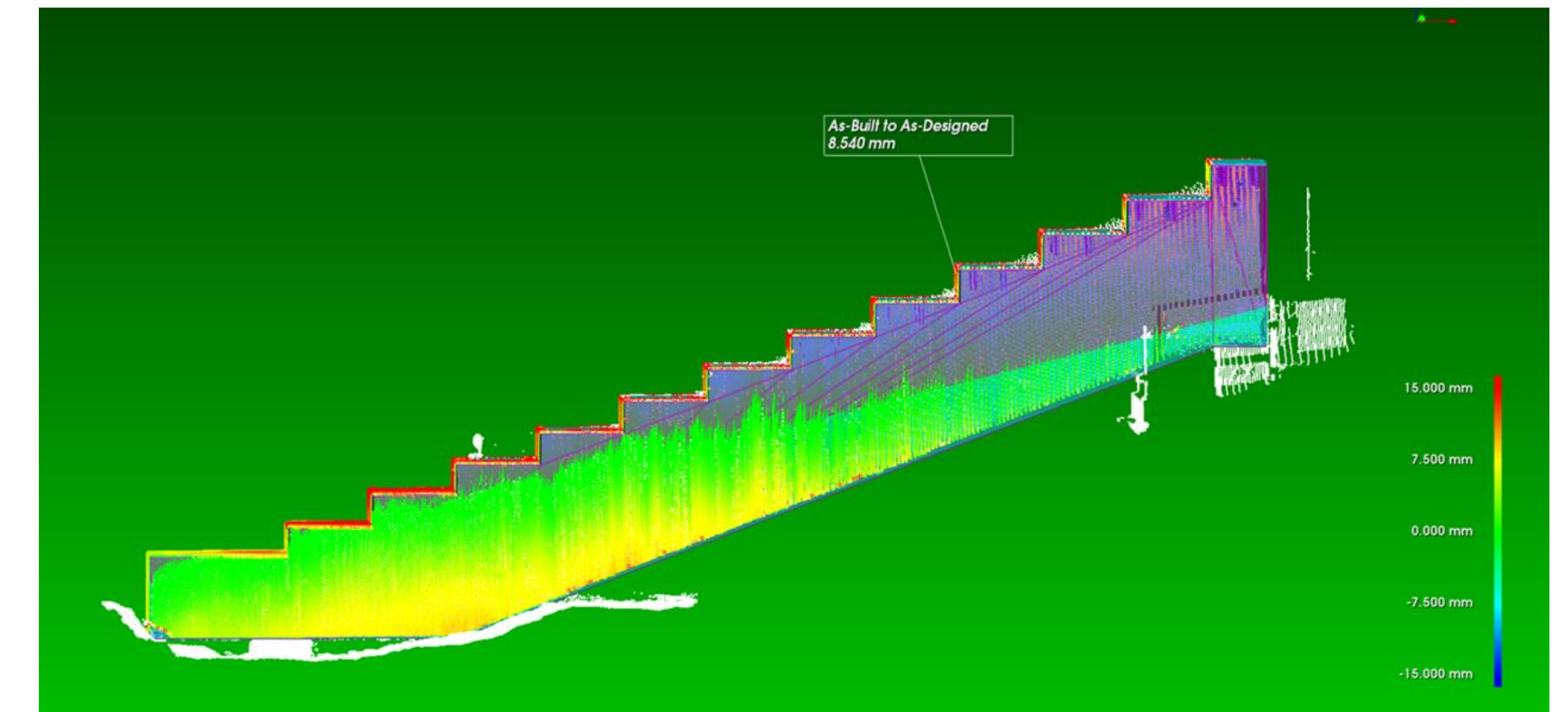
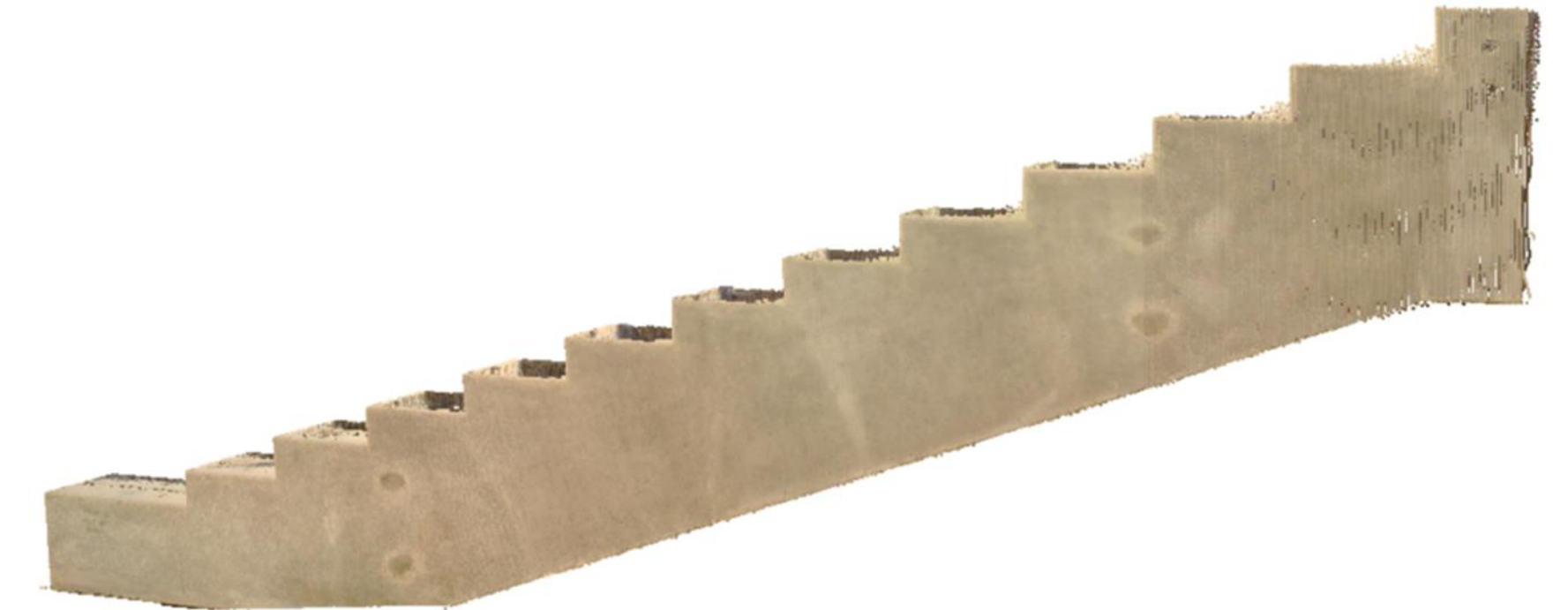
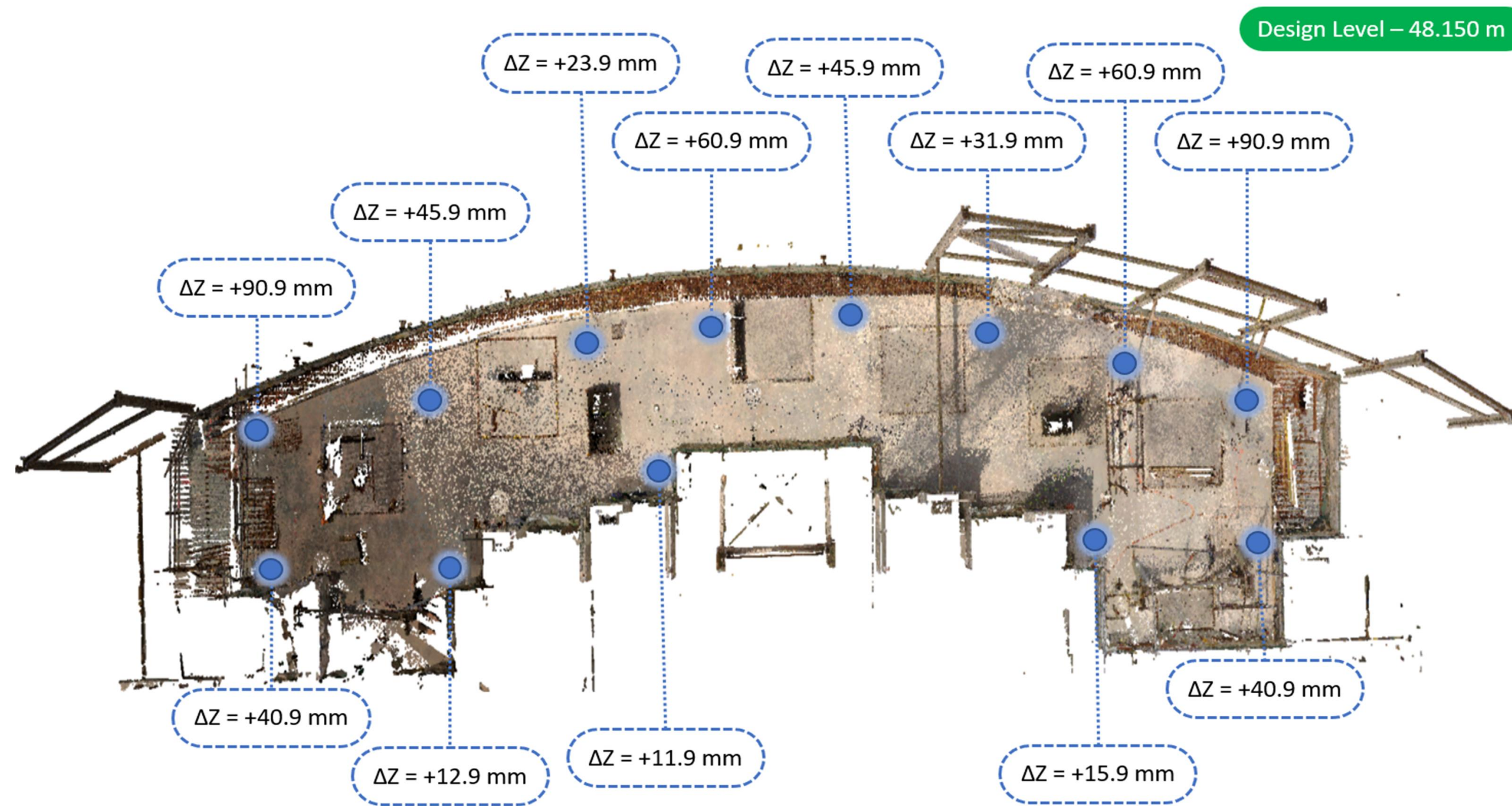




- Processing of millions of closely spaced points to capture actual level and member orientation.
- Deviation analysis extracted by point cloud facilitates erection and minimize the overall tolerance of combine structure during the erection stage.
- Improves coordination and collaboration on jobsite, leading to faster and better decision-making saving time and cost.



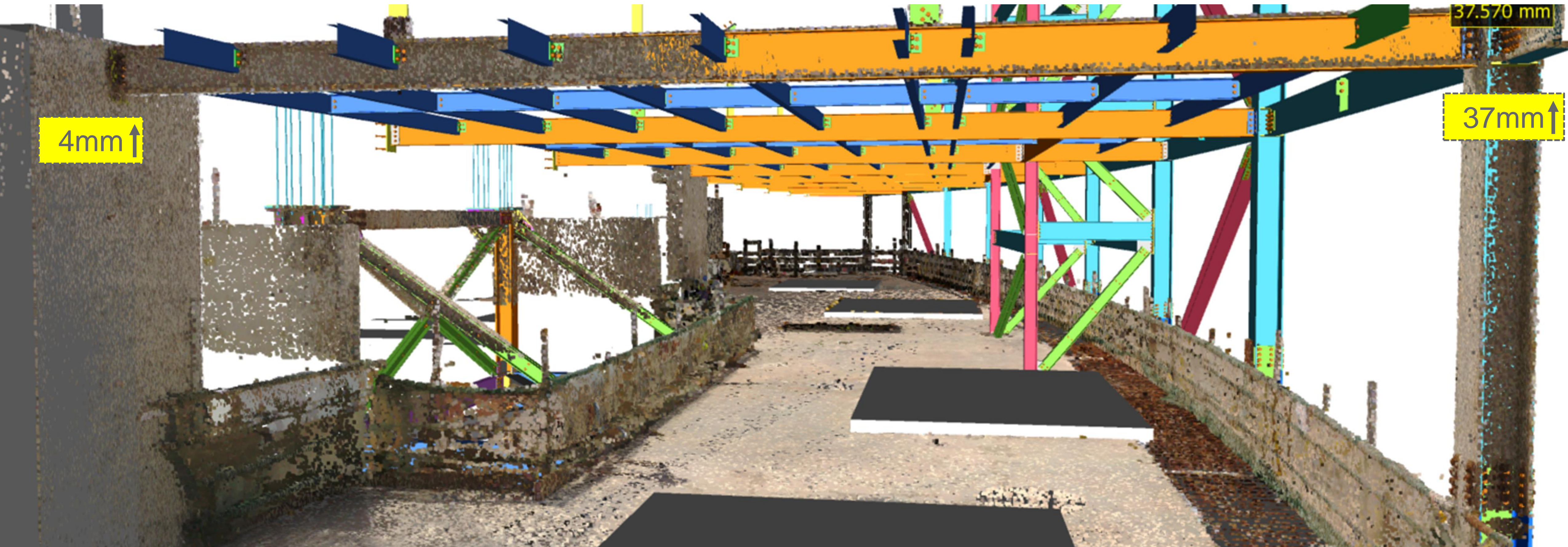
Leveling and Alignment Control



- ❑ Feedback and evaluations during erection staging. It fine-tunes and delivers precise installation of precast/prefabricated elements in the field



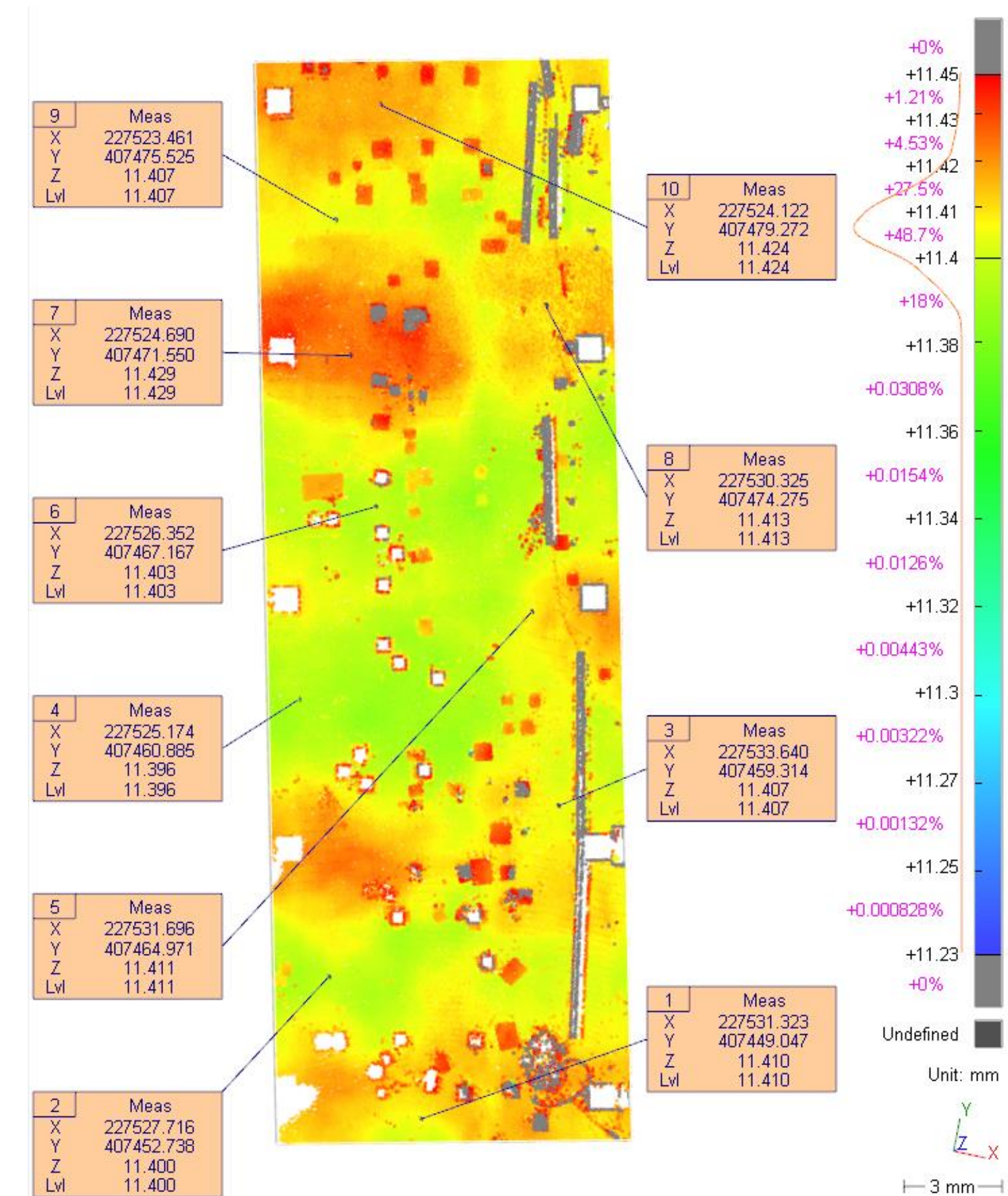
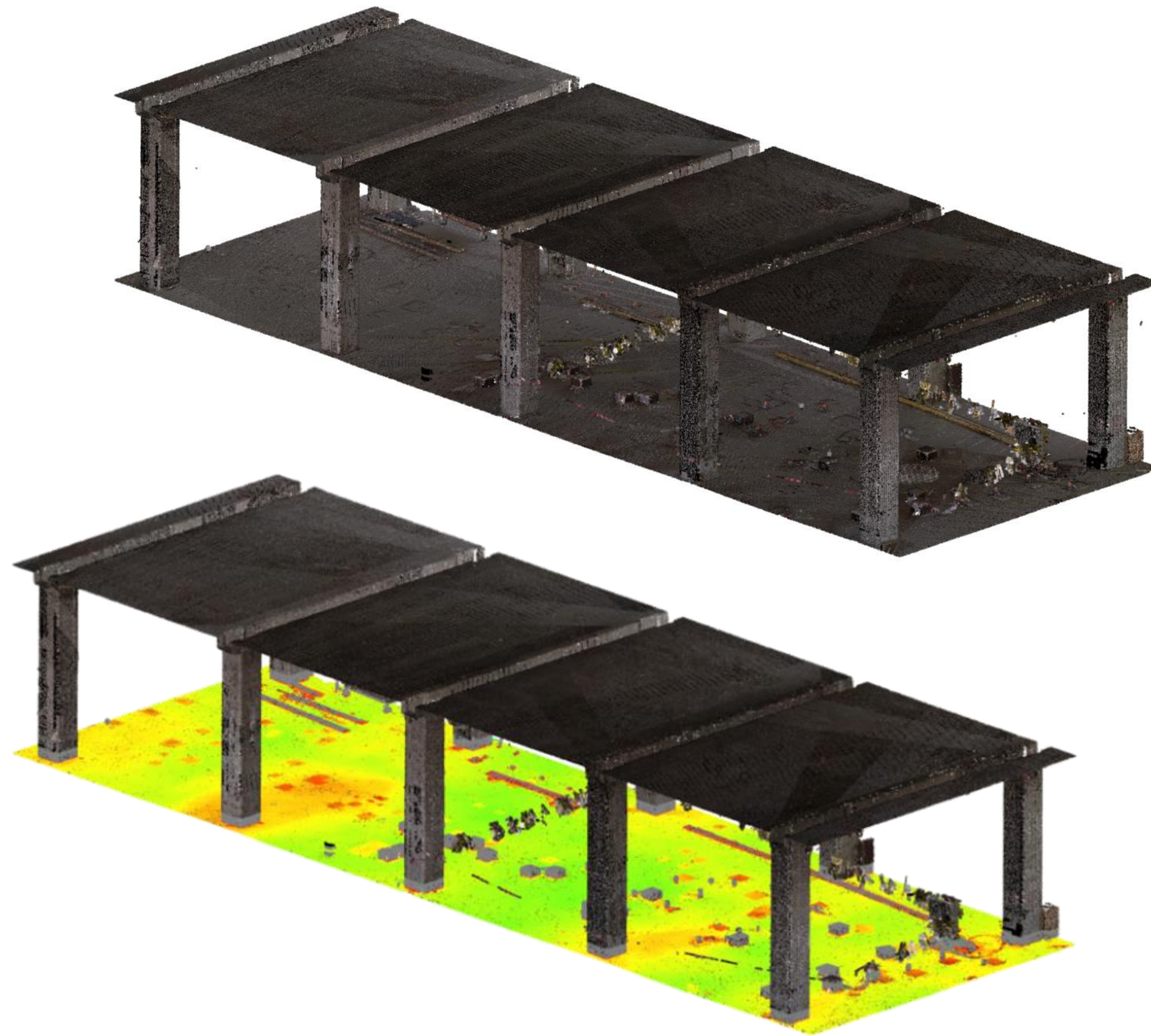
Deviation Analysis



- ❑ Steel beams are important part of main structure and needs to be in place. Laser Scanning provides the clear understanding on the geometry of the beams
- ❑ The top Steel beam is connected to the core wall from one side and with a steel column from another side which is subjected to pre-camber to set out the structure after full load consideration



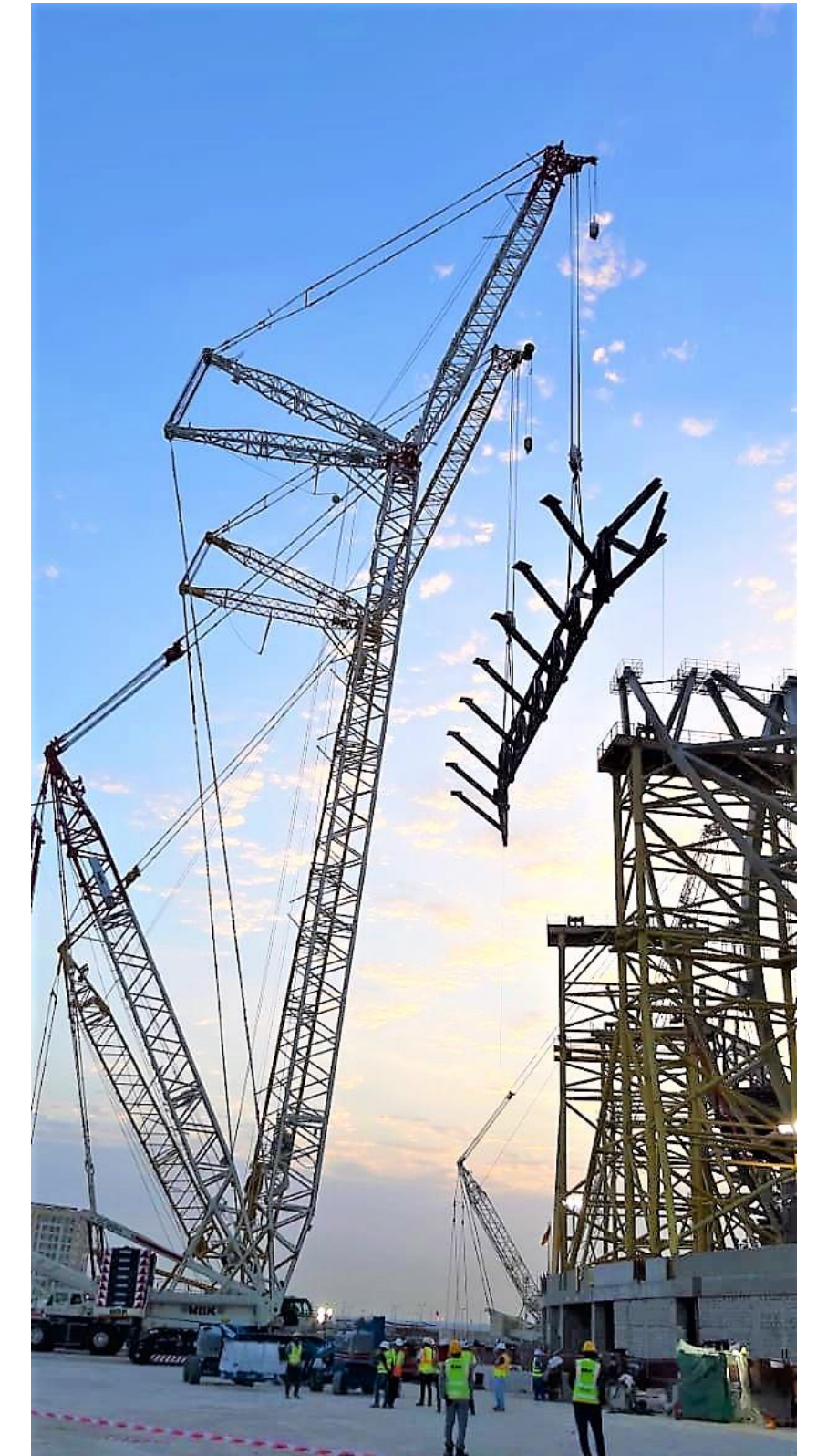
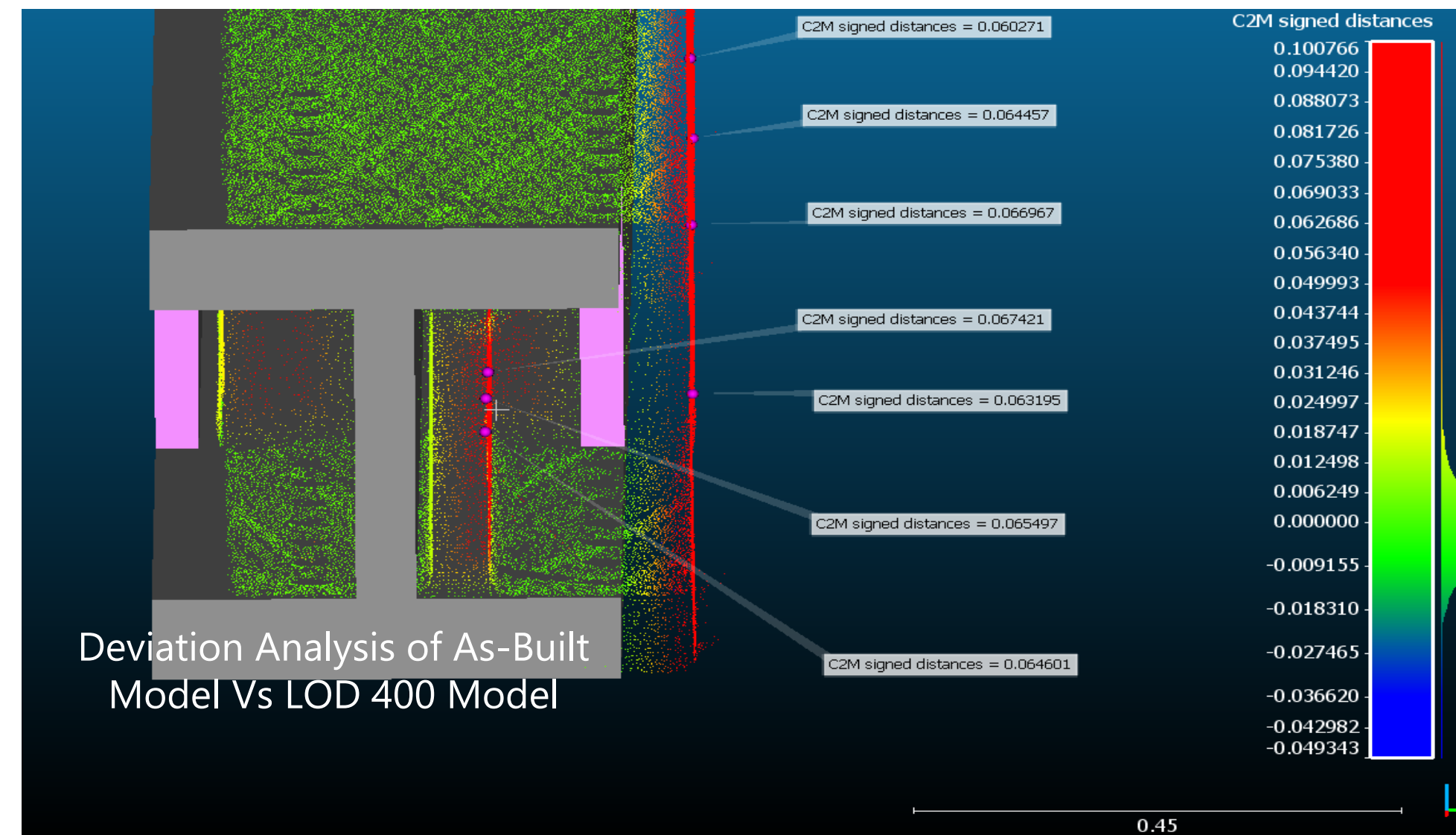
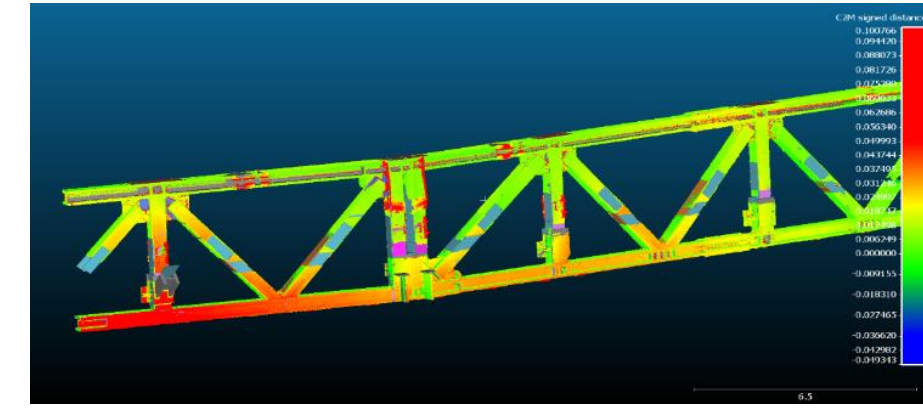
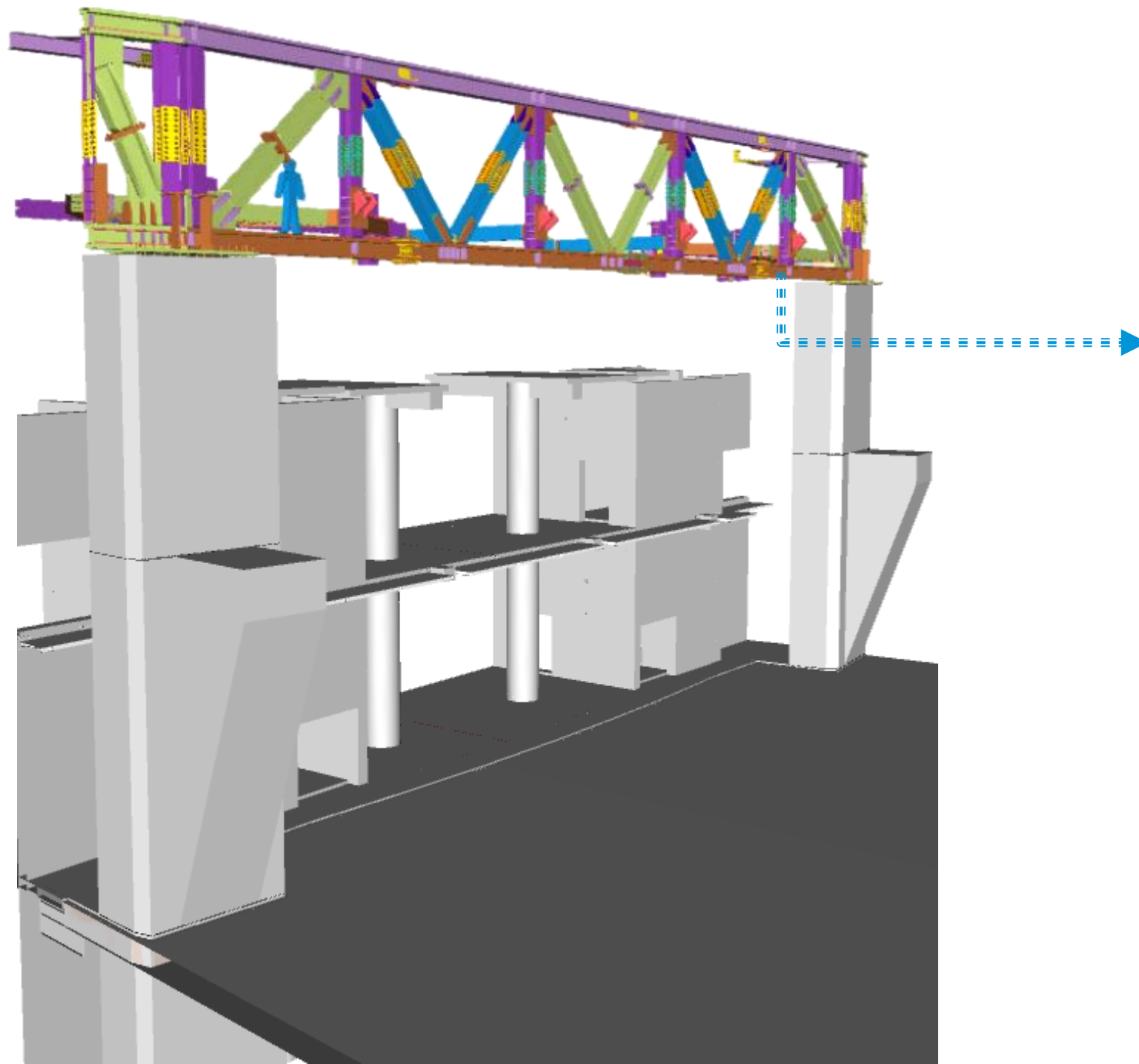
Leveling and Alignments – Slope Analysis on Slab



❑ Slope analysis on the concrete slab shows clear understanding using heat map



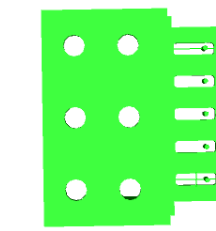
Deflection Monitoring of Long Span Structures – Steel Trusses



- ❑ Defective construction is easily identified by reviewing the point cloud in conjunction with high resolution of 360 color photos obtained by 3D Laser Scanning
- ❑ Insight into a construction project by analyzing and comparing what has actually been built against the design model



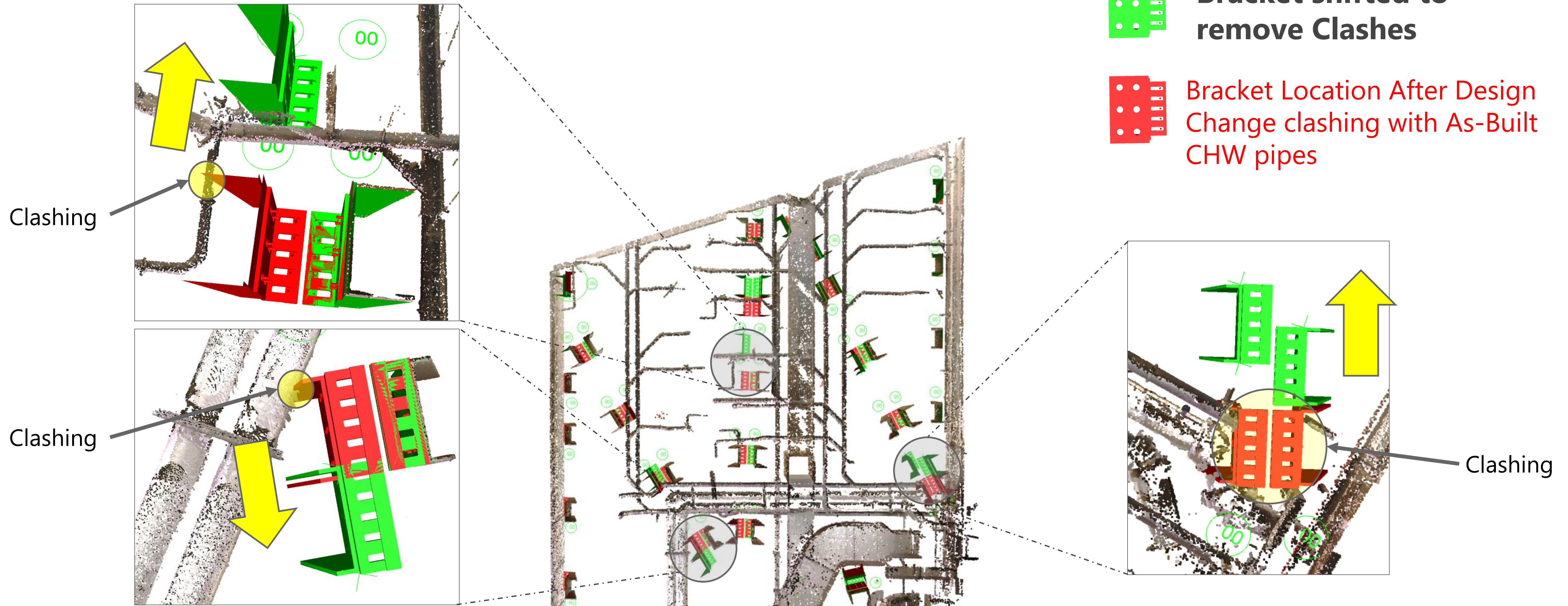
Façade Brackets Coordination



**Bracket shifted to
remove Clashes**

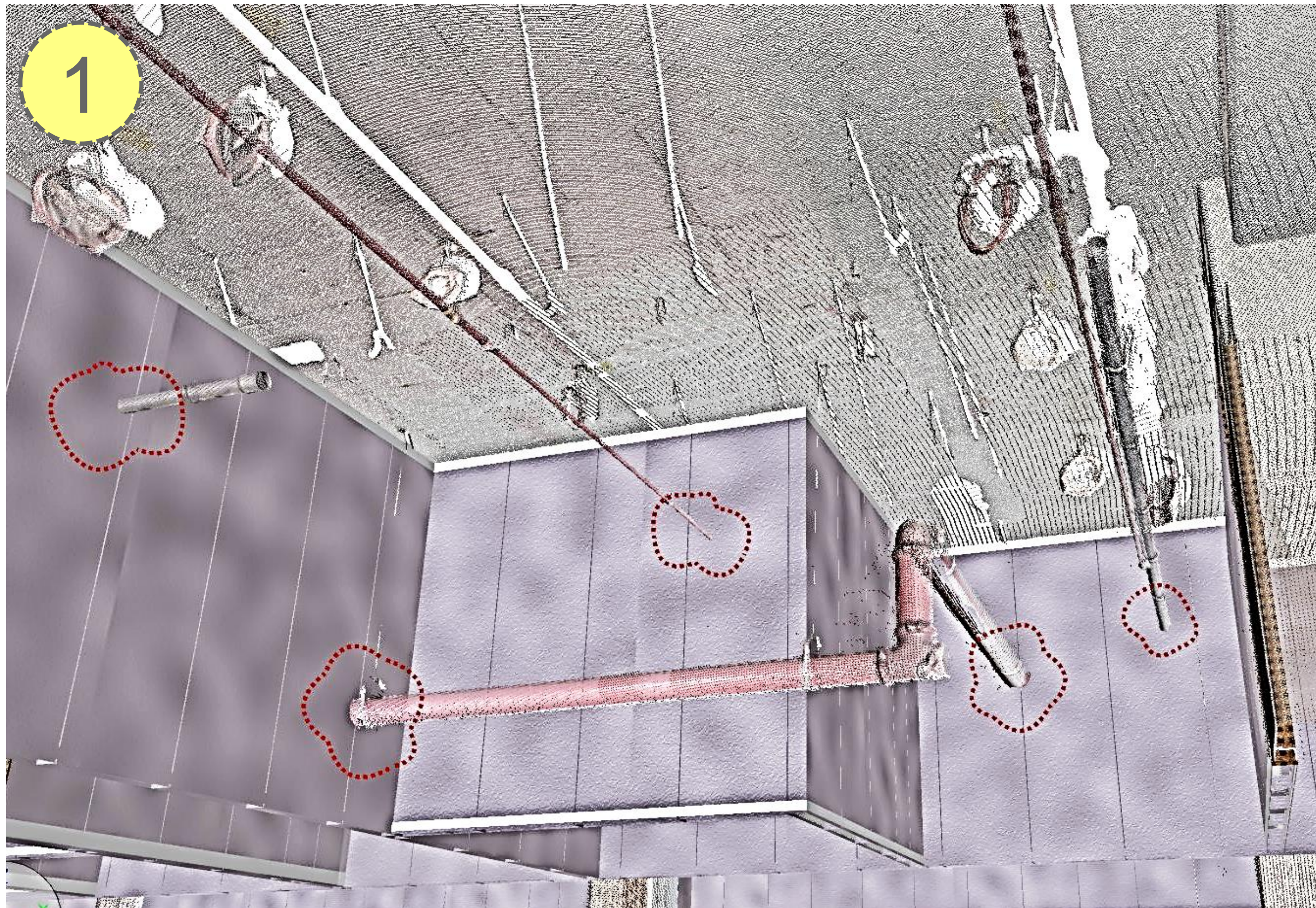


**Bracket Location After Design
Change**
clashing with As-Built
CHW pipes



Laser Scanning For Coordination between Services

Coordination b/w As-Built MEP Services and As-Design AAC Panels

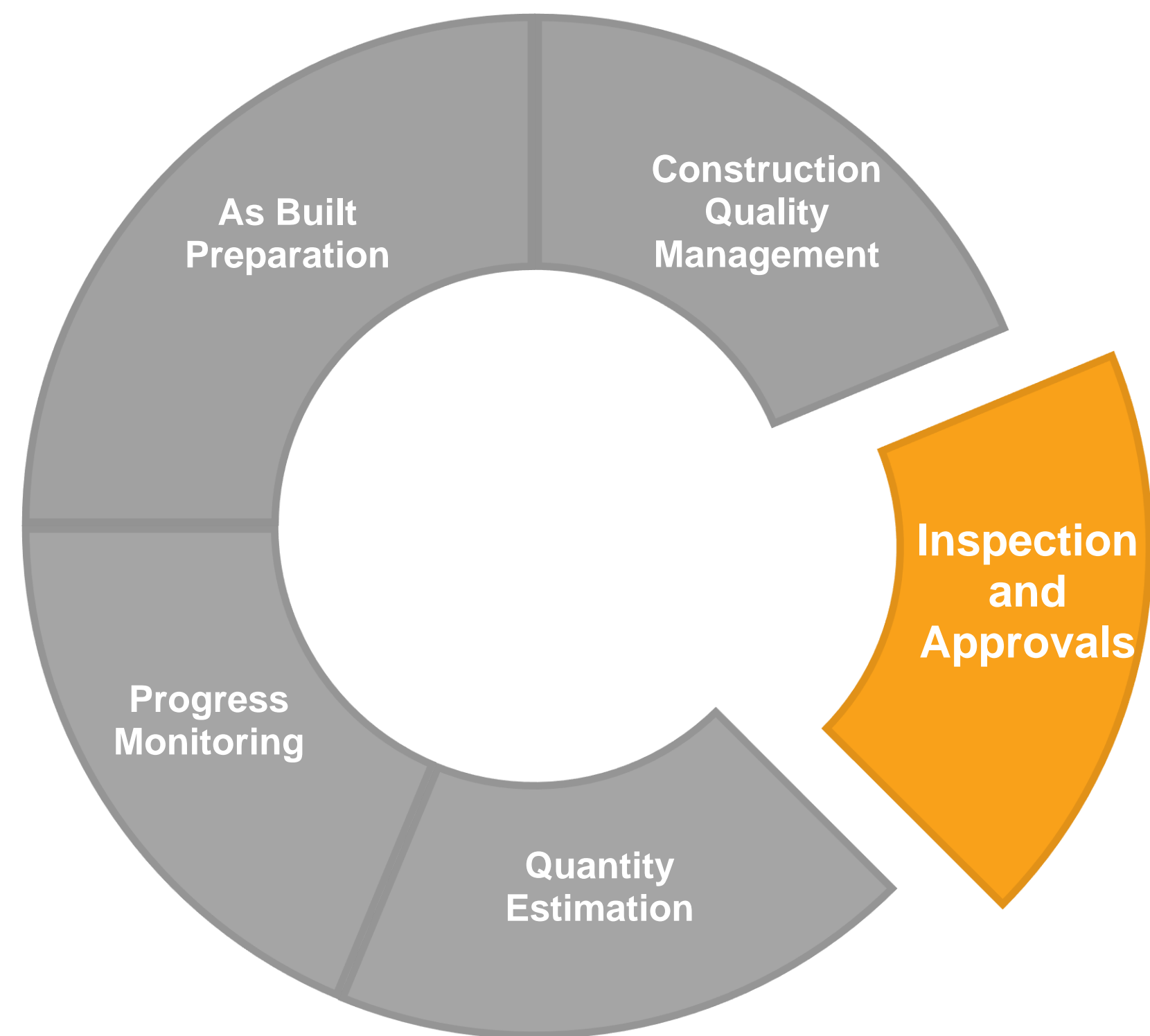


Clash between
As Built Fire Protection Pipe & As Design AAC
Panels for Cutouts



Clash between
As Built Drainage, Mechanical, Fire Protection Pipe,
Cable Tray and As Design AAC Panels for Cutouts

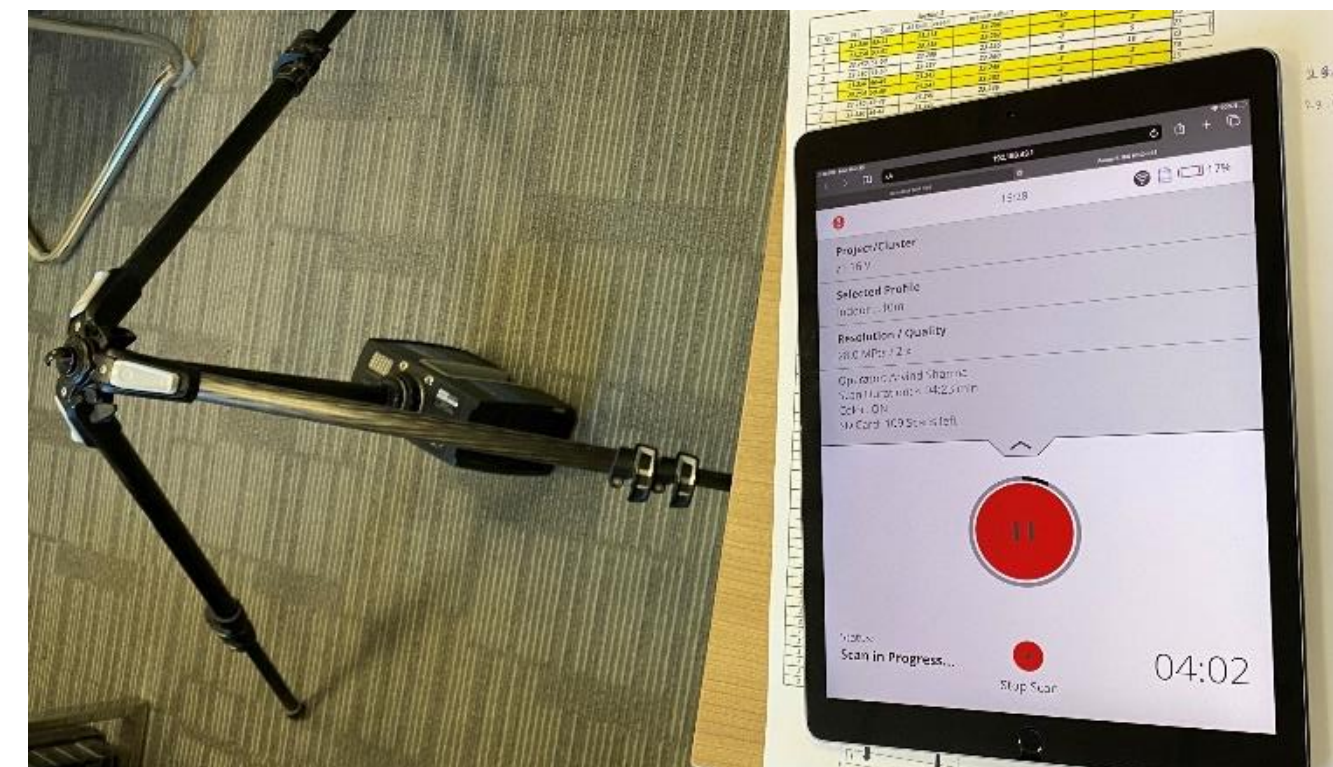
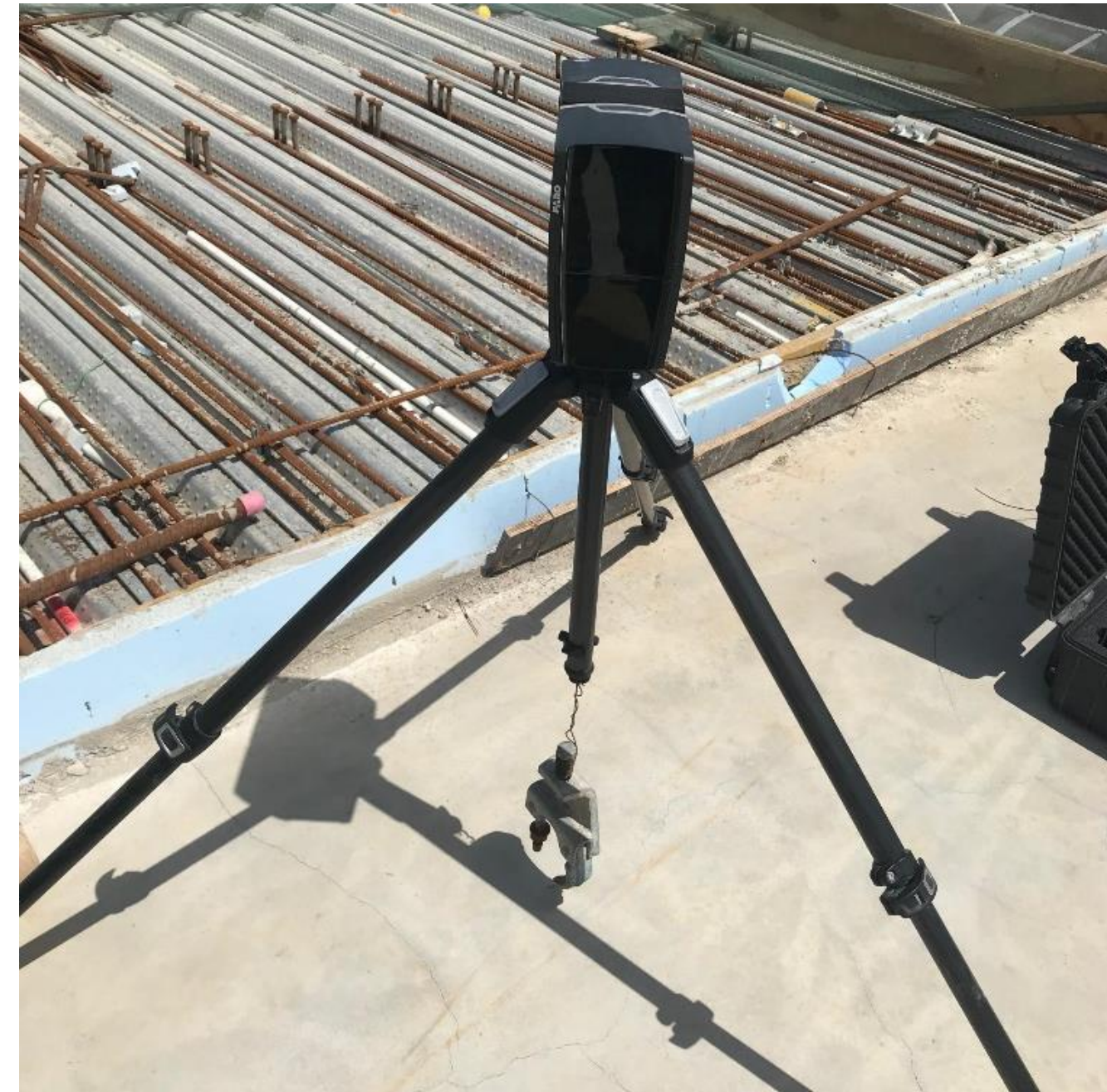




The overlay of the LOD 400 models versus the collected point cloud creates a composite model that clearly reflect the deviations between the as-designed and as-built stage.



Scanners Locations and Accuracy Control



Digital Inspection Methods



Traditional Method –Total Station



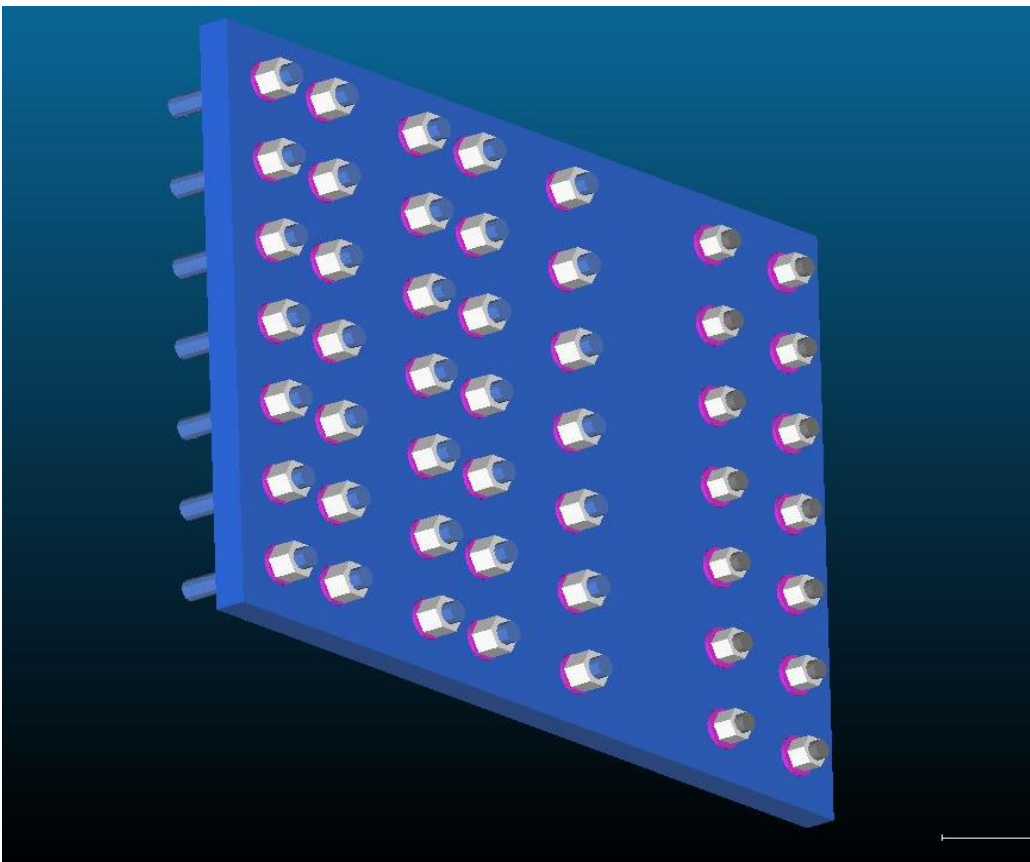
Point Cloud Output from Laser Scanning

	Name	Traditional Method Total Station	3D Laser Scanning	Manhours Savings
Time	Embedded Steel Plate Bolt Verification	2*12(No. of Plates) = 24 hr.	3 hr.	21 hr.

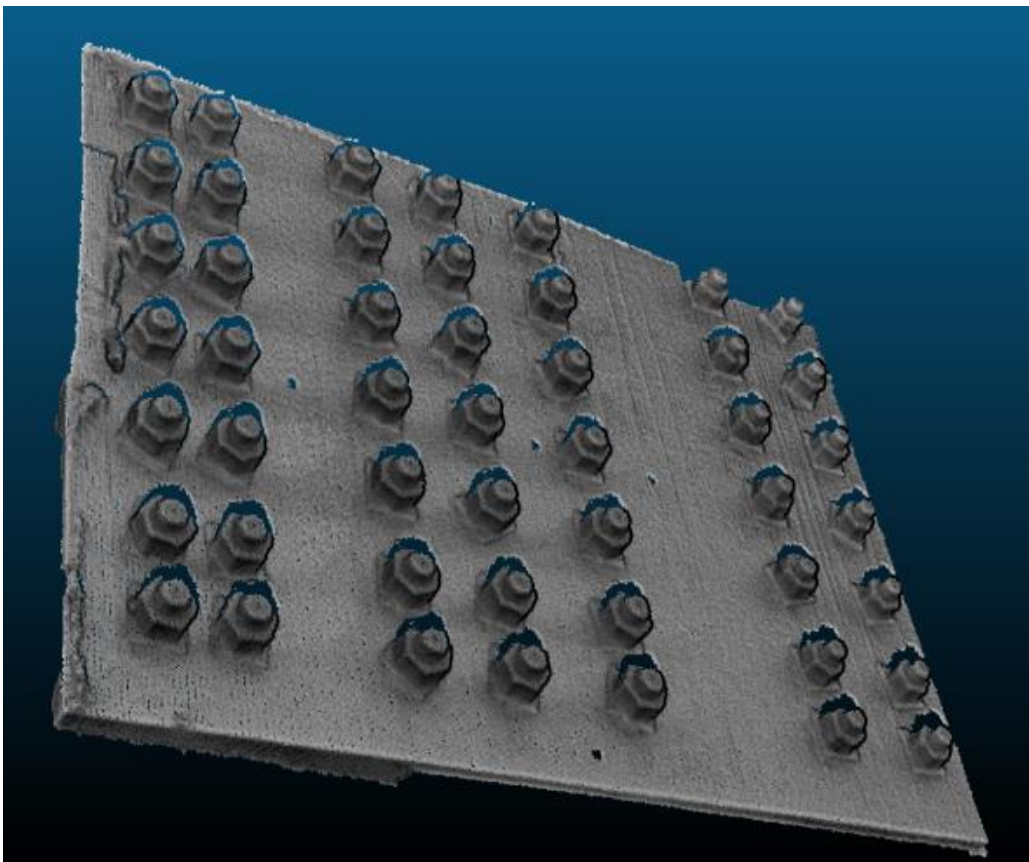


Laser Scanning for Inspection Purposes

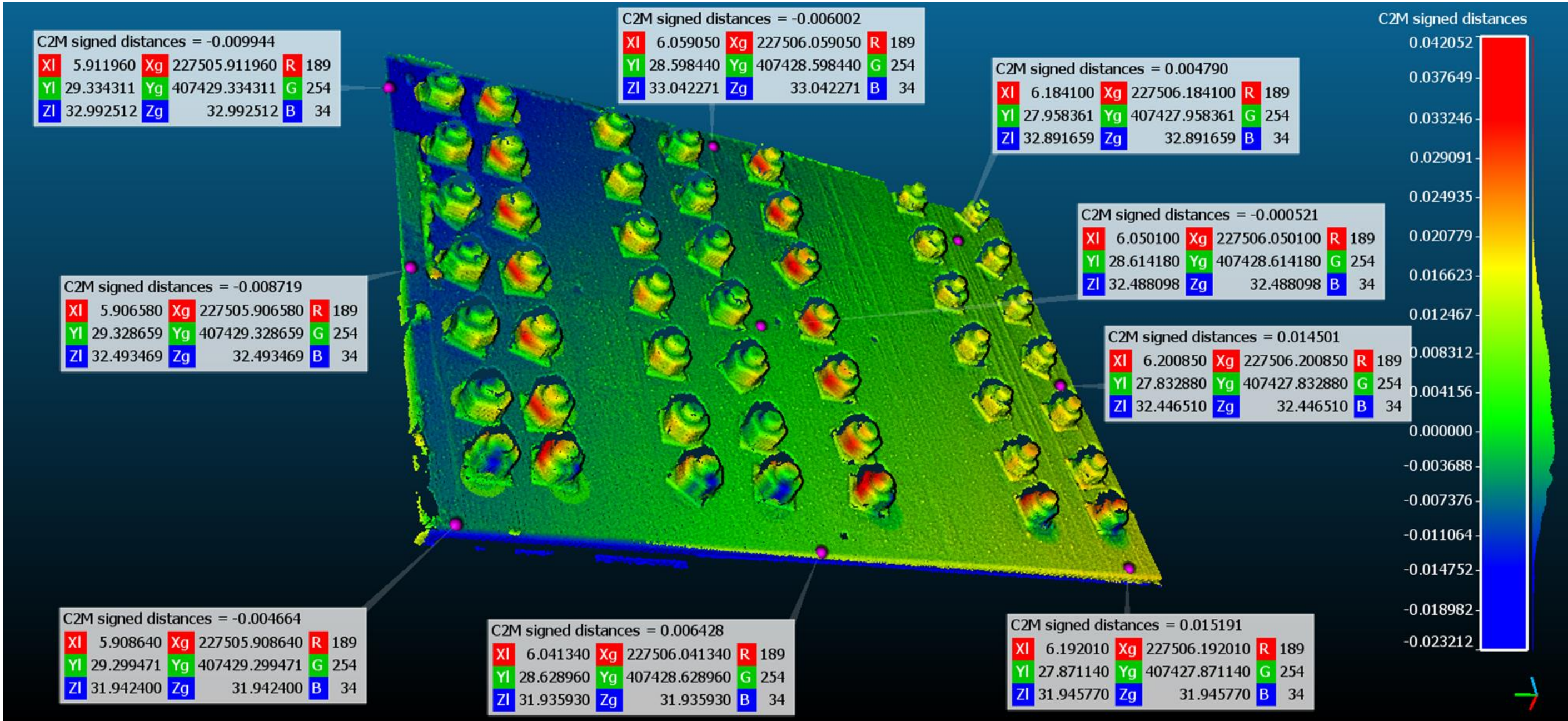
Inspection of Embedded Plates



On-Site Scanning of Steel Part



Point Cloud Model

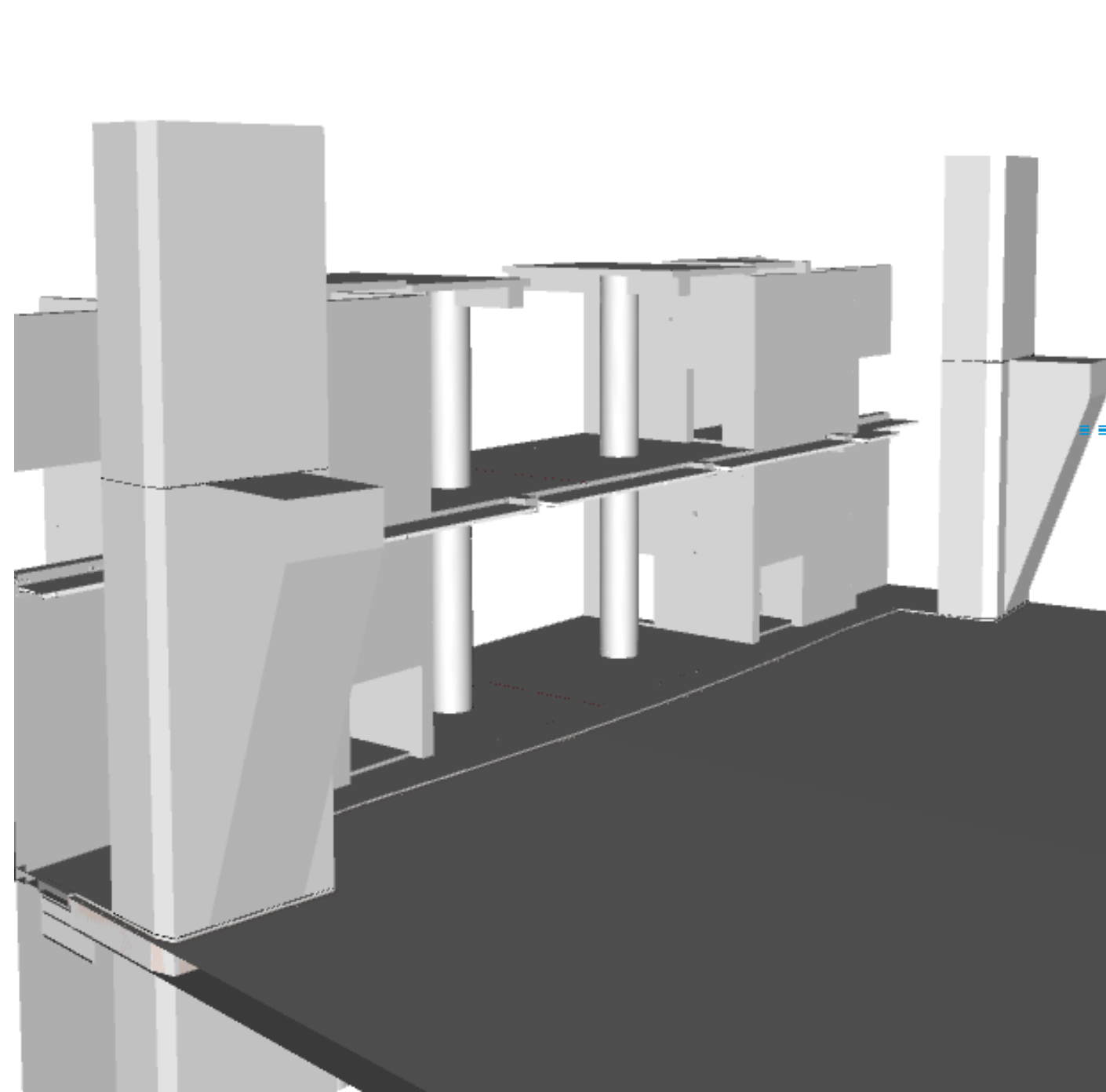


Deviation Analysis of As-Built Model Vs LOD 400 Model

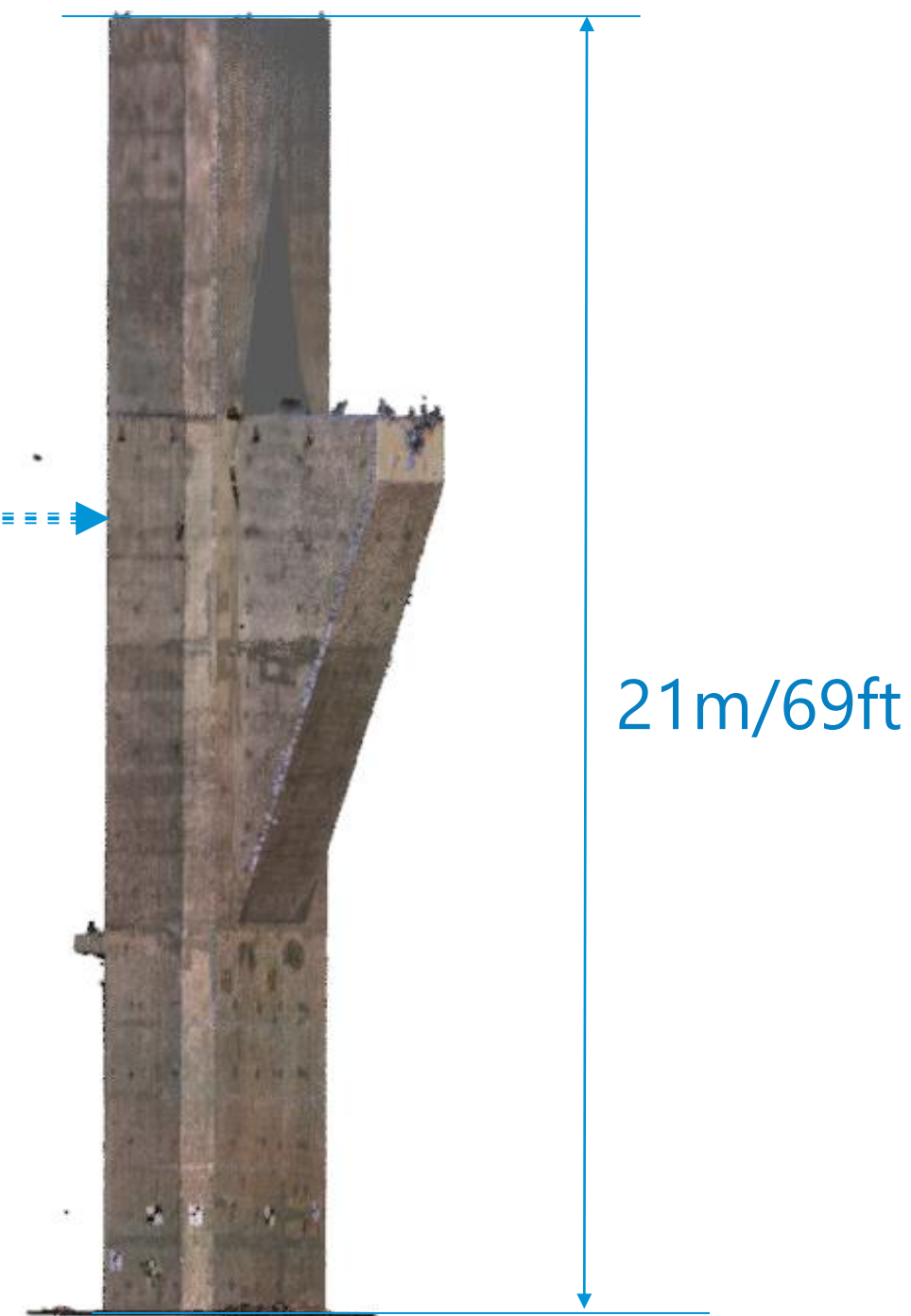
Pinpoint analysis & verification of steel elements before assembly & installation using 3D laser scanning



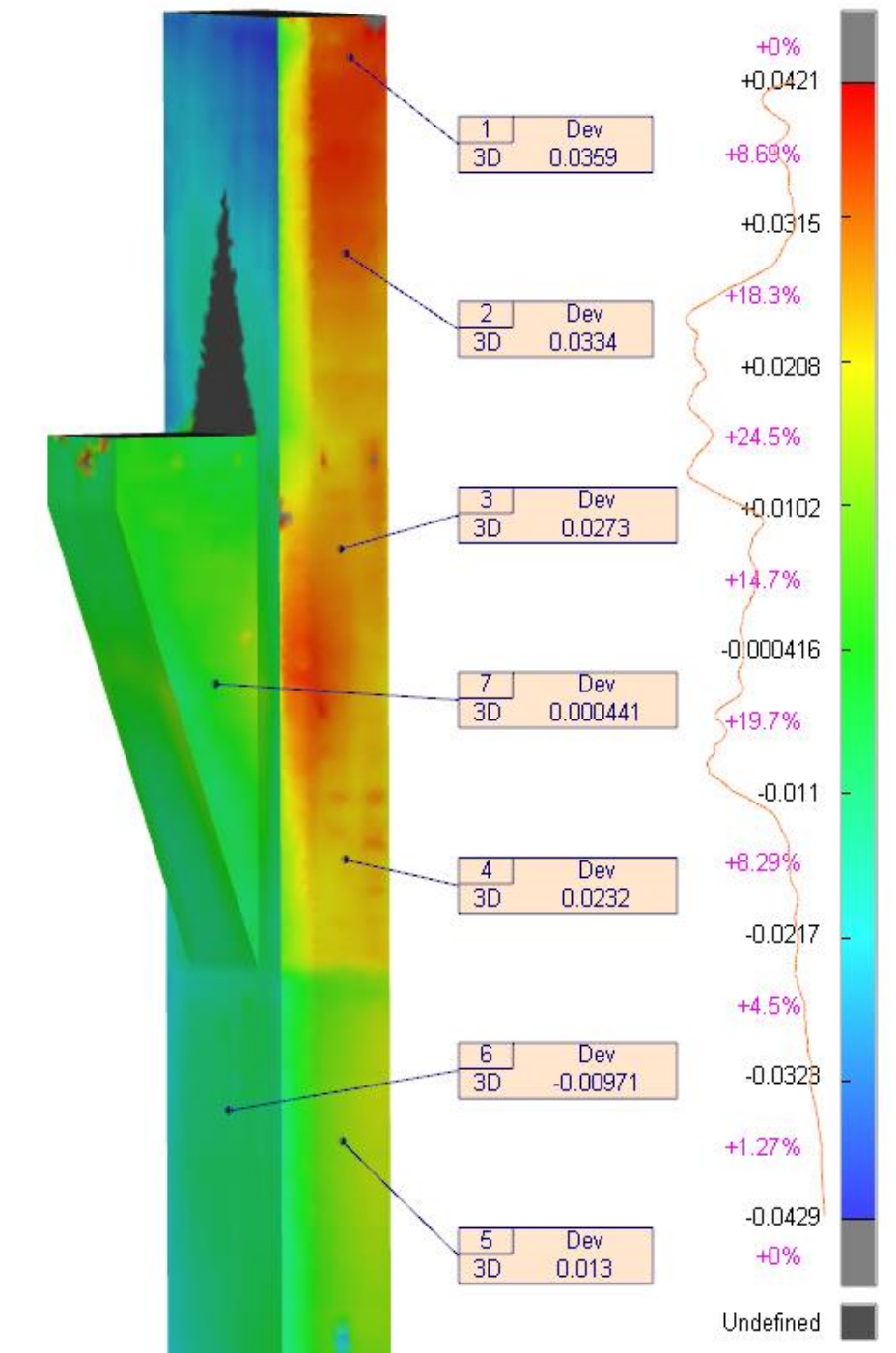
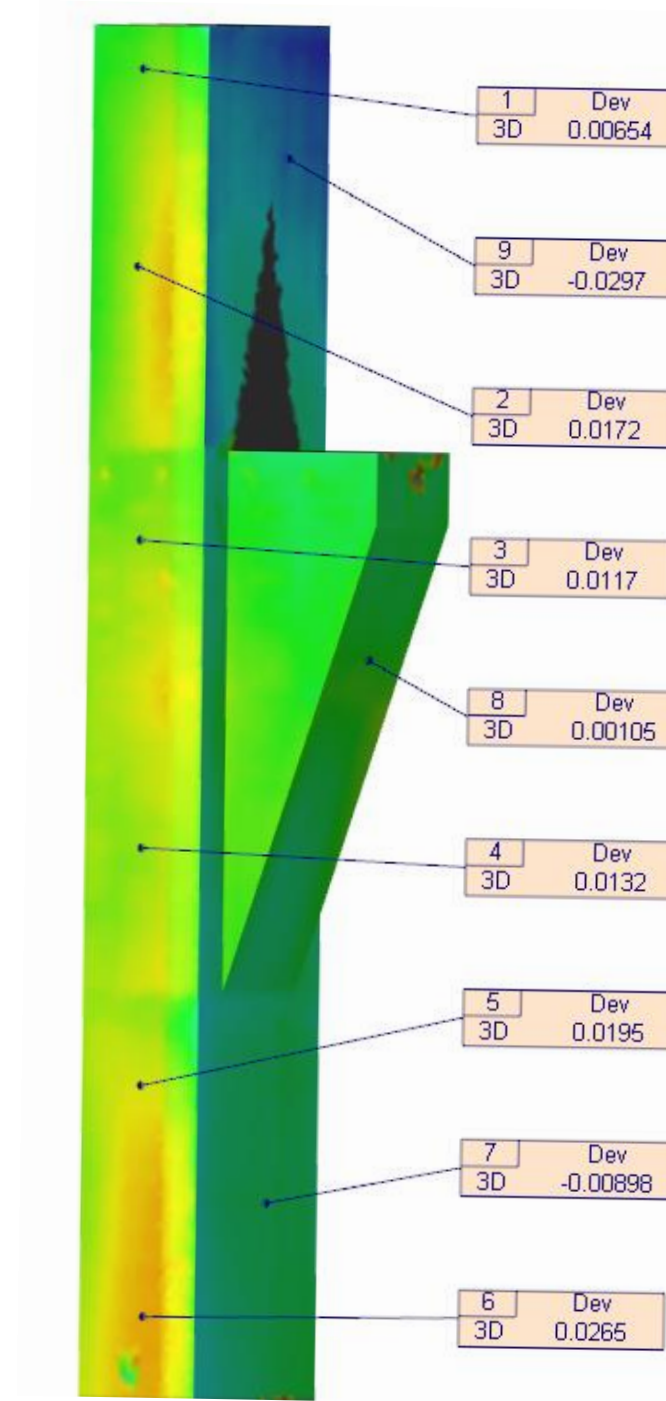
Deflection Monitoring of Long Span Structures - Concrete Buttresses



Concrete Buttresses BIM Model



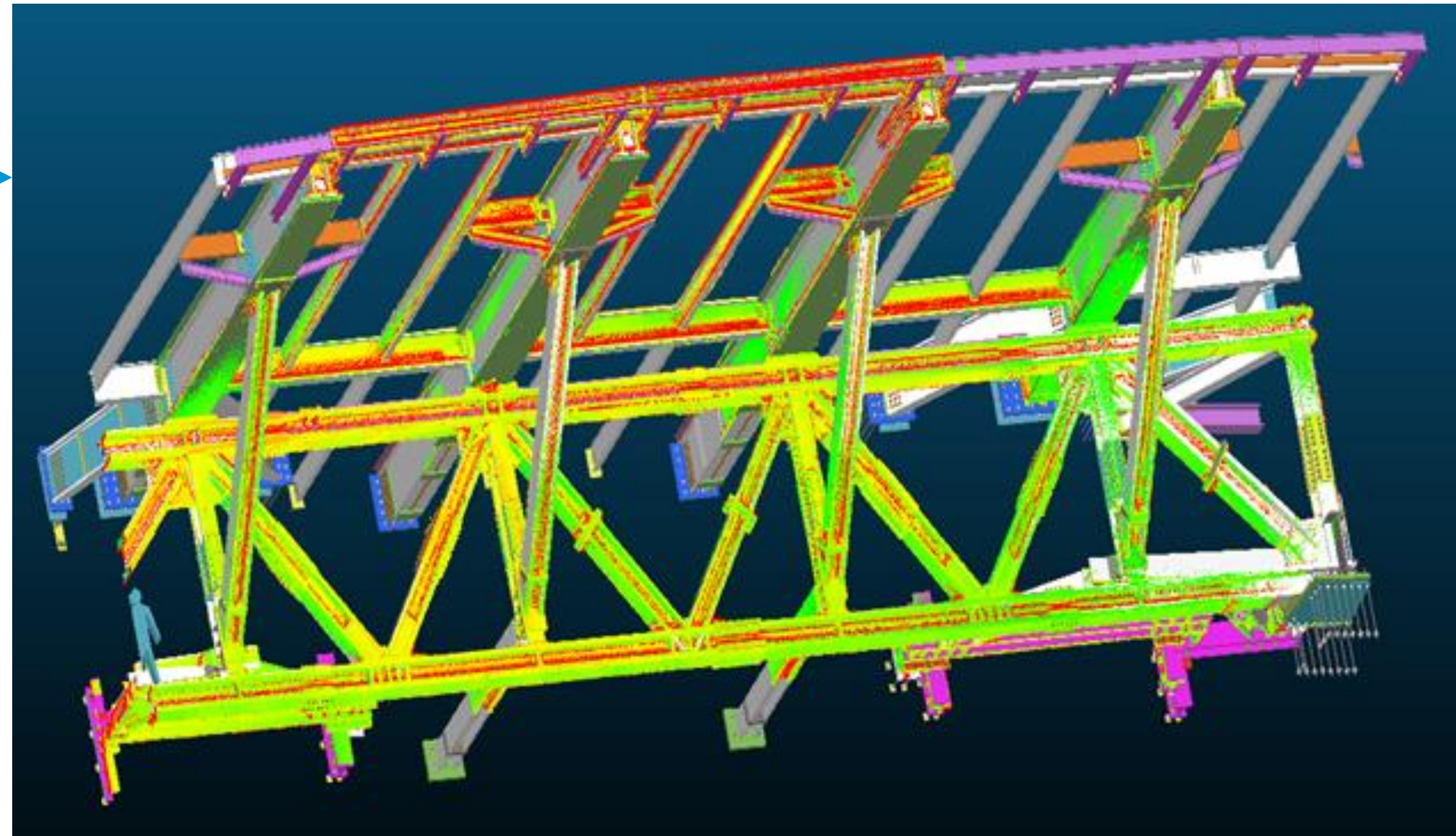
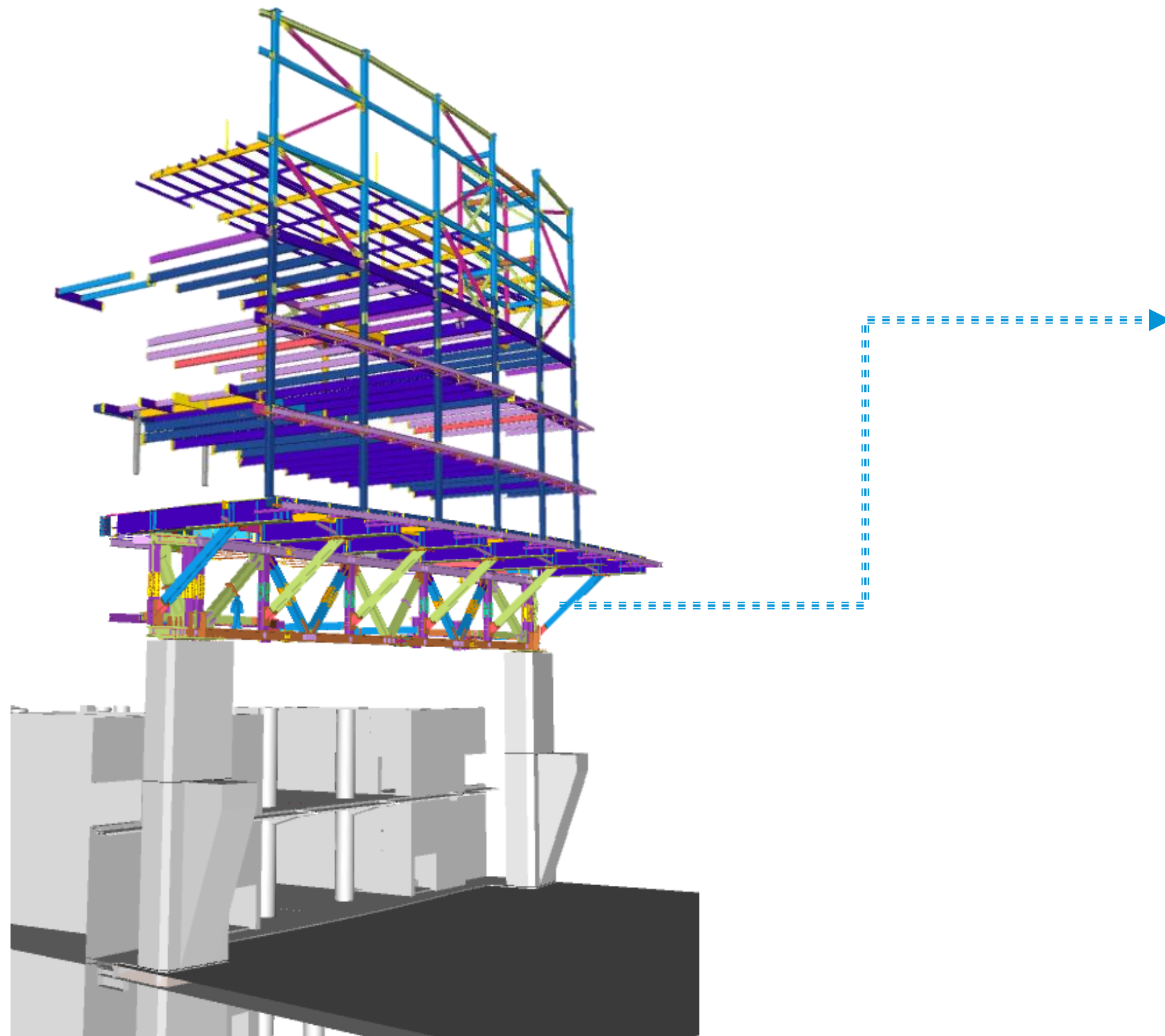
Concrete Buttresses Point Cloud



Deviation Analysis of As-Built Model Vs LOD 400 Model

- ❑ Generation of point cloud versus design BIM Model overlays capturing outputs of deflection mode paths of long span structures
- ❑ Detailed representation of structural elements deformation under various stages of a Project

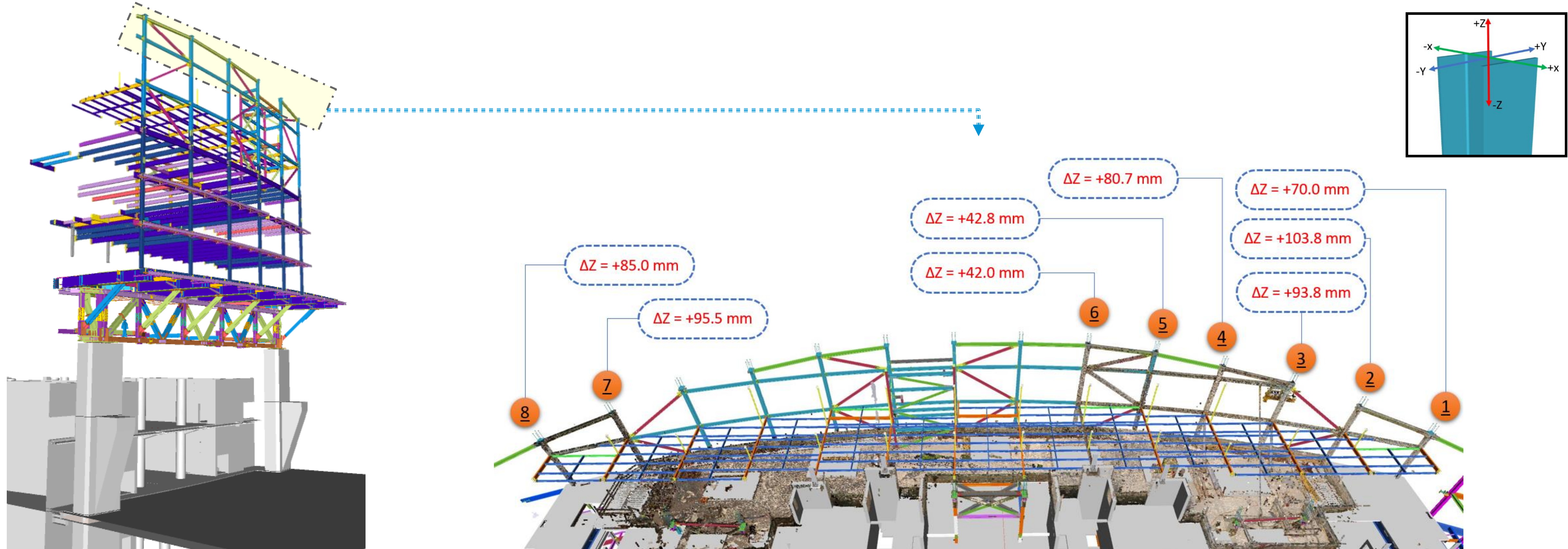
Deflection Monitoring of Long Span Structures – Post Erection Analysis



Deviation Analysis of As-Built Model Vs LOD 400 Model

- ☐ Continuous deformation under construction/service load enables to evaluate and validate all assumptions made by designers against serviceability criteria of structural codes

Deflection Monitoring of Long Span Structures - Post Erection Analysis



- ❑ Comparison of point cloud versus the BIM model is made using a point to point verification software that proved extremely powerful in the deviation analysis workflow we used
- ❑ General Contractors and inspectors used the same methodology for their internal quality assurance and quality control procedures

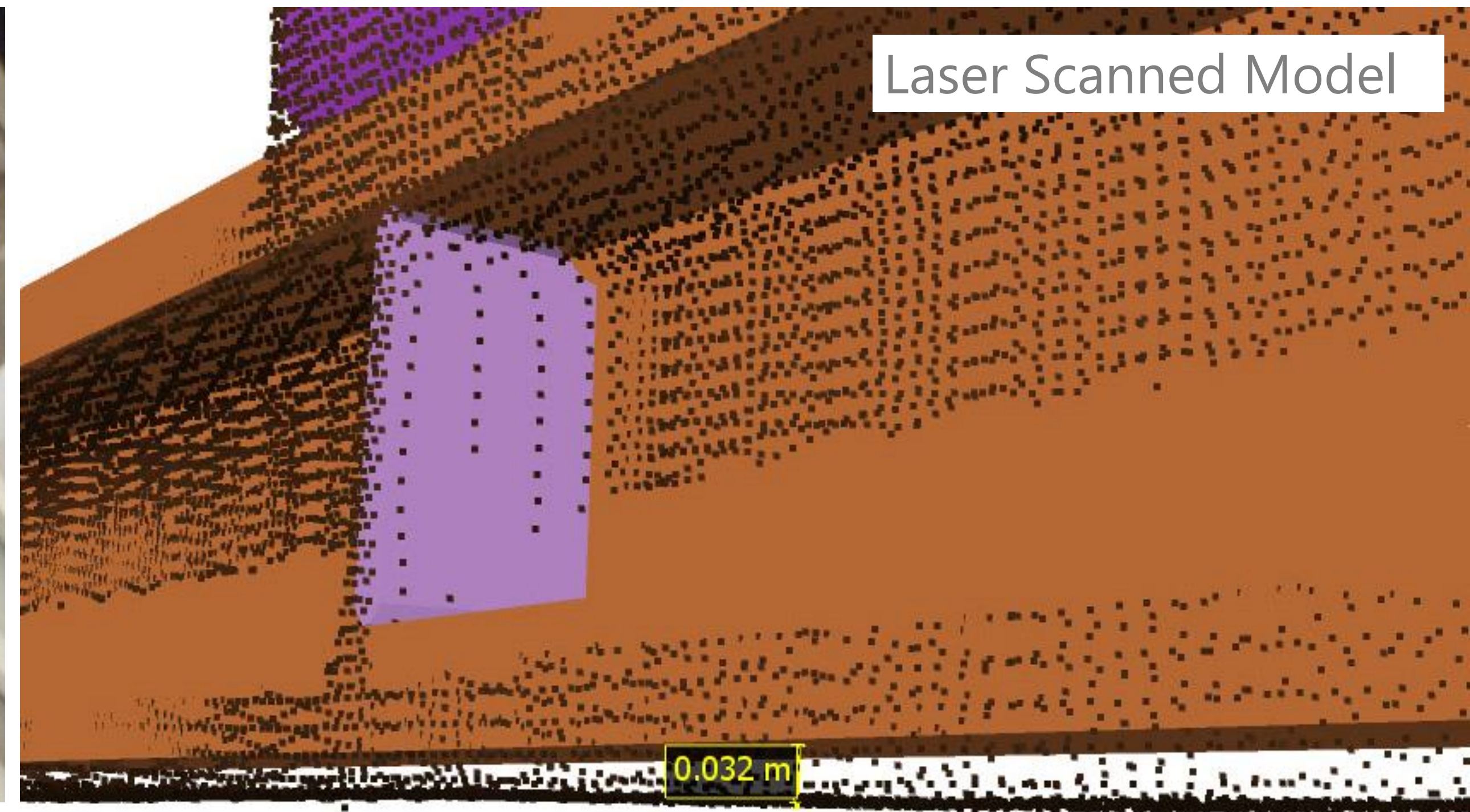
Thickness Measurement of Fire Proofing



Fireproofing Thickness Gauge

Conventional Method

In Conventional Method, thickness of various fire proofing is measured by Fireproofing Thickness Gauge



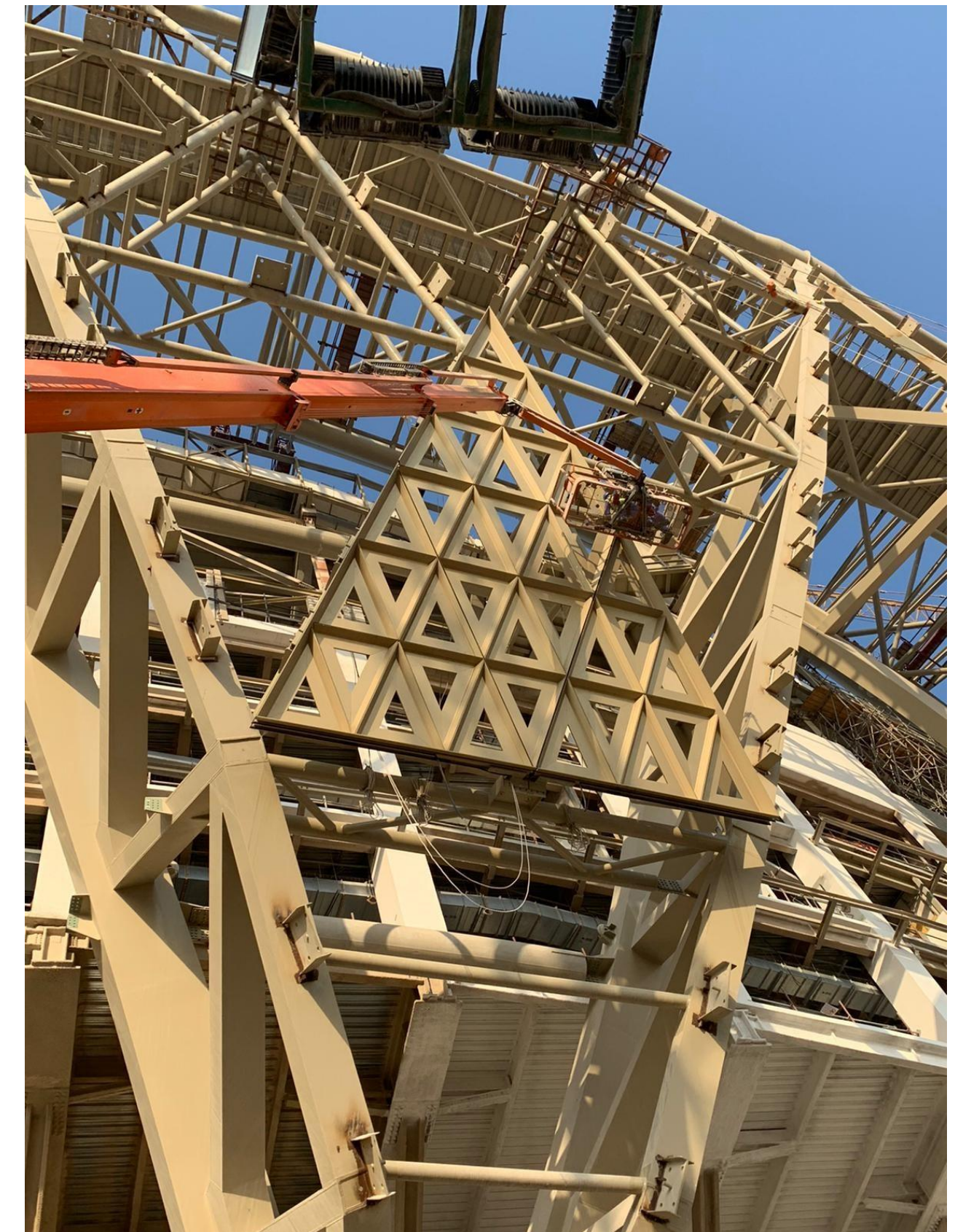
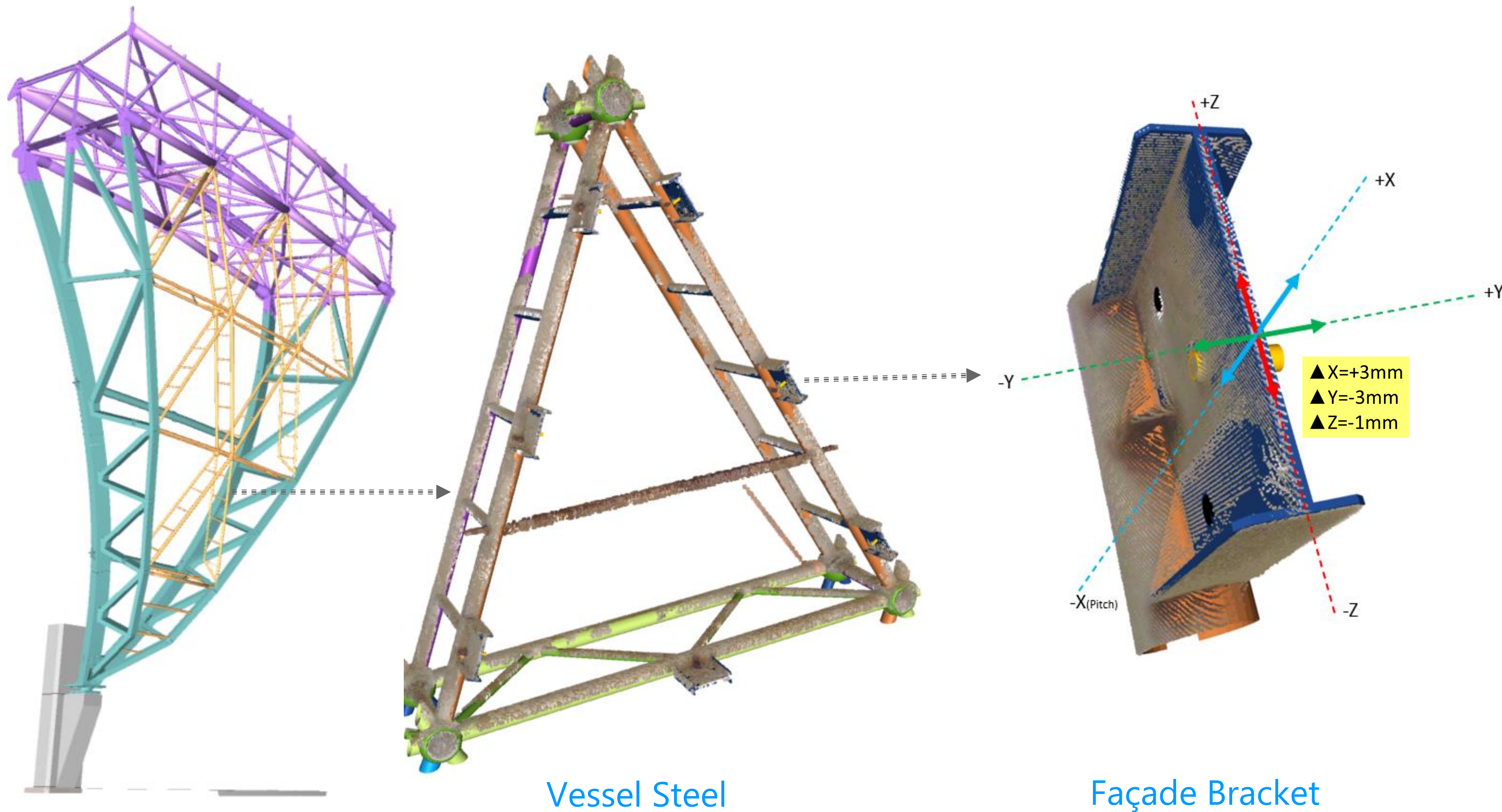
Laser Scanned Model

Laser Scanning Method

Laser Scanning provides clear As-Built model after application of fire proofing. Thickness can easily be measured in BIM environment



Laser Scanning for Inspection

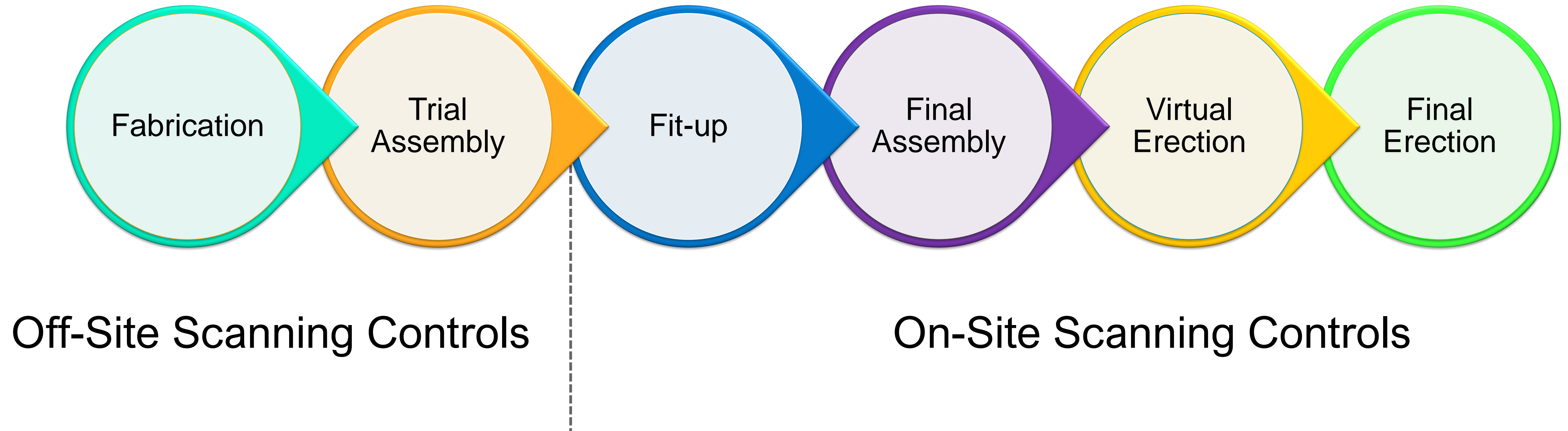


Façade Erection

- ❑ Façade Bracket installed in place within the allowable tolerance
- ❑ It helps to validate the installation procedure for huge number of brackets



Roadmap of Steel & Facade Structure Delivery



Fabrication

Fabrication

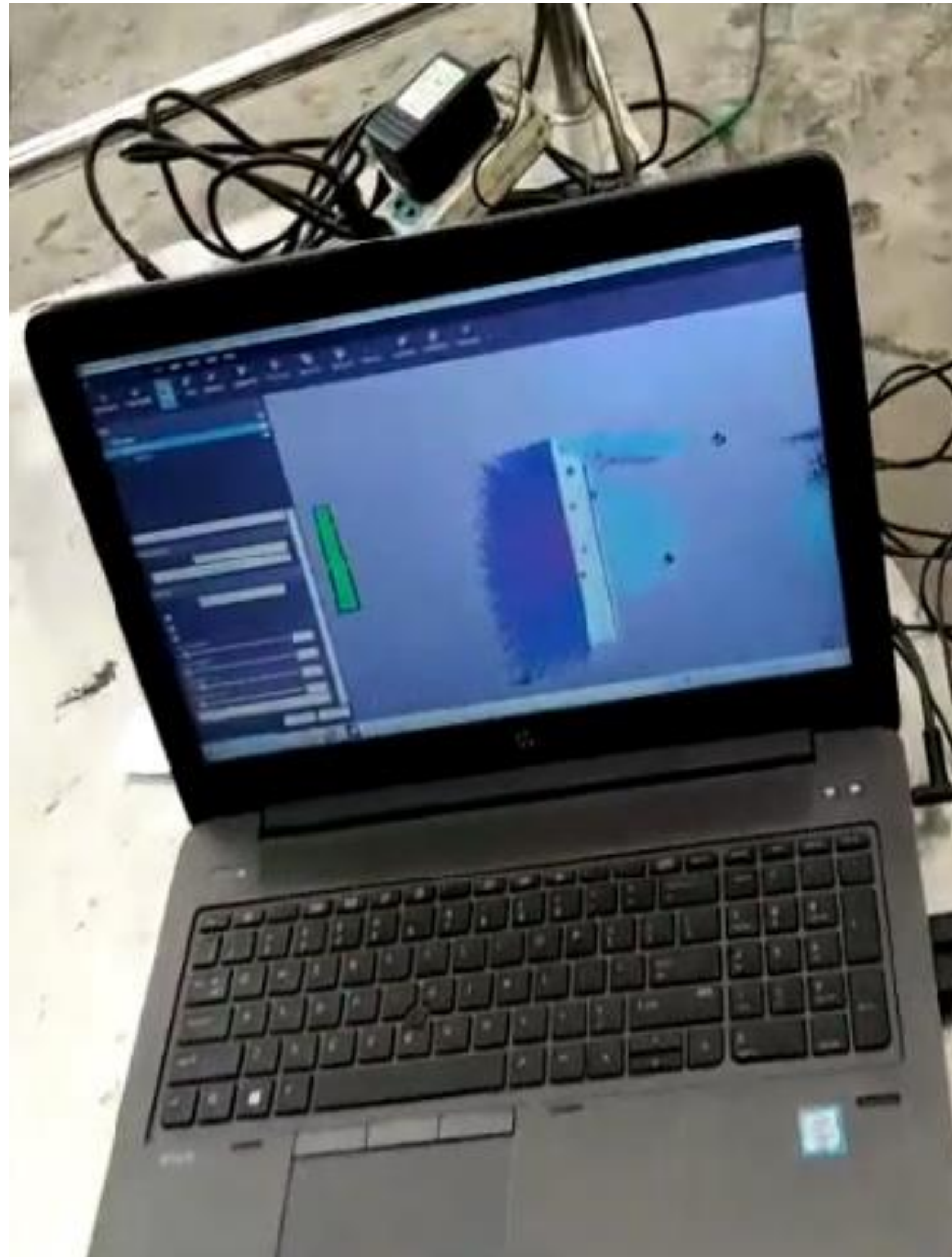
Trial
Assembly

Fit-up

Final
Assembly

Virtual
Erection

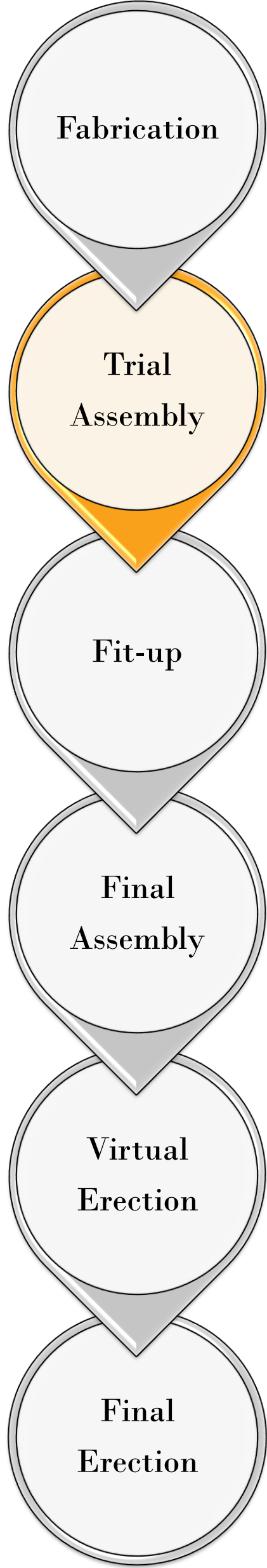
Final
Erection



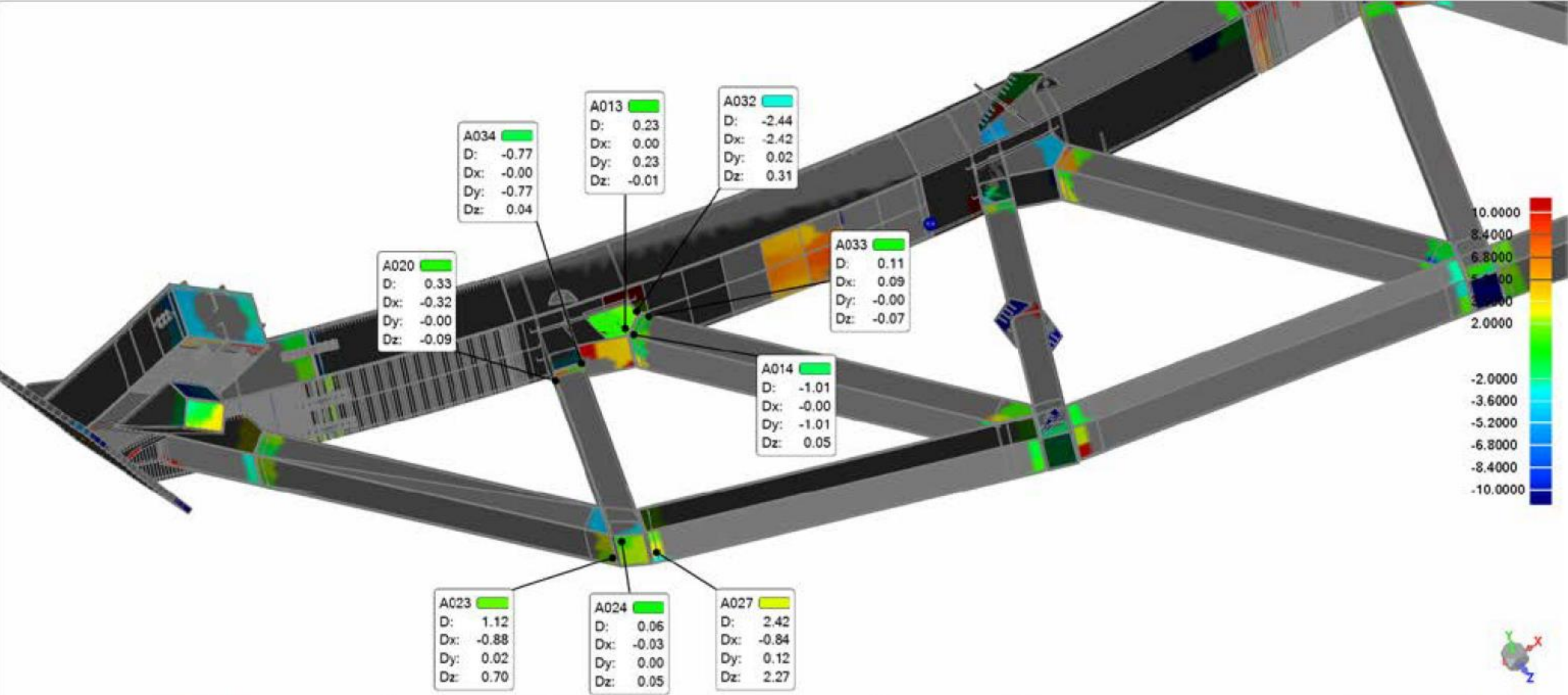
Generative Model

3D Laser Scanning for Web Chord





Trial Assembly



Item	Deviation	State	Tolerance	Refer X	Refer Y	Refer Z	Deviation X	Deviation Y	Deviation Z	Test X	Test Y	Test Z
A013	0.23	Pass	±3	84864.06	-322.24	-831.09	0.00	0.23	-0.01	84864.06	-322.01	-831.10
A014	-1.01	Pass	±3	84906.49	-313.96	-667.05	-0.00	-1.01	0.05	84906.49	-314.97	-667.00
A020	0.33	Pass	±3	83632.94	-441.40	-726.14	-0.32	-0.00	-0.09	83632.62	-441.40	-726.22
A023	1.12	Pass	±3	82811.76	-718.21	2144.57	-0.88	0.02	0.70	82810.88	-718.19	2145.27
A024	0.06	Pass	±3	82957.81	-306.81	2252.47	-0.03	0.00	0.05	82957.78	-306.81	2252.52
A027	2.42	Pass	±3	83352.17	-642.10	2483.28	-0.84	0.12	2.27	83351.32	-641.98	2485.54
A032	-2.44	Pass	±3	85166.21	-415.94	-1044.51	-2.42	0.02	0.31	85163.78	-415.92	-1044.20
A033	0.11	Pass	±3	85259.47	-400.15	-858.85	0.09	-0.00	-0.07	85259.56	-400.16	-858.92
A034	-0.77	Pass	±3	84048.68	-312.61	-679.46	-0.00	-0.77	0.04	84048.68	-313.38	-679.42

On-site Inspection After Shipping

Fabrication

Trial
Assembly

Fit-up

Final
Assembly

Virtual
Erection

Final
Erection

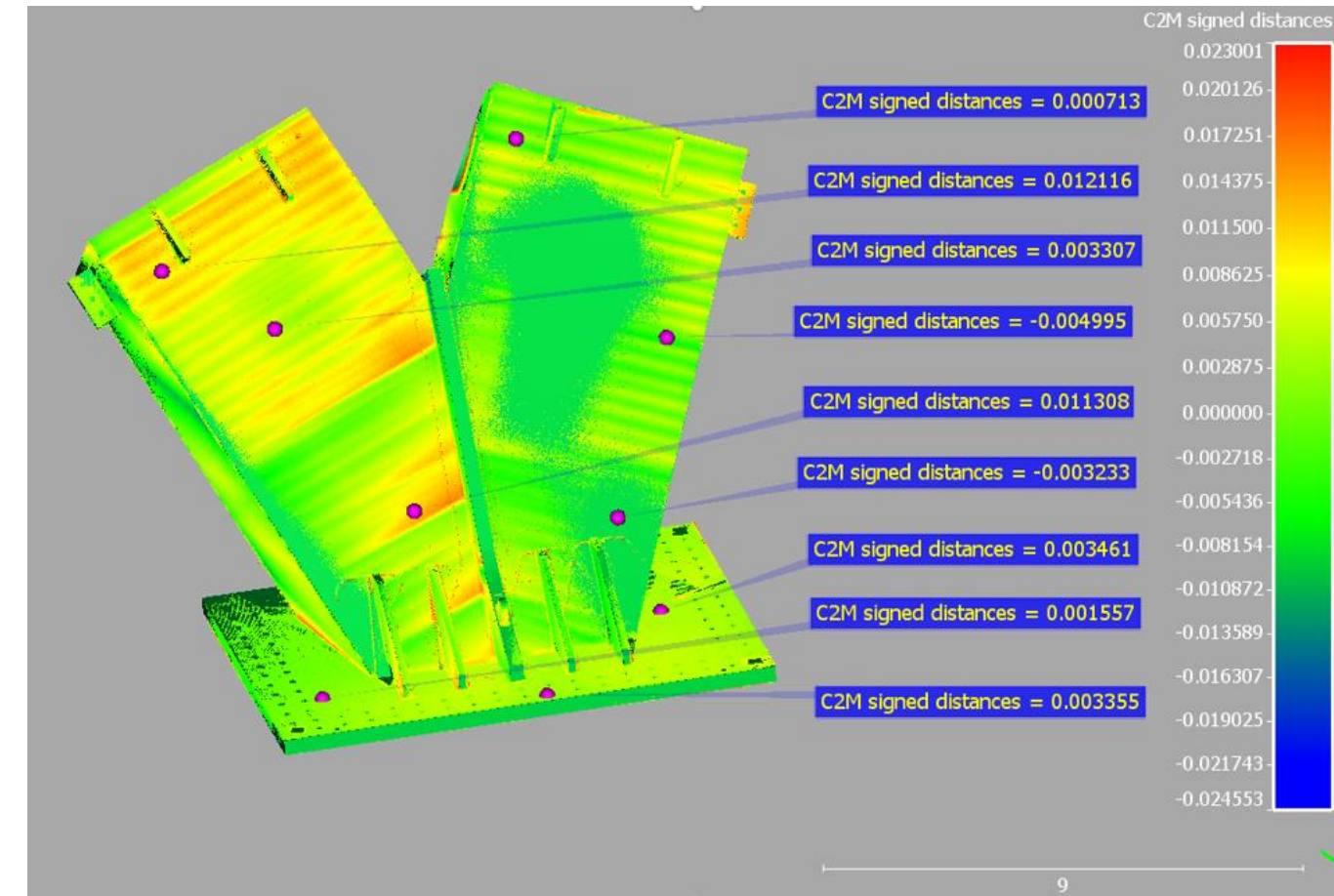
On-Site Scanning of
Steel Part



Point Cloud Model of Steel
Part



Deviation Analysis of As-Built Vs
LOD 400 Model



Actual Fit-up On-Site



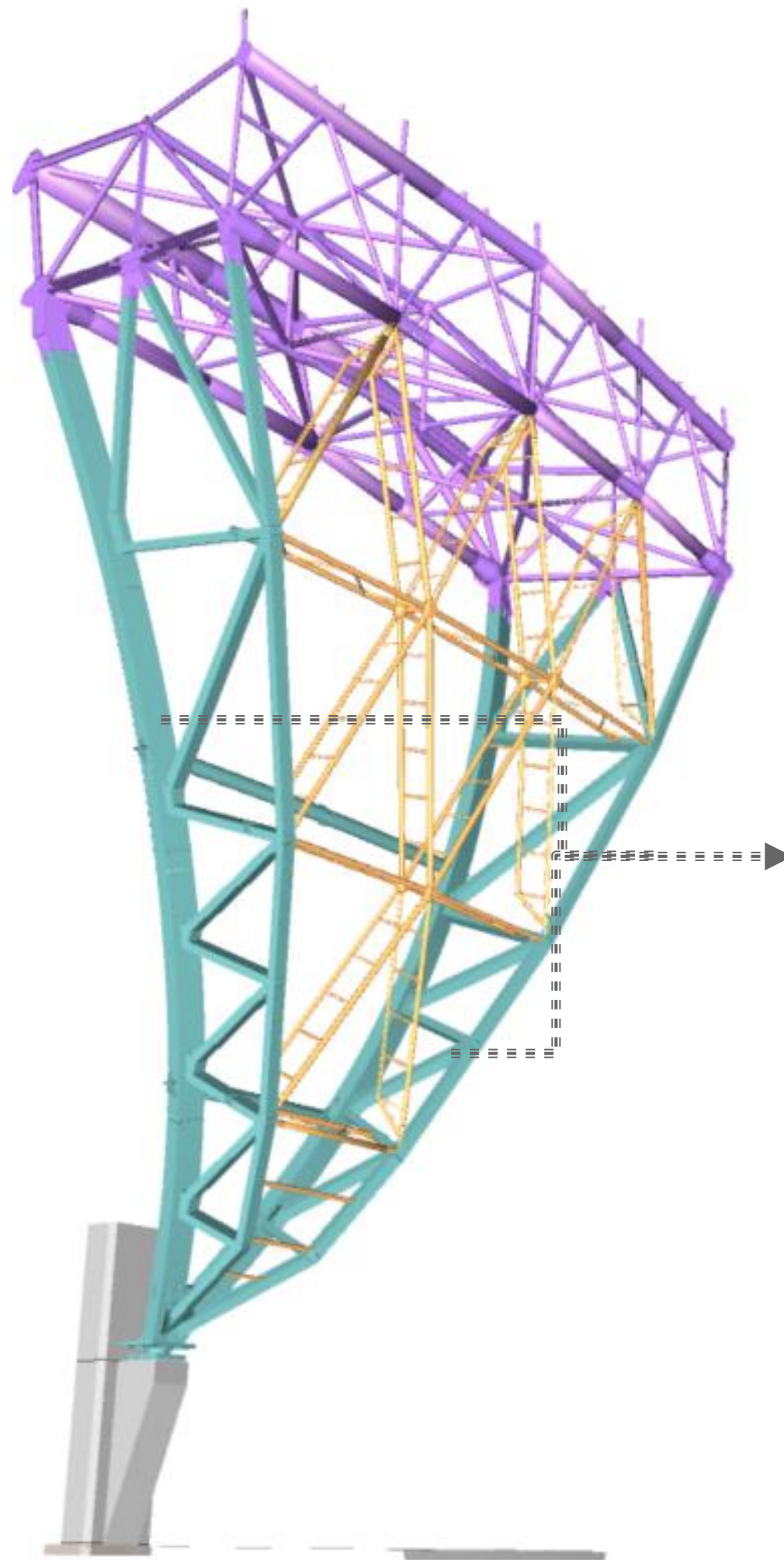
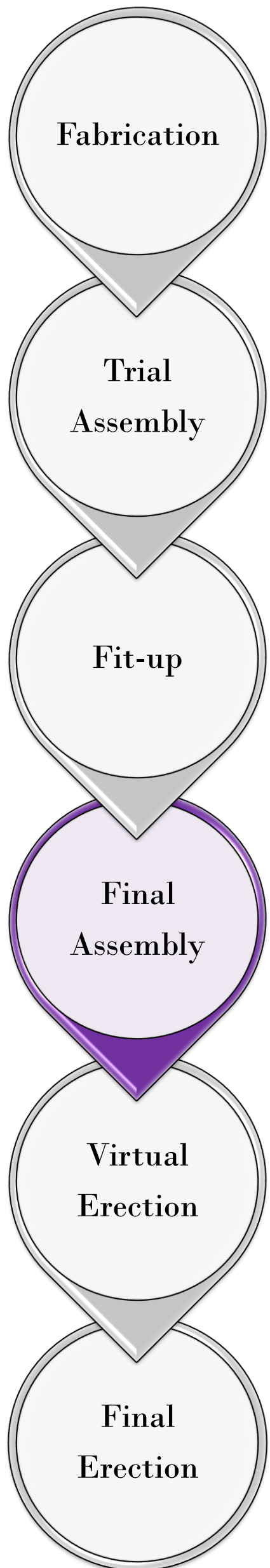
Pinpoint Analysis & Verification of steel elements before assembly & installation using 3D Laser Scanning

- Conclusions** – 1. Base plate of steel part is fabricated with 0.5mm accuracy
2. Deviation beyond 30mm from the design location which is taken into account by designer to accept it or rectify before assembly



Deflection Monitoring & Control of Long Span Structures

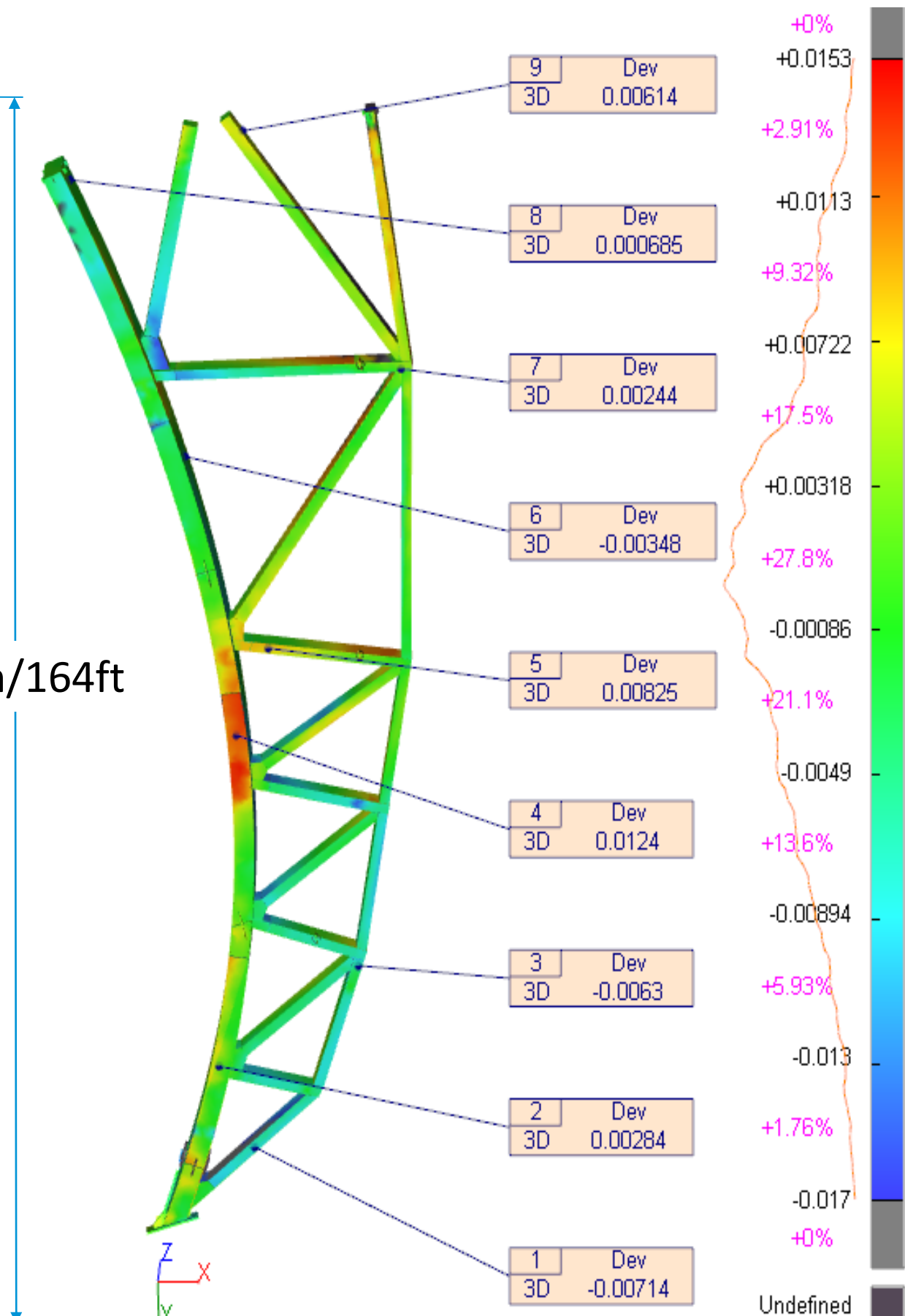
Analysis of Steel Frame



Steel Frame Assembly



Steel Frame Point Cloud



Virtual Erection of Steel Frame

Fabrication

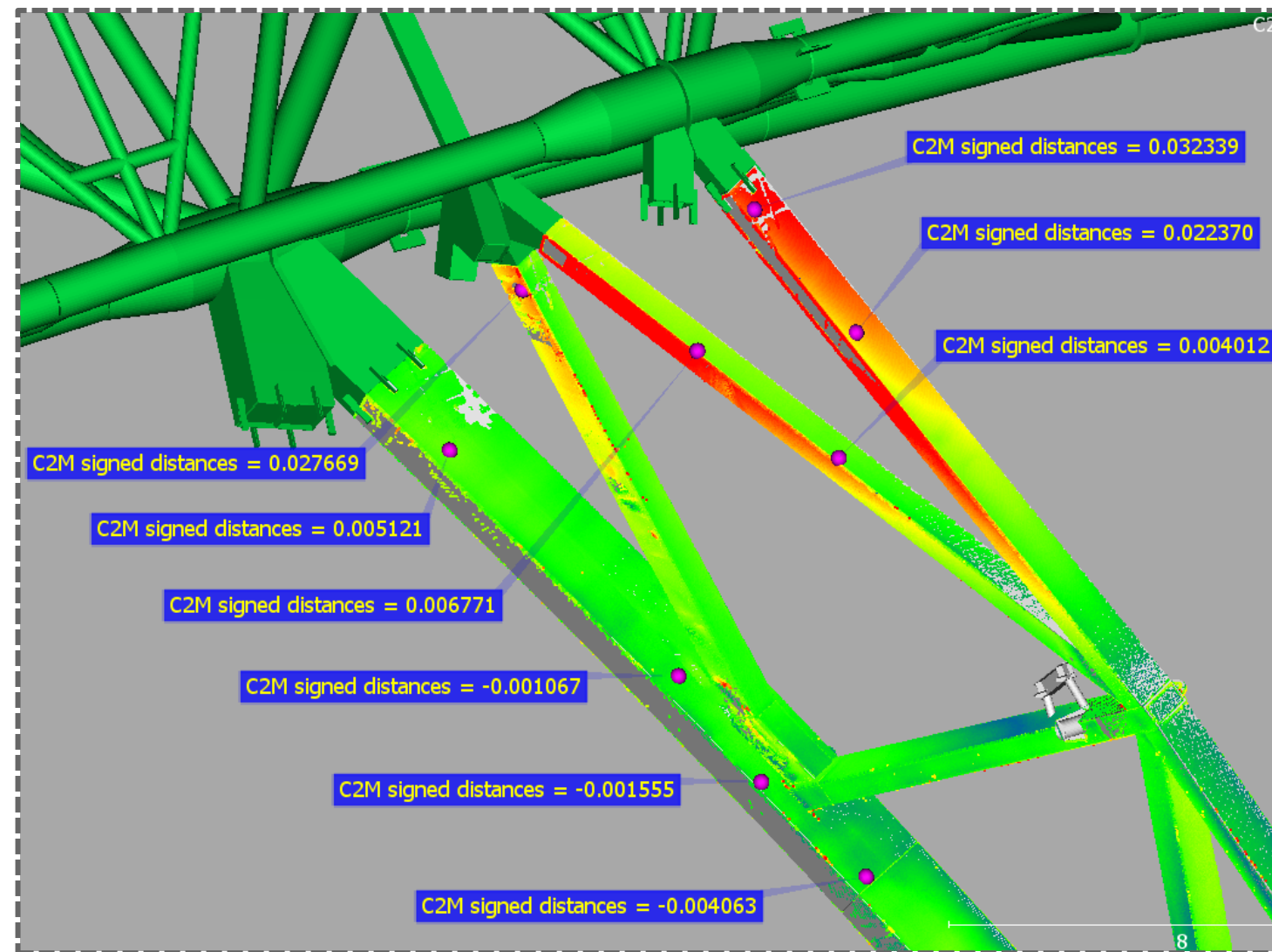
Trial
Assembly

Fit-up

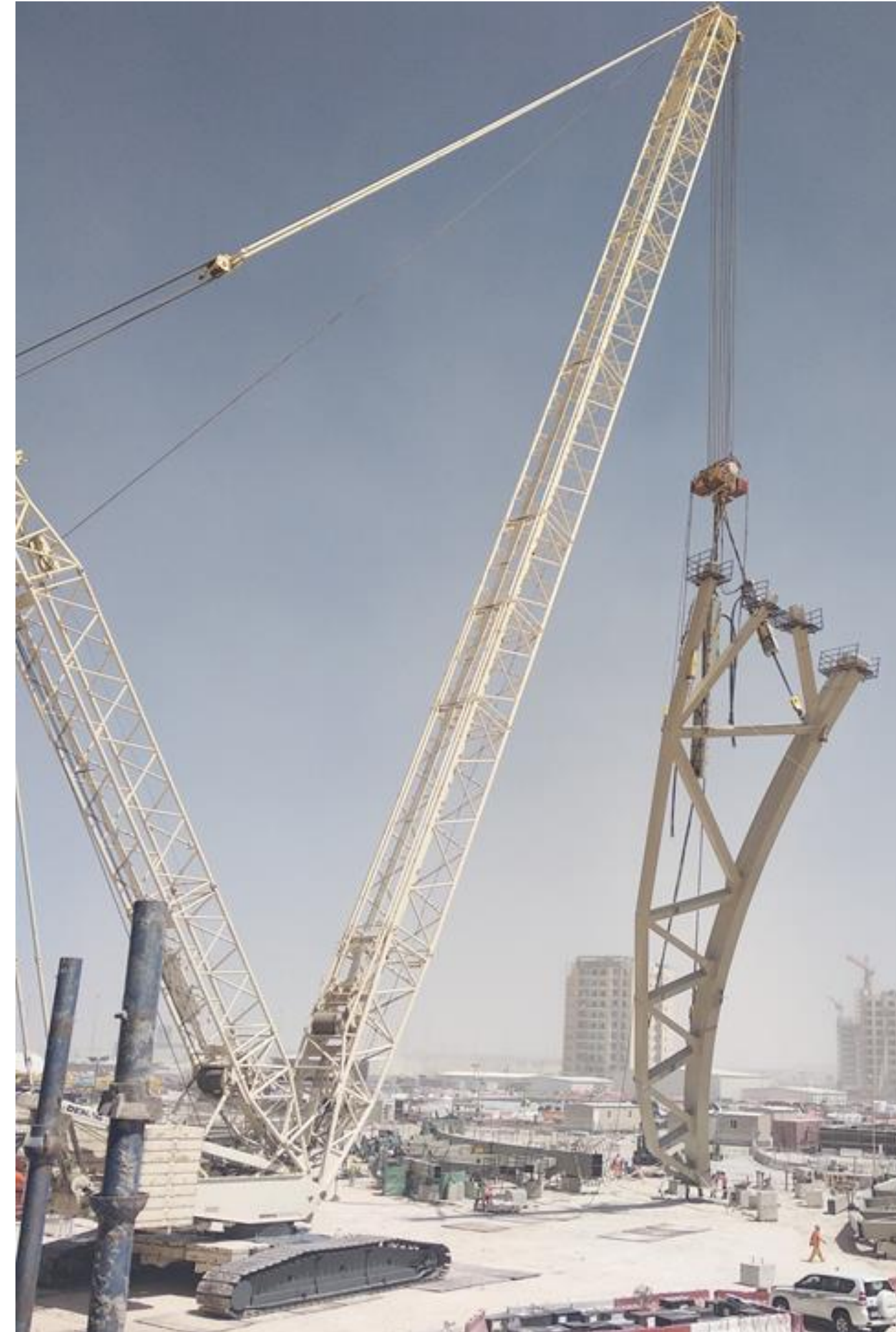
Final
Assembly

Virtual
Erection

Final
Erection



The point cloud model moved to design location virtually in software to check the errors before lifting



Lifting Sequences



Virtual Erection of Compression Ring(CR)

Fabrication

Trial
Assembly

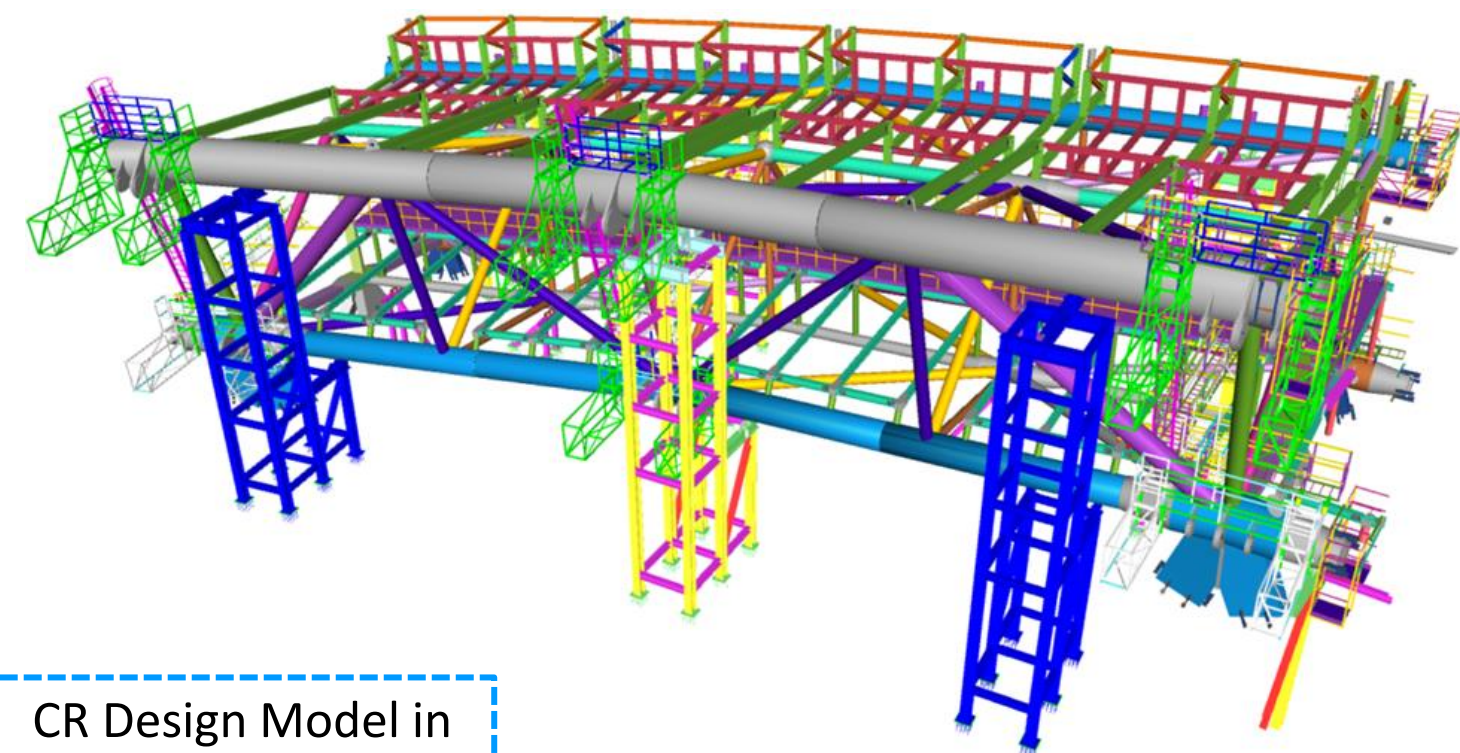
Fit-up

Final
Assembly

Virtual
Erection

Final
Erection

1



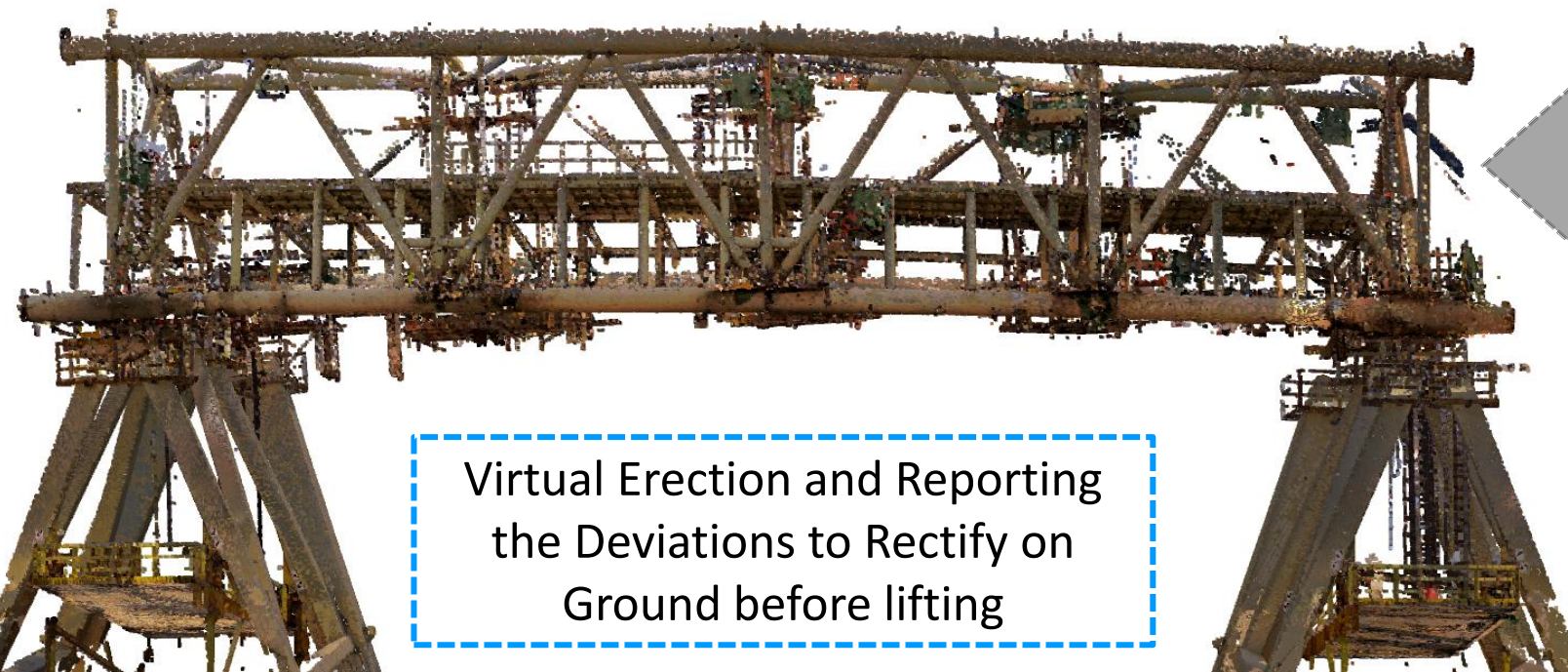
CR Design Model in
Fabrication Yard

2



CR Point Cloud in
Fabrication Yard

4



Virtual Erection and Reporting
the Deviations to Rectify on
Ground before lifting

3



CR Moved from Fabrication Yard
to Design Location to Perform
Best Fit Alignment



Virtual Erection of Compression Ring – Closer Segment

Fabrication

Trial
Assembly

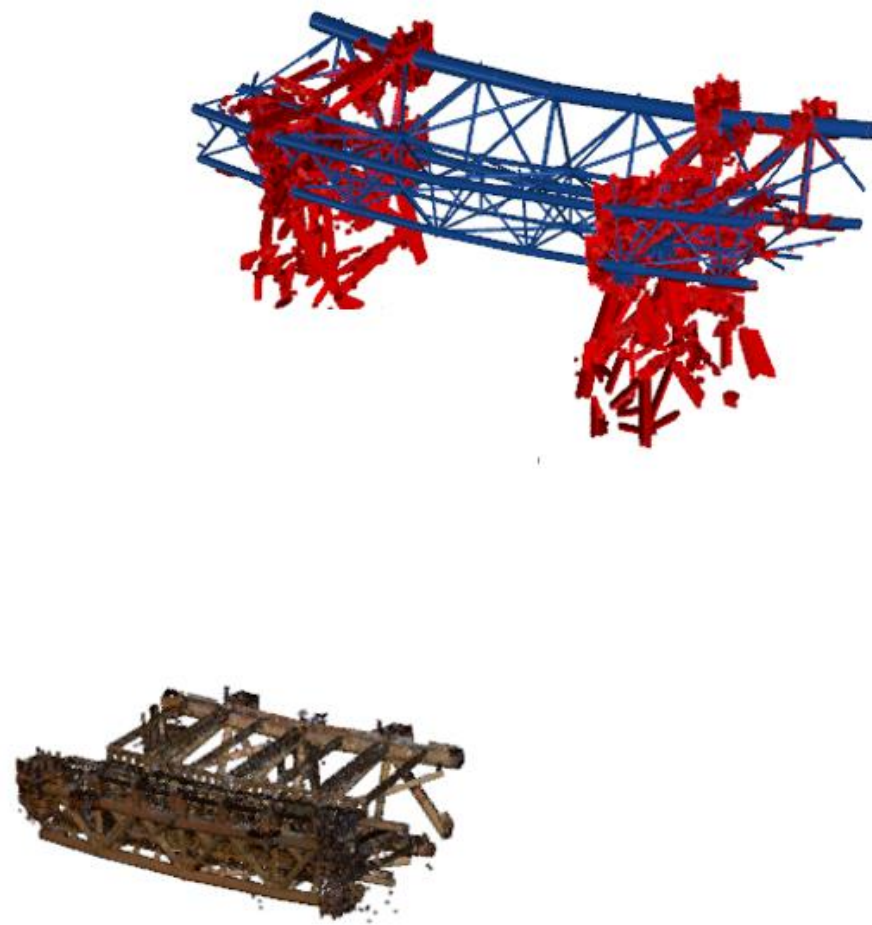
Fit-up

Final
Assembly

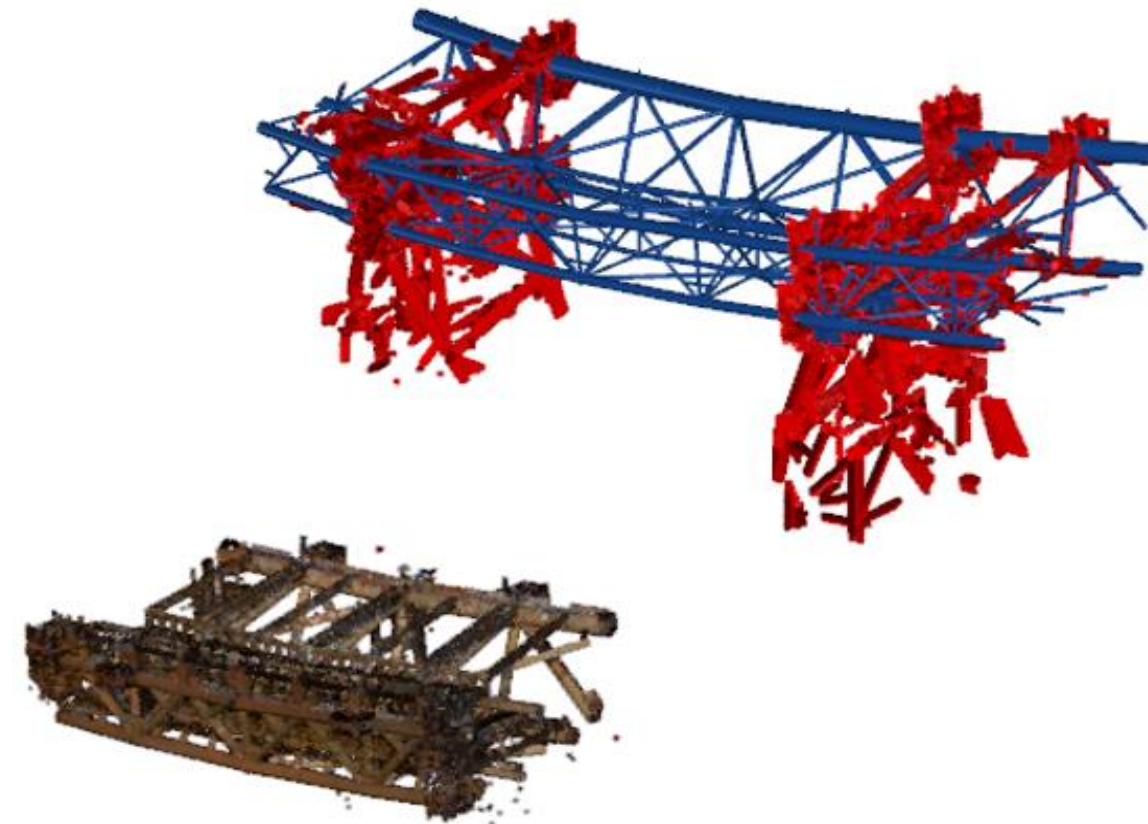
Virtual
Erection

Final
Erection

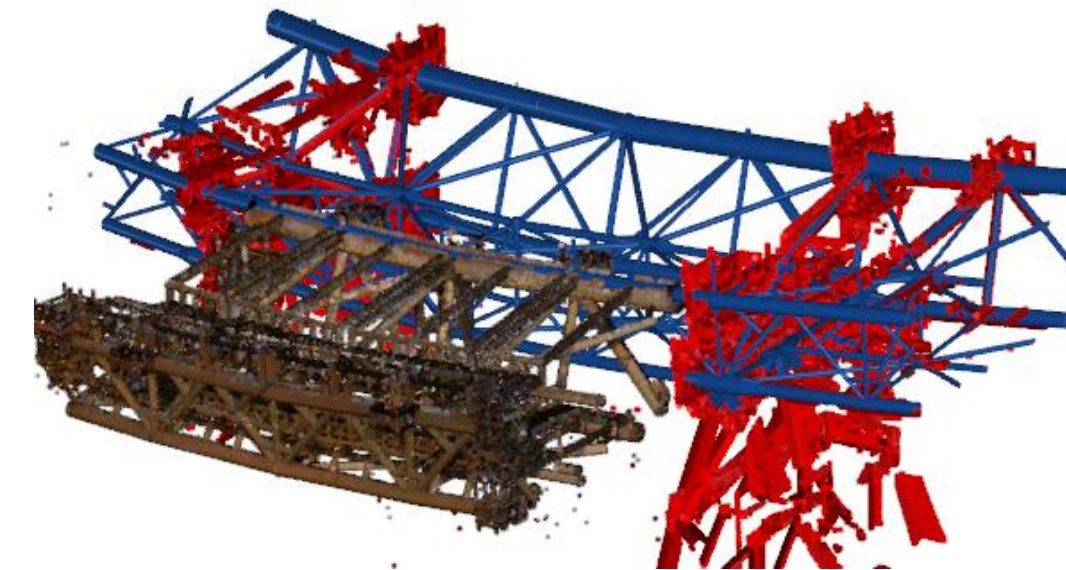
Stage 1
CR Level – +5m



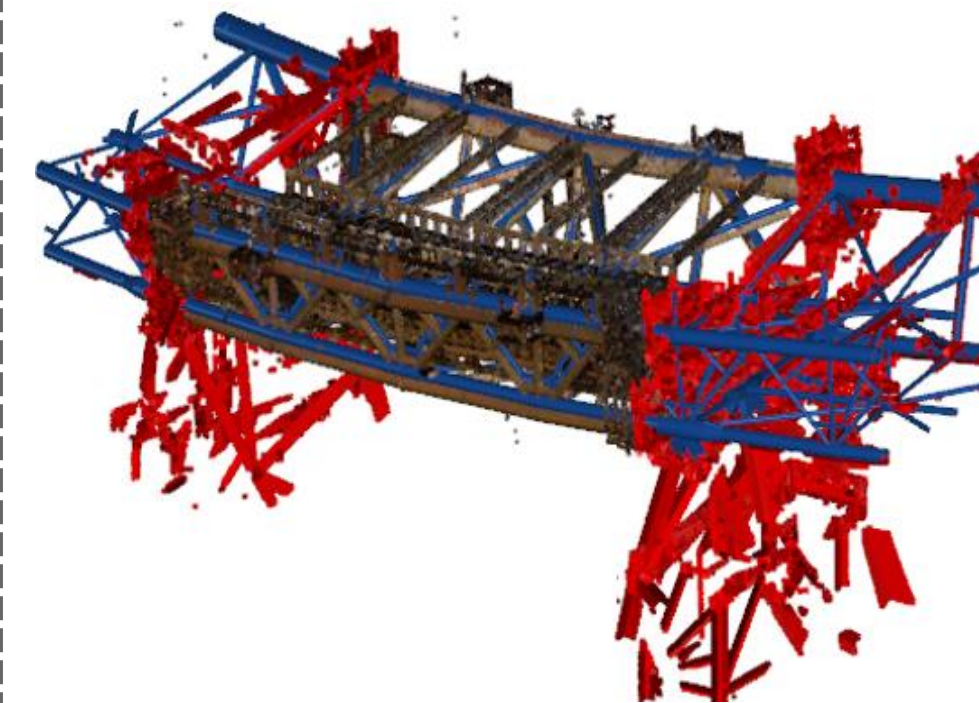
Stage 2
CR Level – +48m



Stage 3
CR Level – +60m



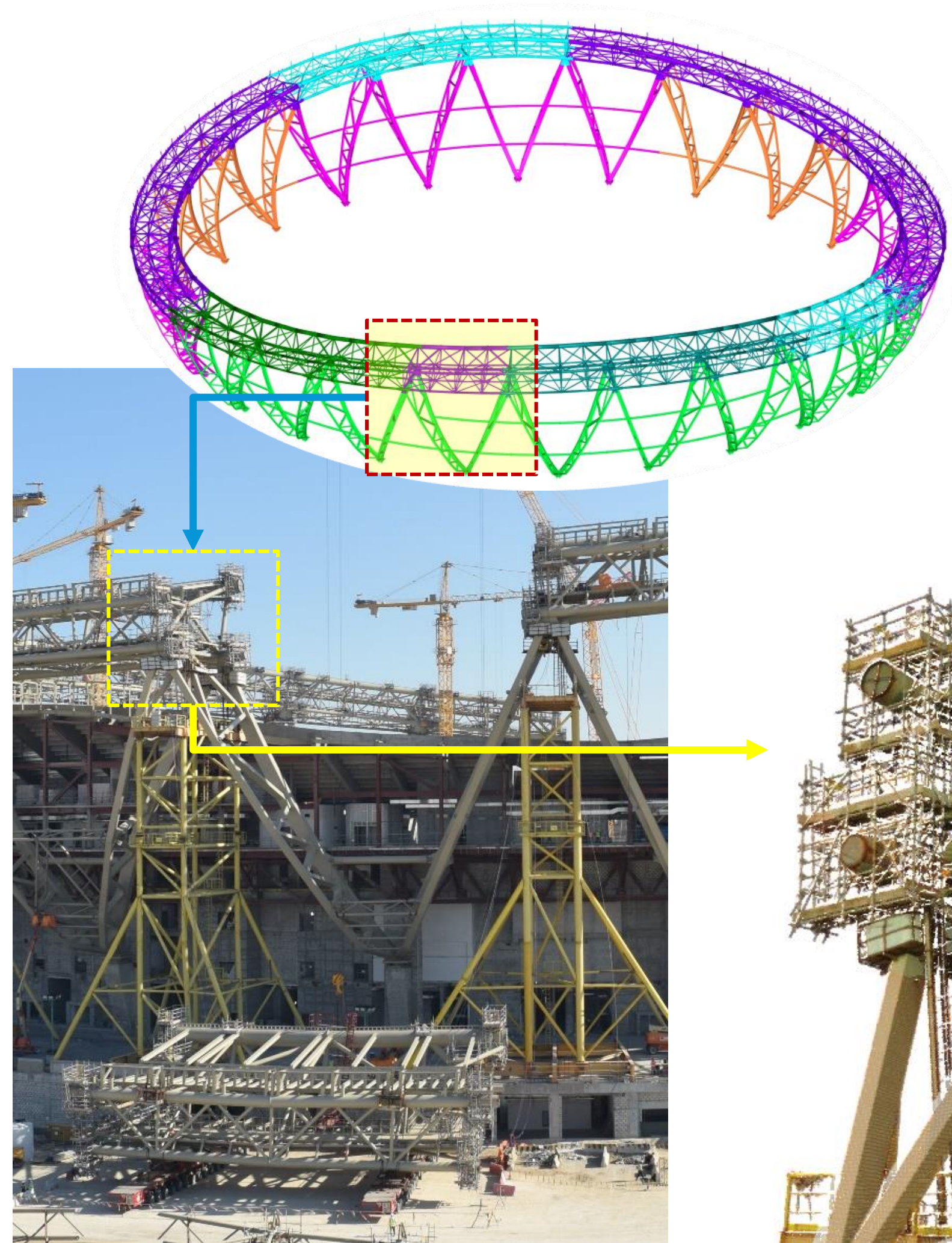
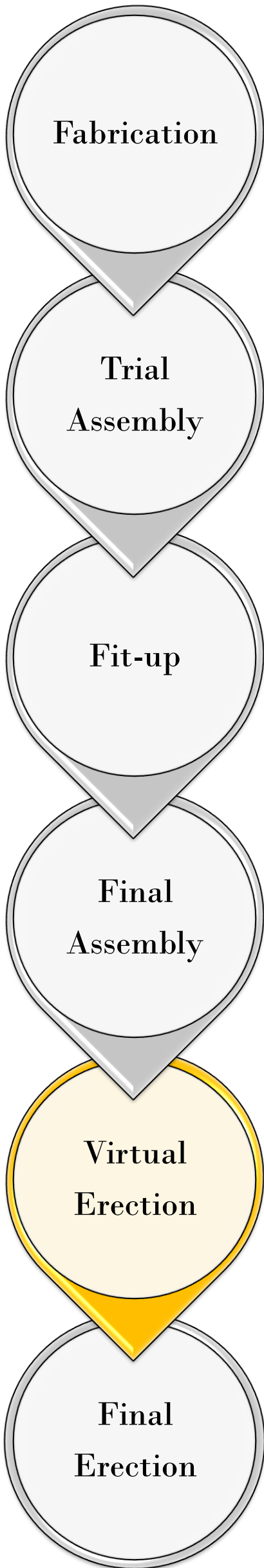
Stage 4
CR Level – +60m



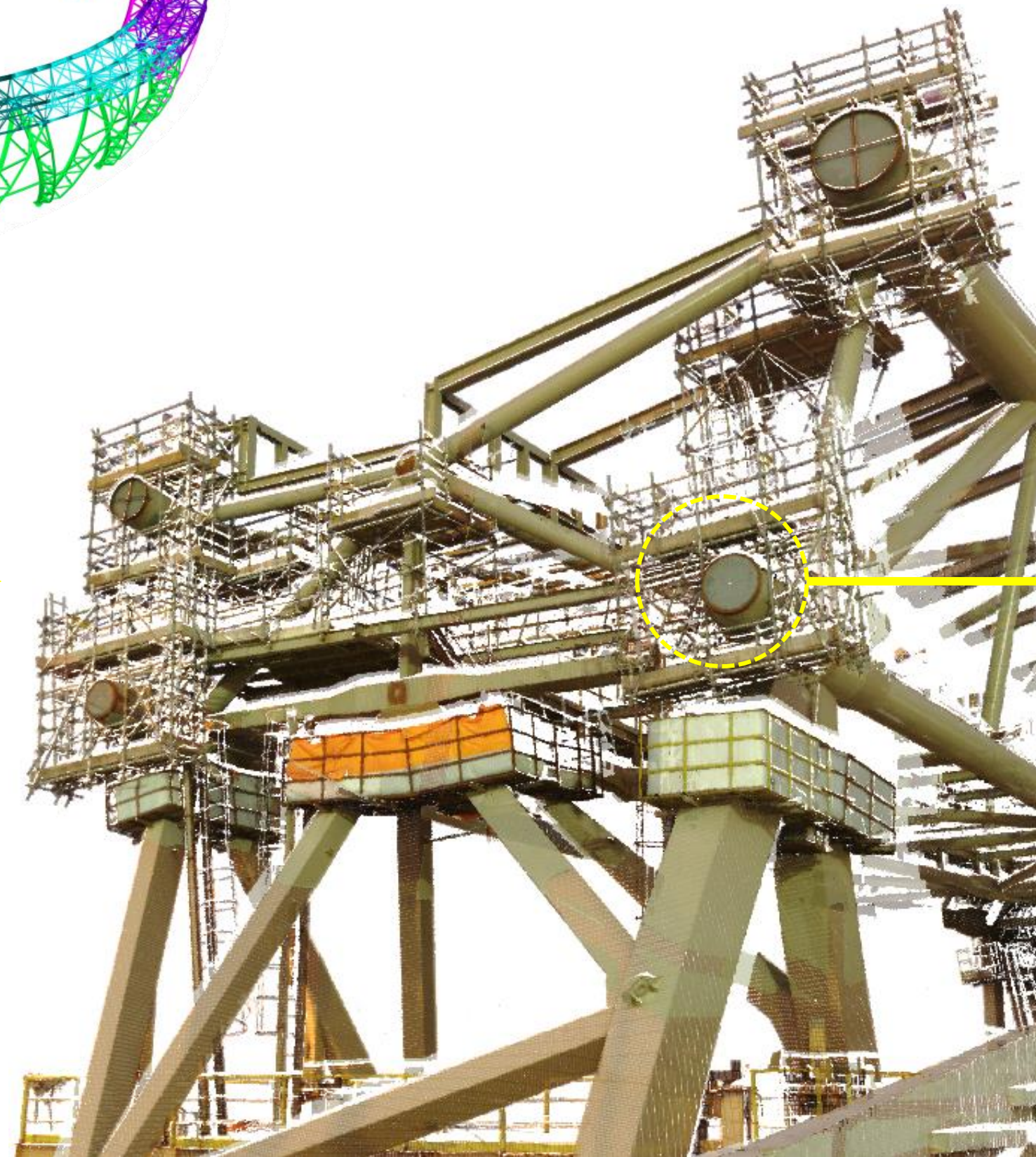
- Conclusions –**
1. Extraction of lifting path to adjust the segment properly in place
 2. Identification of clashes with As-built elements to rectify on ground before lifting
 3. Reduction of lifting attempts by one lifting path



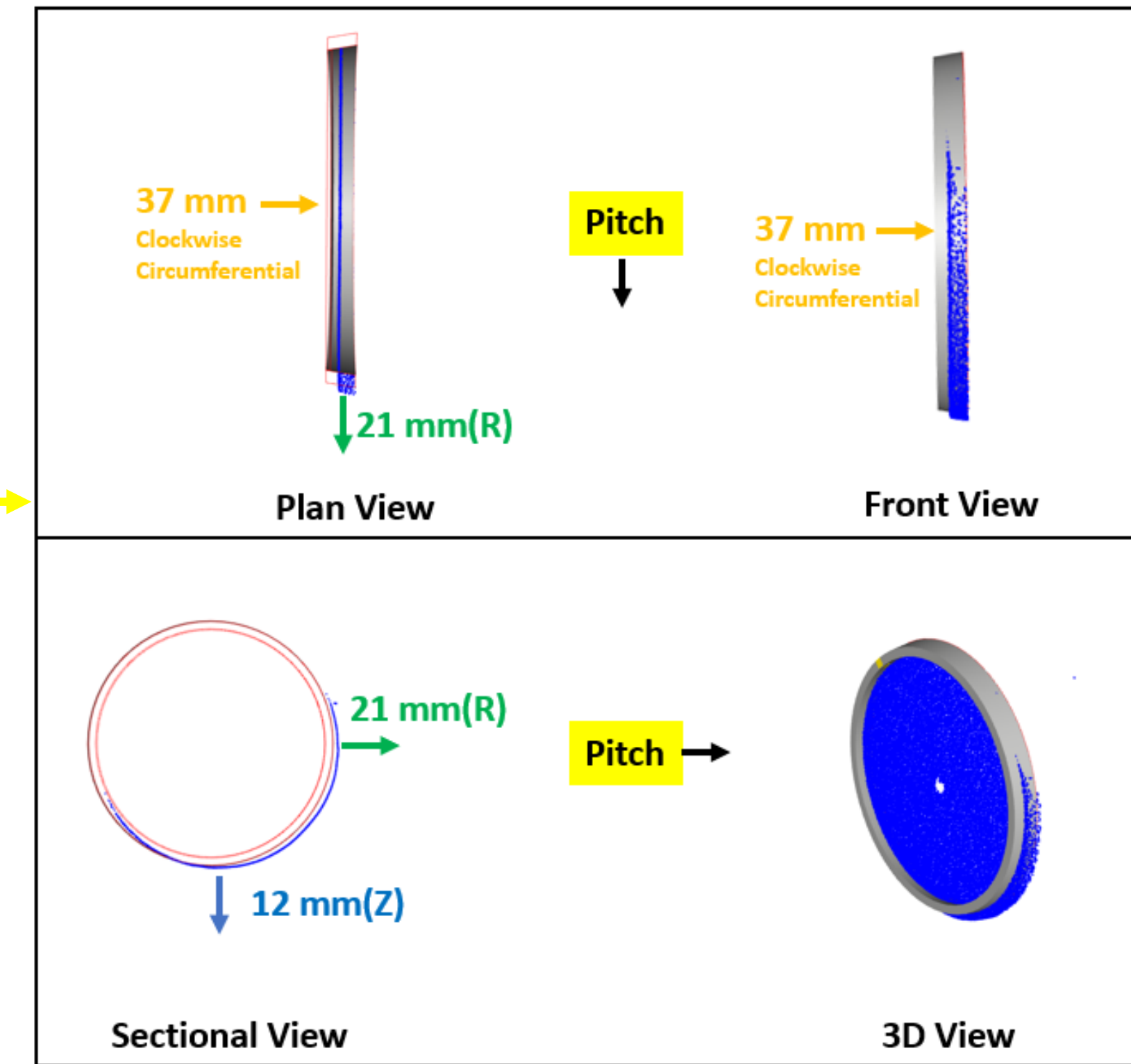
Deviation Analysis of Installed Compression Ring



Closer Section



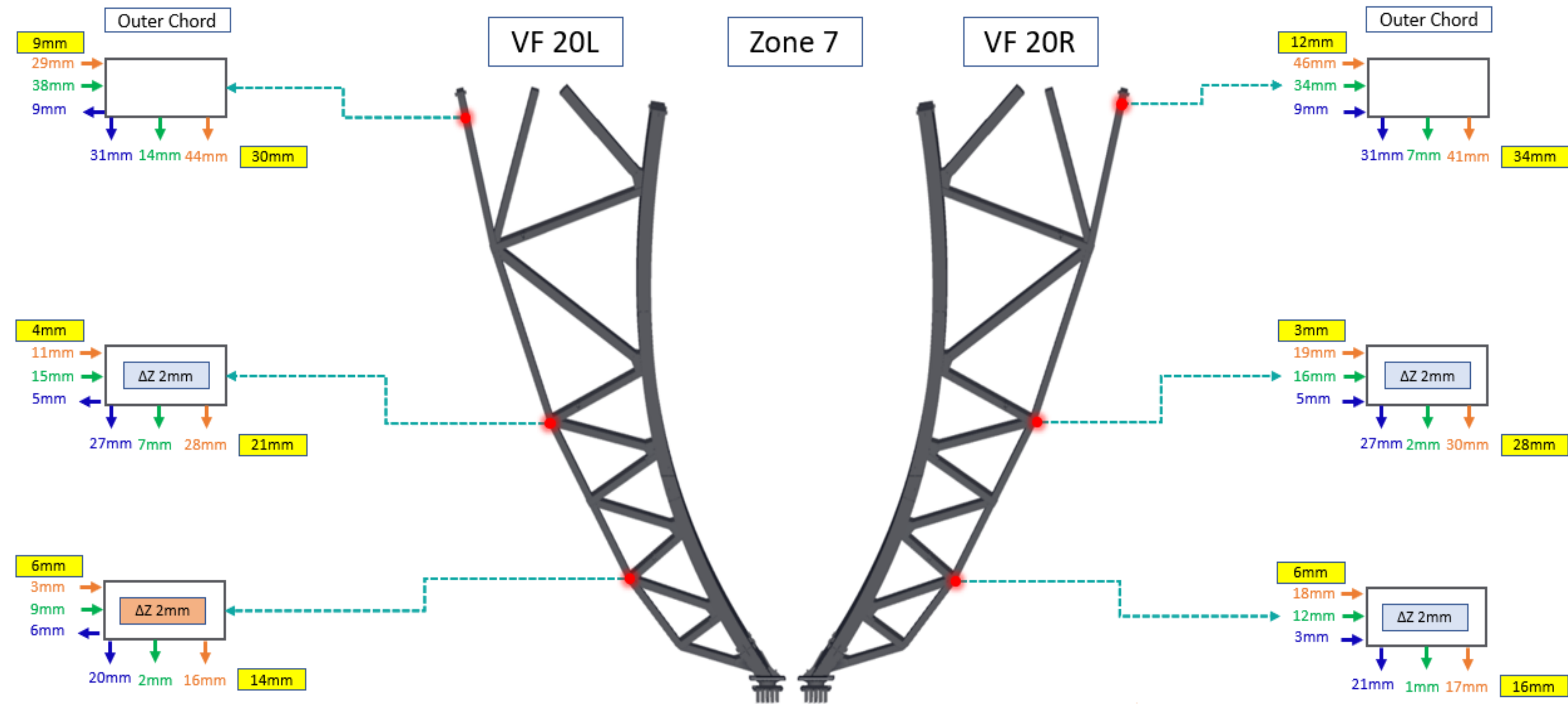
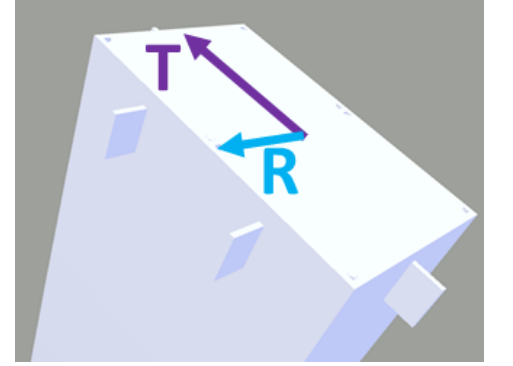
Point Cloud



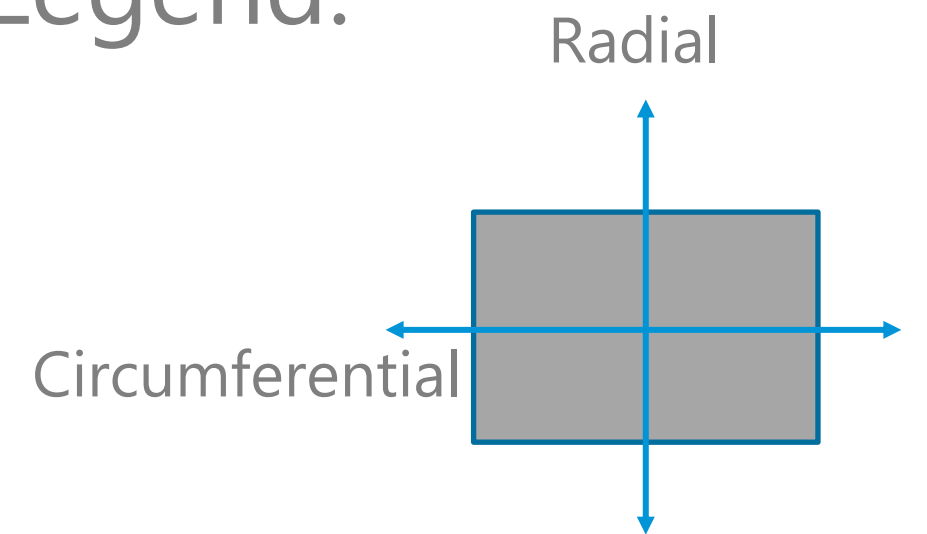
Deviation Analysis



Laser Scanning for Long Span Structures



Legend:



- IFC Vs As-Built Before De-Propping
- IFC Vs As-Built After De-Propping
- Theoretical displacement (IFC Vs Support Unload Model)
- Actual Displacement (Difference b/w As-Built Before & After De-Propping)

Conclusions – 1. Difference between theoretical(■) and actual(■) displacement is less than 10mm which helps contractor to validate the de-propping process in allowable tolerance

2. Evaluation and validation of all assumptions made by designers against the de-propping of large steel structure



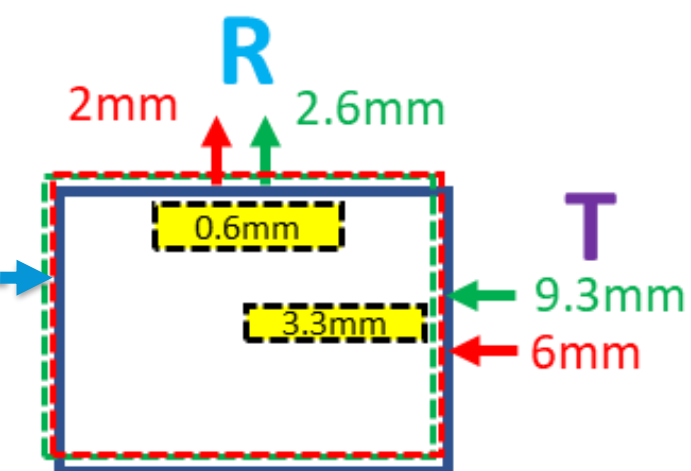
Reality Capture Reporting



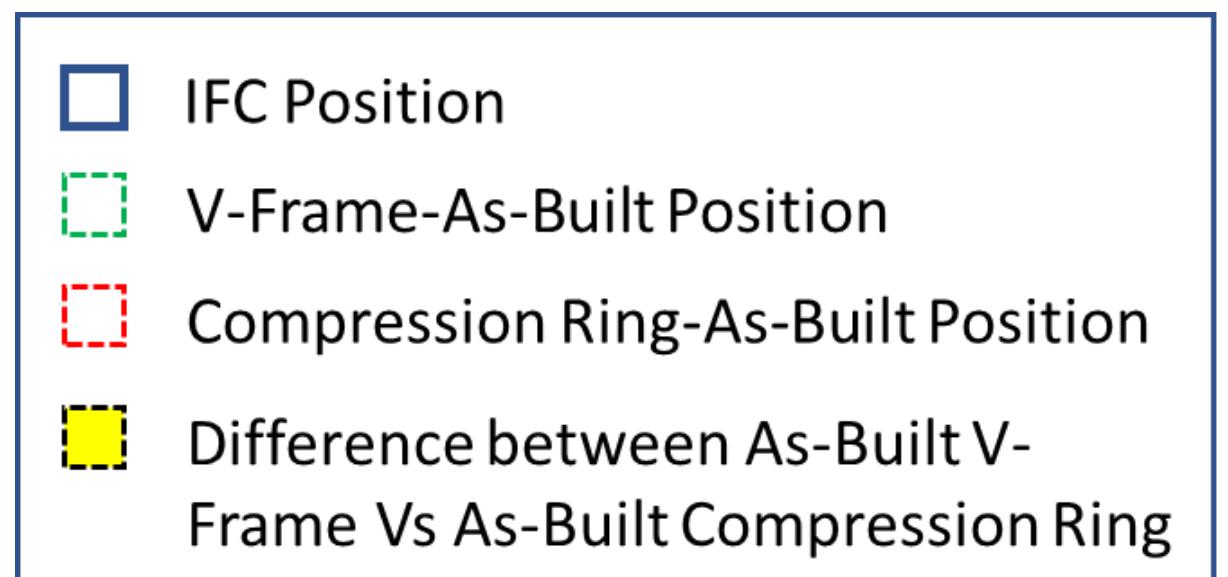
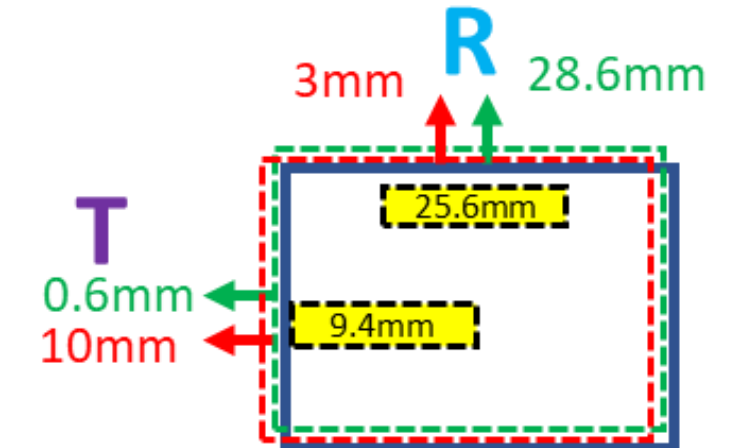
Tower 20



4R



5L



Fabrication

Trial
Assembly

Fit-up

Final
Assembly

Virtual
Erection

Final
Erection





Measuring quantity and maintaining the volume of stockpiles, cut & fill in heavy earthwork industries is difficult. Traditional survey methods are inaccurate and measure up to 80% of original volumes. Measuring a stockpile volume using 3D Laser Scanning is by far the fastest and safest method available.

Earthwork Management

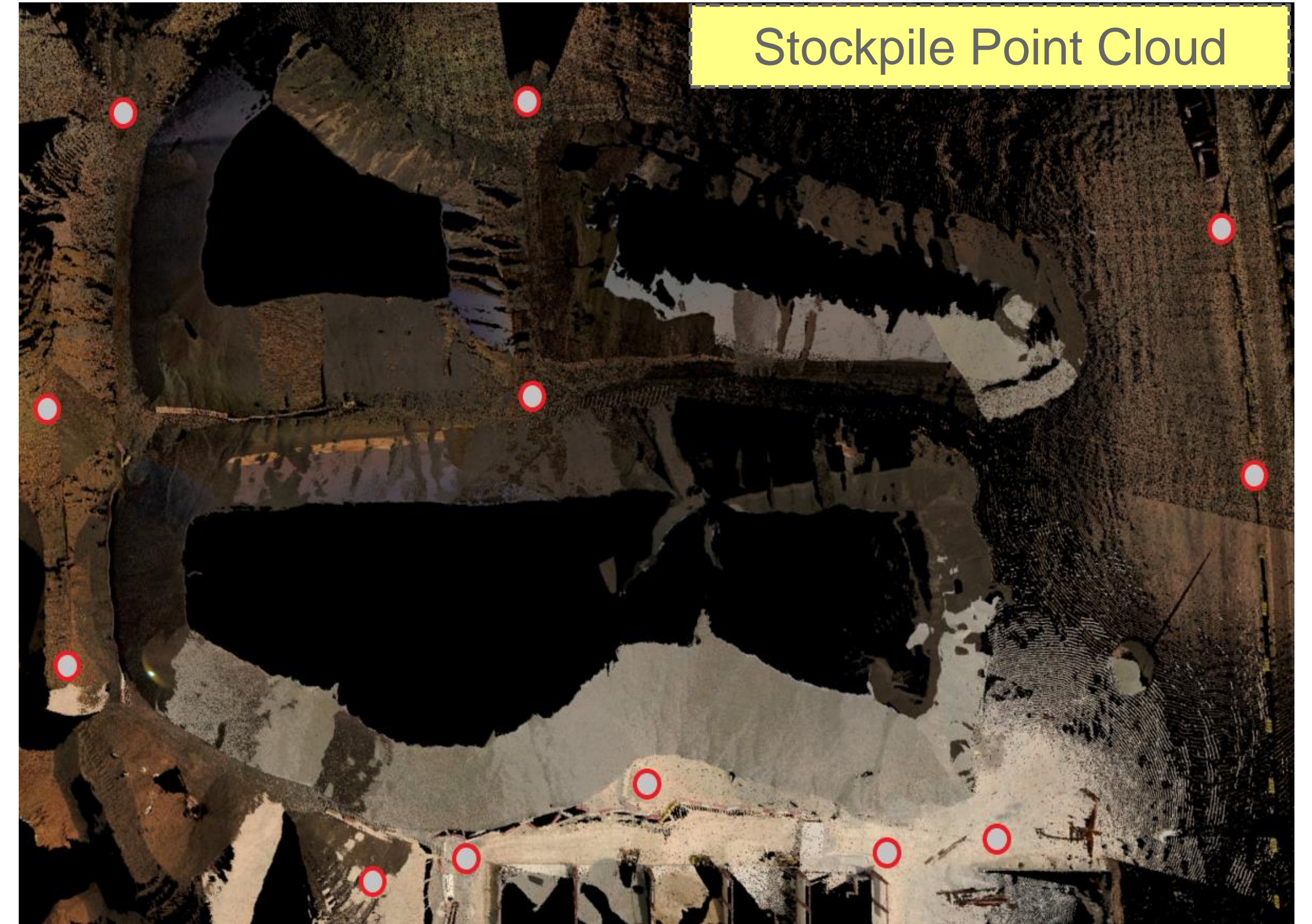
Stockpile Quantification & Management

○ Laser Scanner Location

Laser Scanning on Stockpile



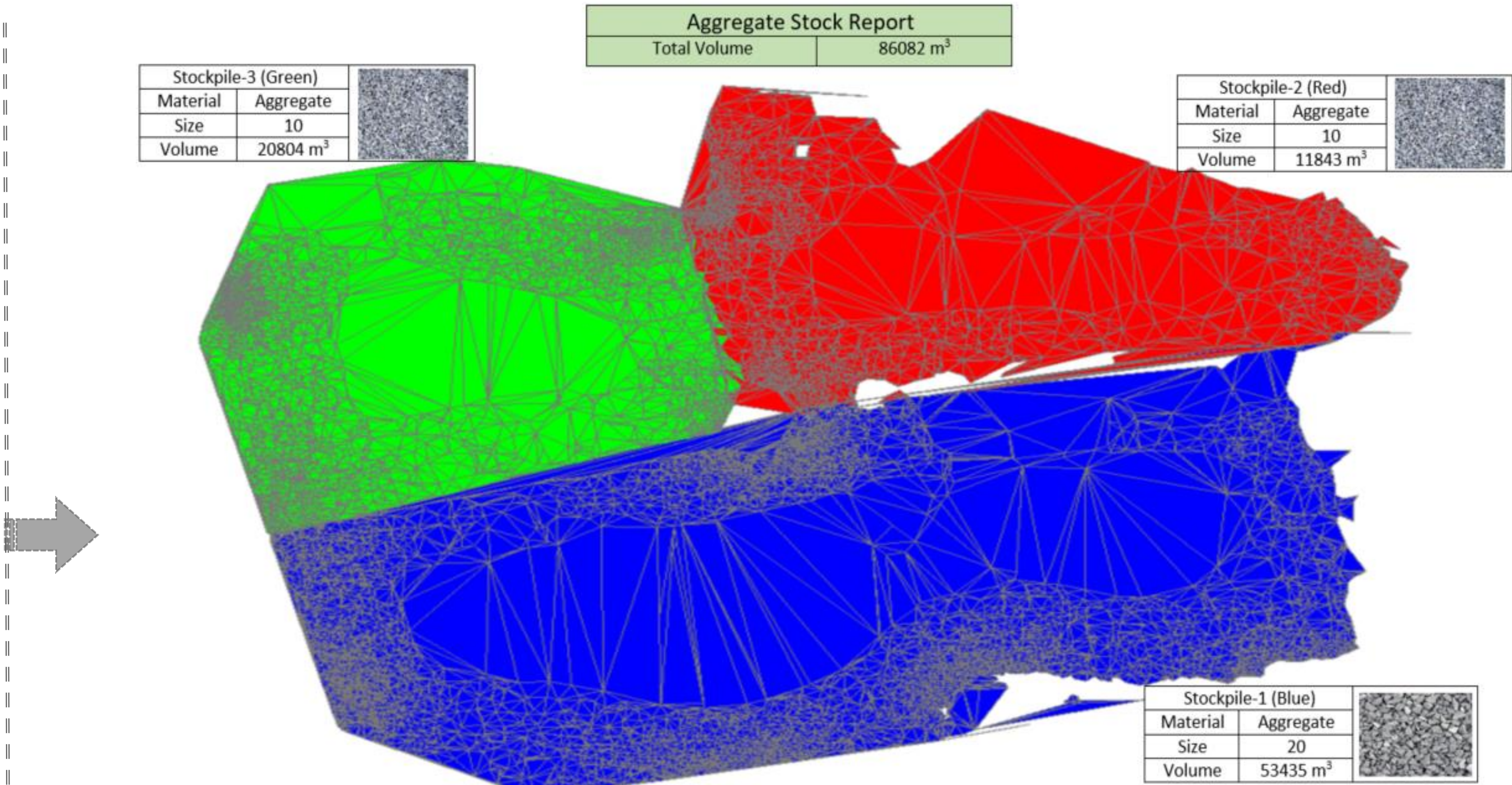
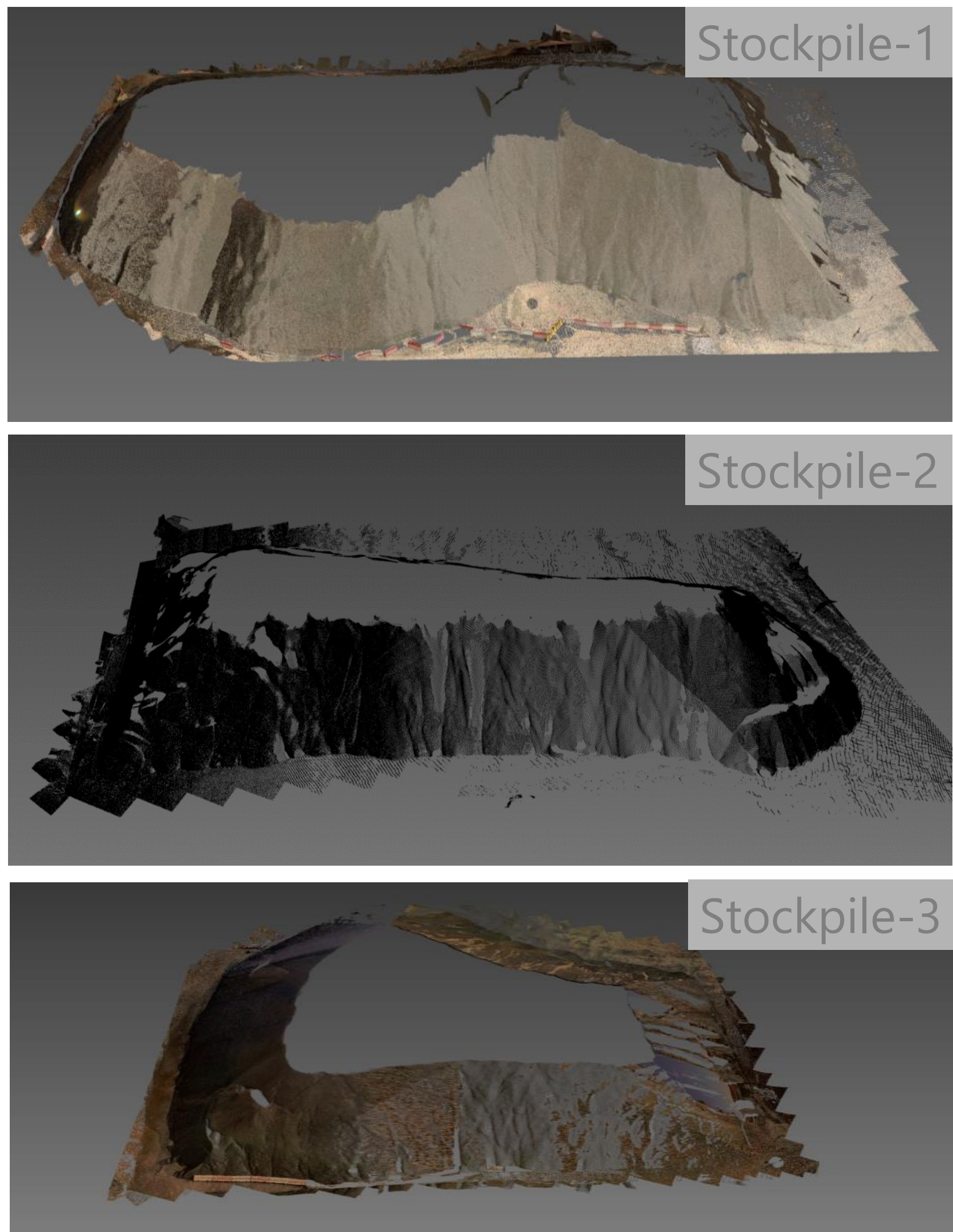
Stockpile Point Cloud



- ❑ General contractors quantify the stockpile material by triangulating point cloud data. Complex mesh elements resulted from the triangulation are used for computation of 3D volume elements of various bulk materials



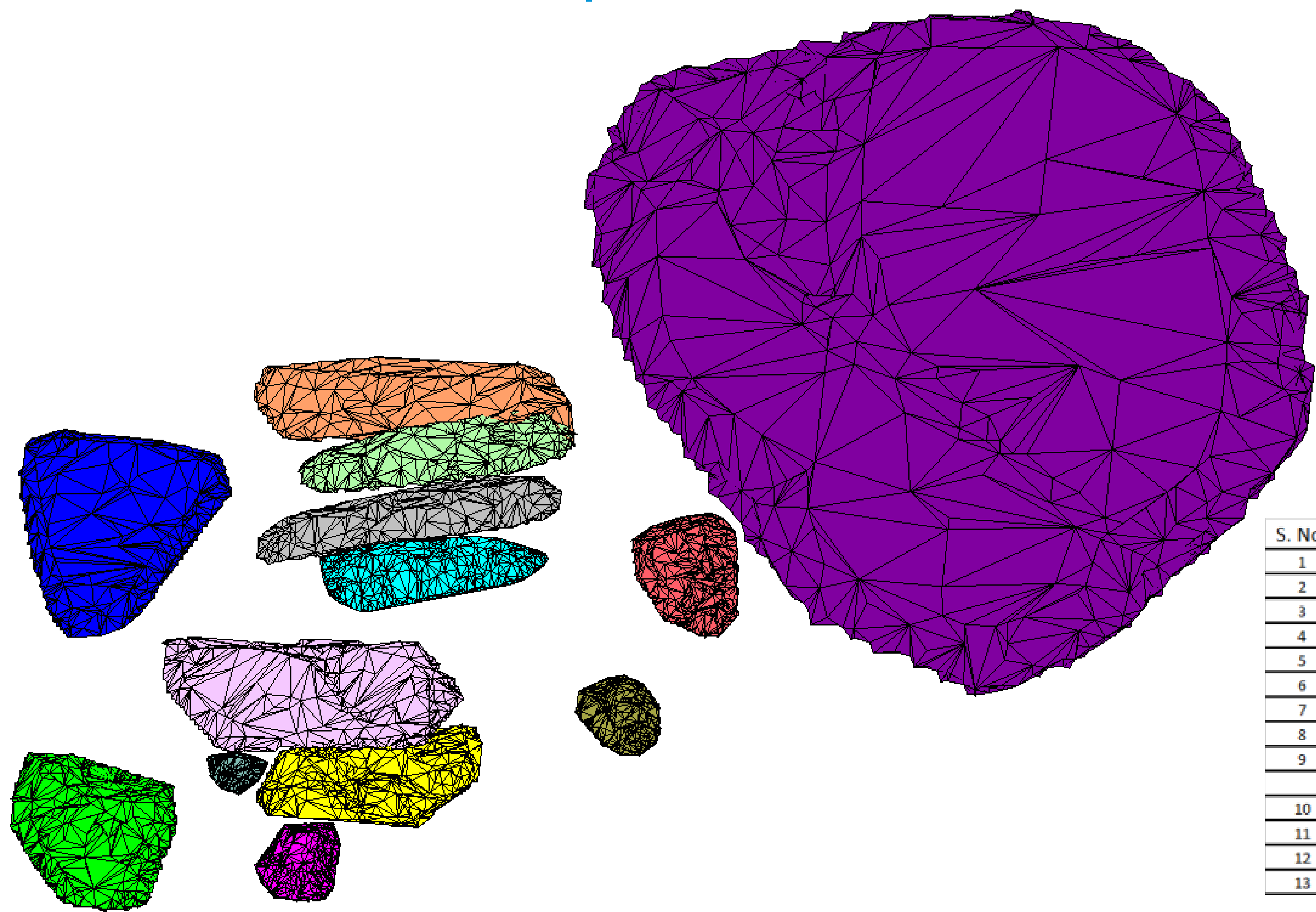
Stockpile Quantification & Management



	Actual	Total Station	Laser Scanning
Total Volume	86700 m ³	93500 m ³	86082 m ³
Percentage Error	-	8%	0.07%



Stockpile Quantification & Management

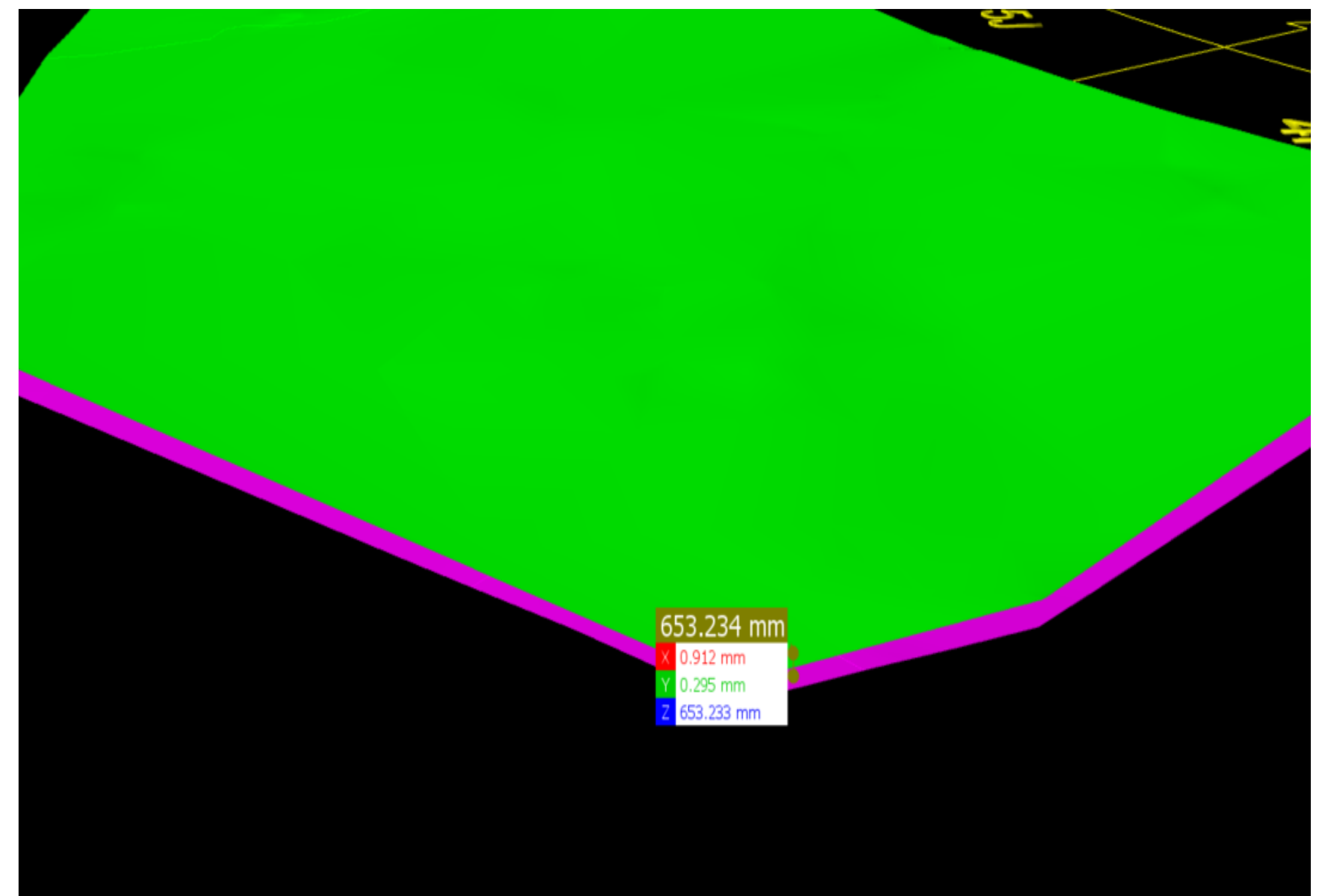
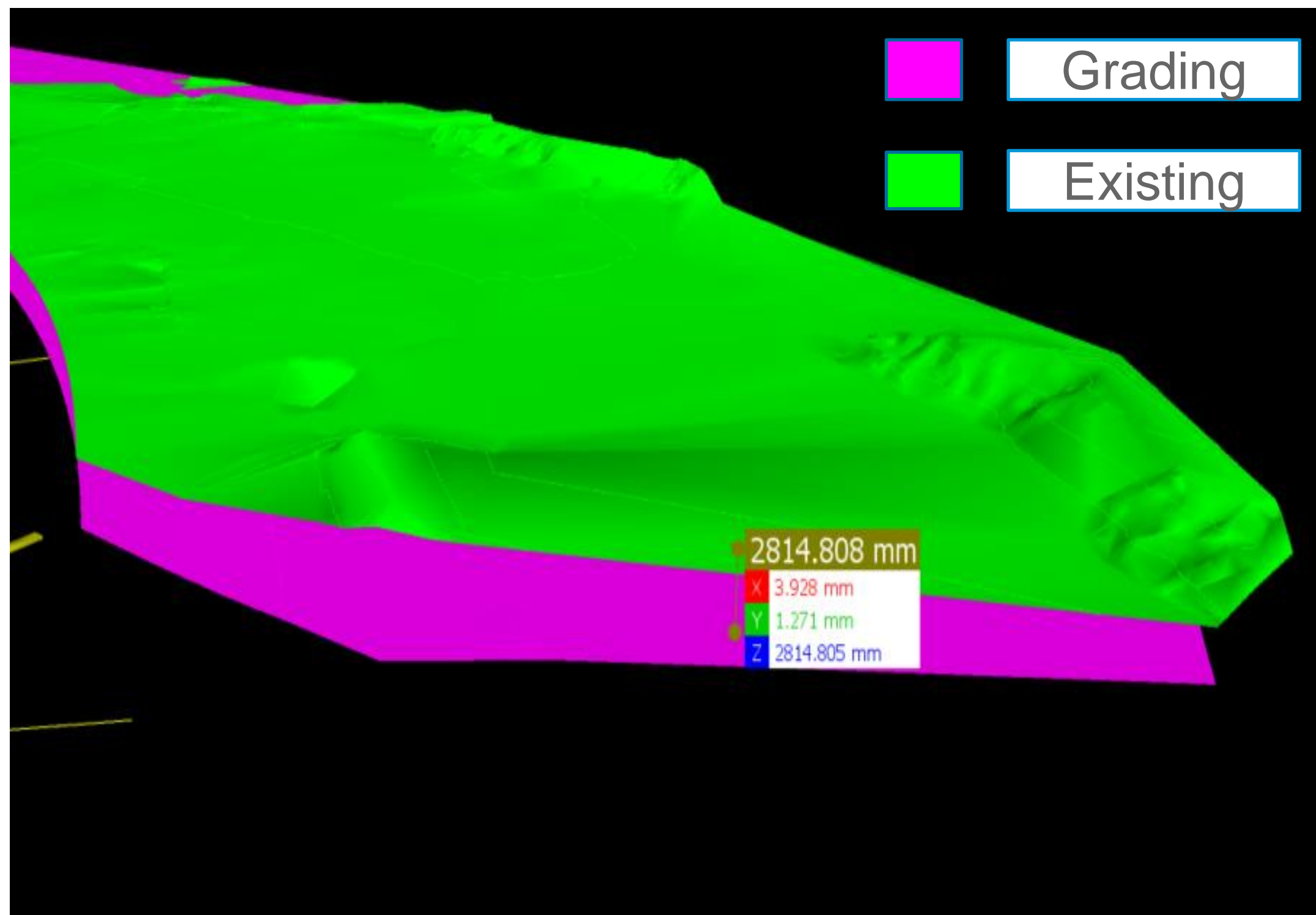


S. No.	Stockpile Name	Volume(Cubic Meter)	Colour Code
1	Dune sand	2835.00	
2	Screen matls1	6101.00	
3	Screen matls2	1058.00	
4	Stone1	2365.00	
5	Stone2	2512.00	
6	Stone3	6100.00	
7	Stone4	1118.00	
8	Unscreen matls(Excavation Mate1	221155.00	
9	Unscreen matls(Excavation Mate2	4984.00	
10	B.fill matl.1	2061.00	
11	B.fill matl.2	810.00	
12	Stone5	2011.00	
13	Stone6	136.00	

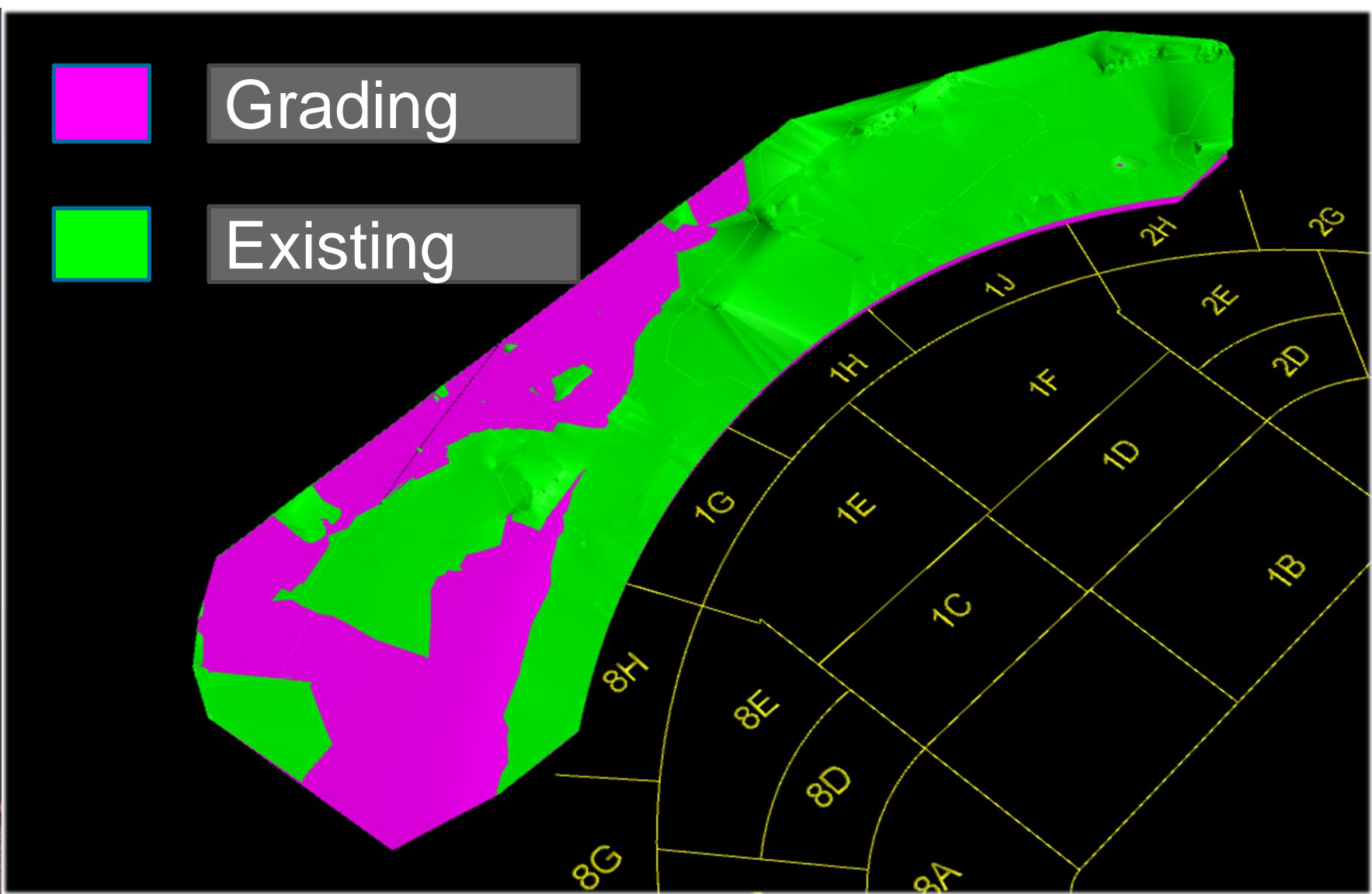
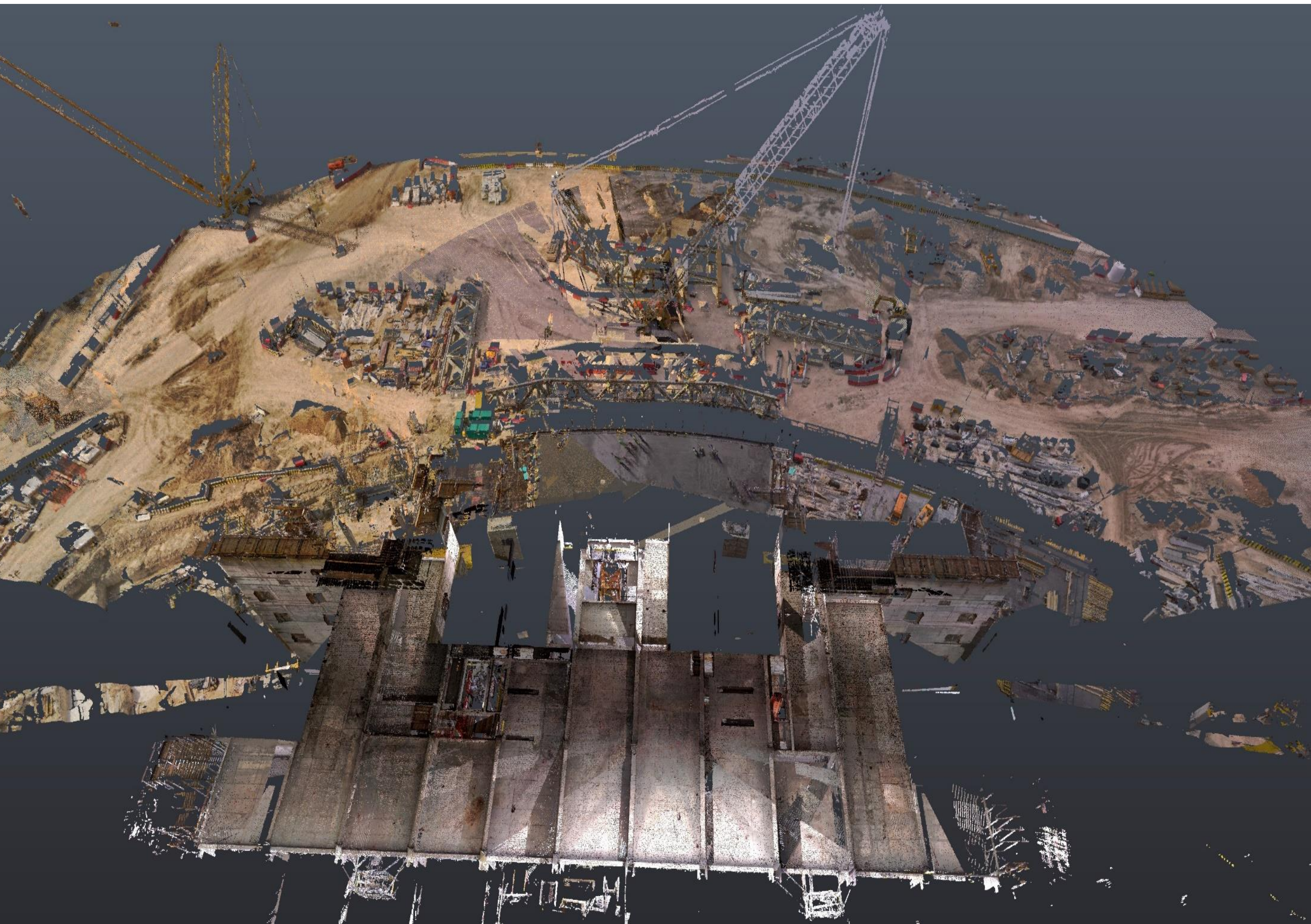


Cut & Fill Quantification

- ❖ The projection of topo surfaces of Grading vs. Existing gives variable height factor between these two surfaces. This variable height helps software to calculate net cut and fill quantities between existing and grading surfaces.



Calculation of Net Cut\Fill

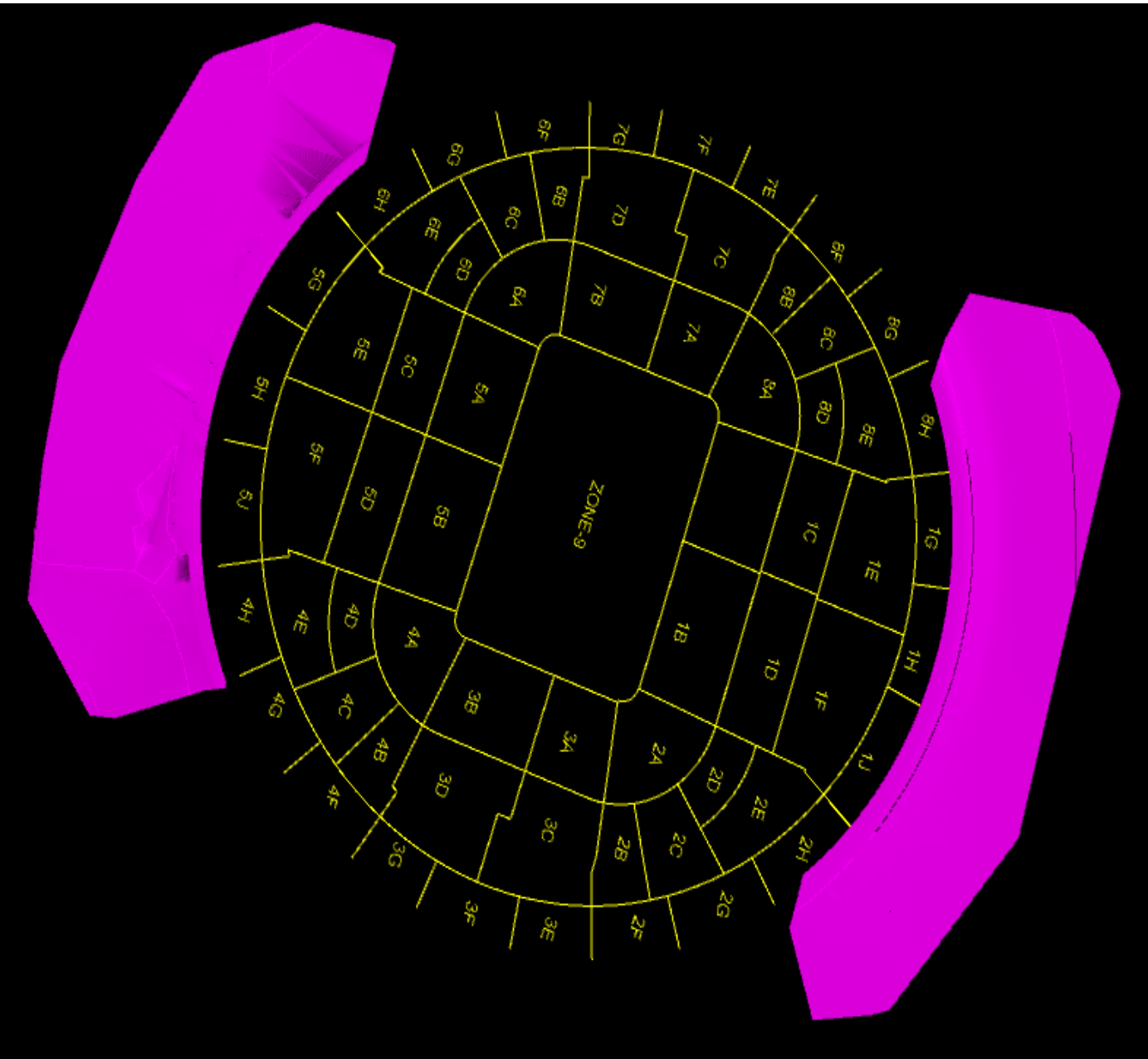


Zone- 1 Projected and Surface Area

Location	Projected Area	Surface Area	Phase
Z1	8862.05 m ²	8972.10 m ²	Existing
Z1	8836.13 m ²	8839.75 m ²	Grading

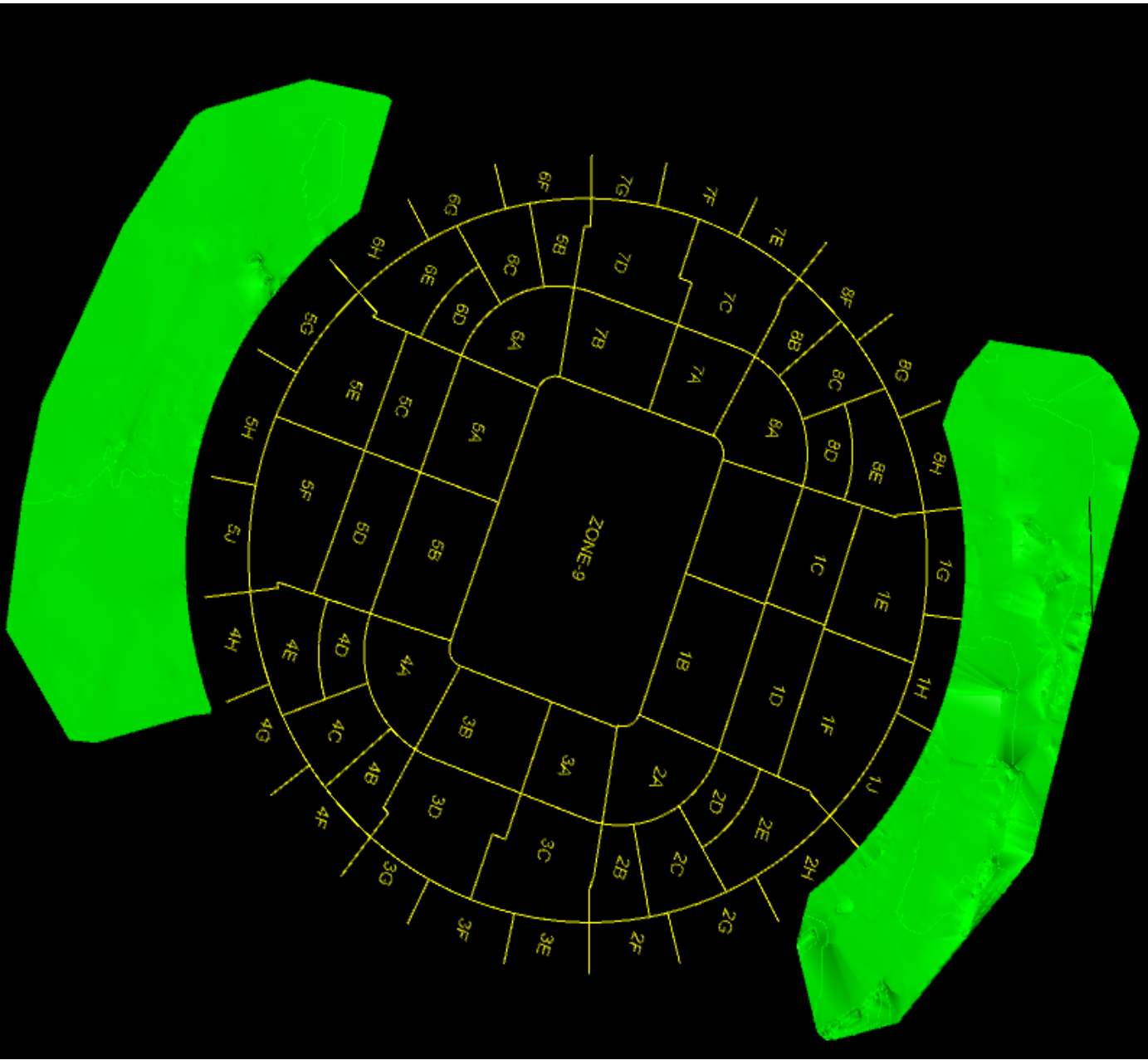
Zone- 1 Net Cut\Fill

Location	Cut	Fill	Net Cut
Z1	6820.78 m ³	438.74 m ³	6382.05 m ³



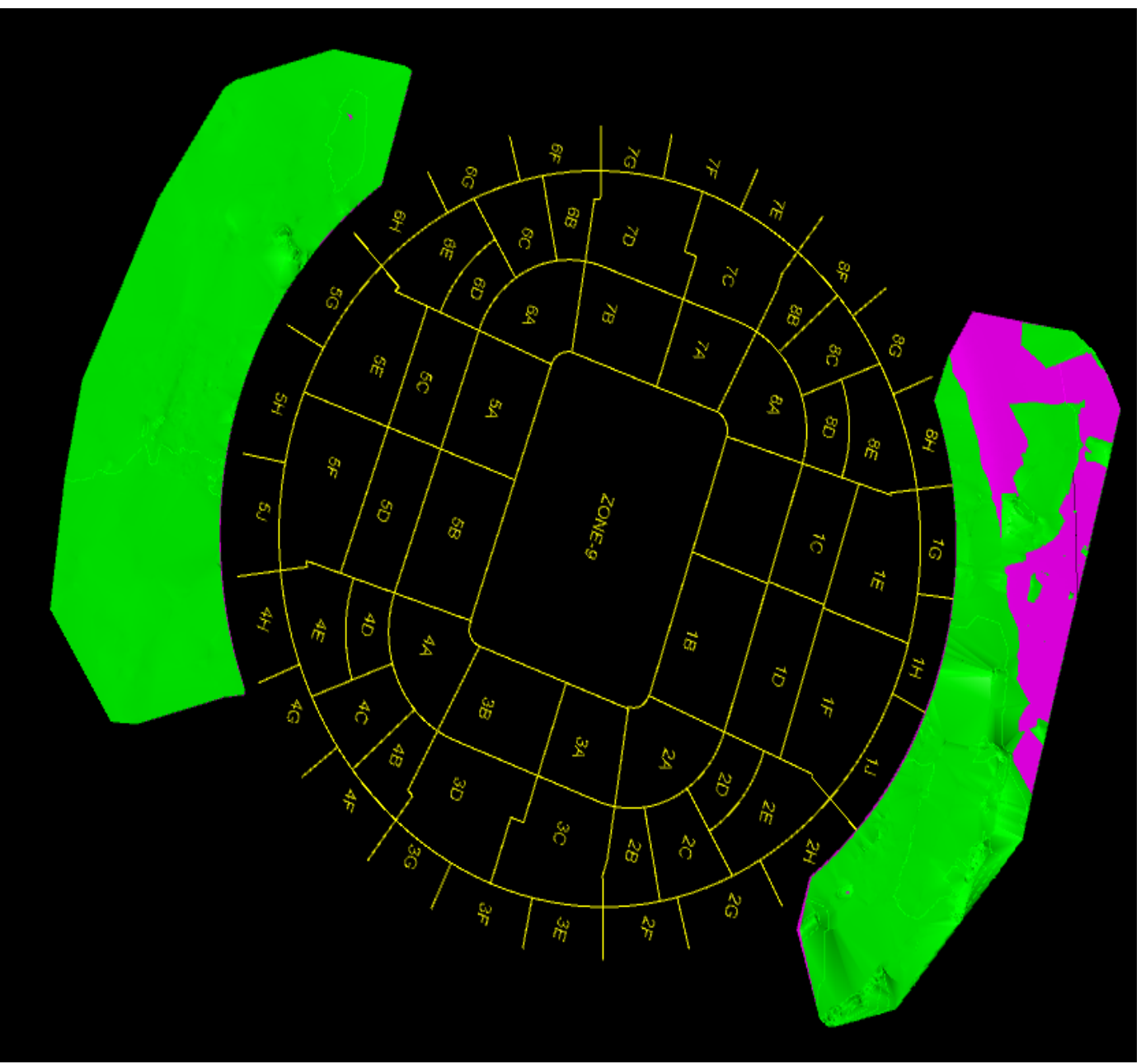
Grading Plan
As Designed

Projected Area	Surface Area
33502.70 m²	33701.60 m²



Existing Plan
3D Laser Scanning

Projected Area	Surface Area
33470.93 m²	33488.25 m²



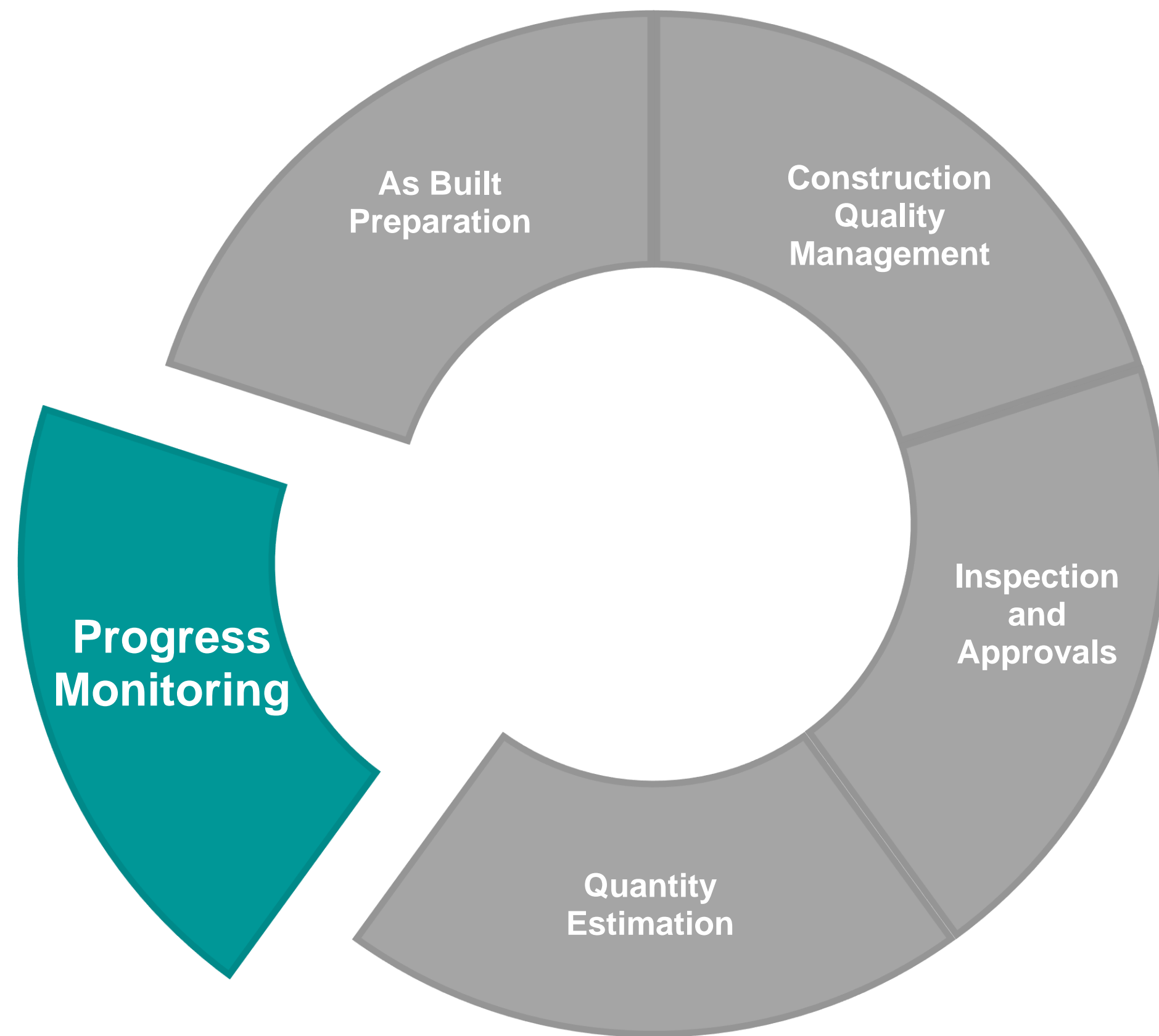
Overlay
Grading VS Existing

Cut	Fill	Net Cut
29878.08 m³	818.05 m³	29060.03 m³

Quantification & Management

Quantification	Traditional Method(Total Station)	3D Laser Scanning
Data Collection & Processing	Few points creates Less number of triangles	Millions of Points creates an exact surface from numerous triangles
Accuracy	90%	98-99%
Time	More working hours (A person need to hold the prism)	Less Efforts and Time (It's a non -contact method)
Cost	Due to more working hours the cost increases proportionally	Less cost and efforts due to less working hours
Safety	Need to climb on loose material that can cause safety hazards	Data can easily collected from distance



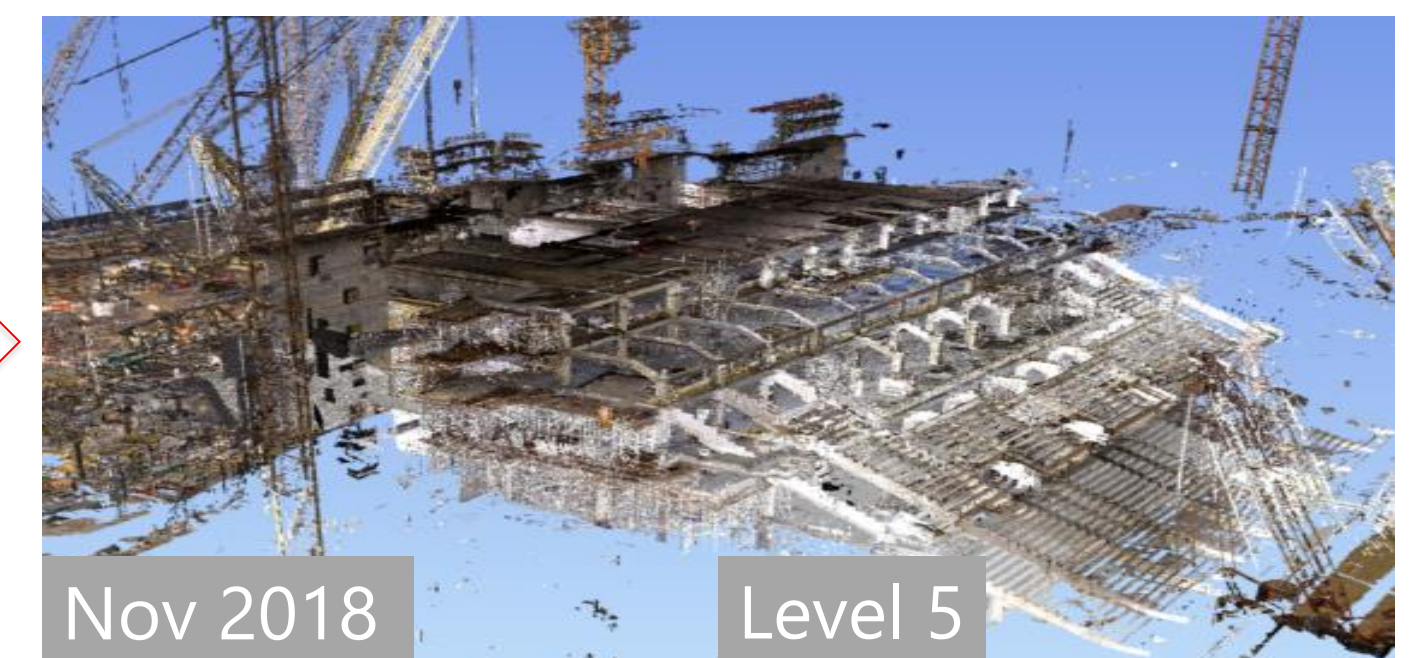
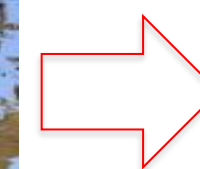
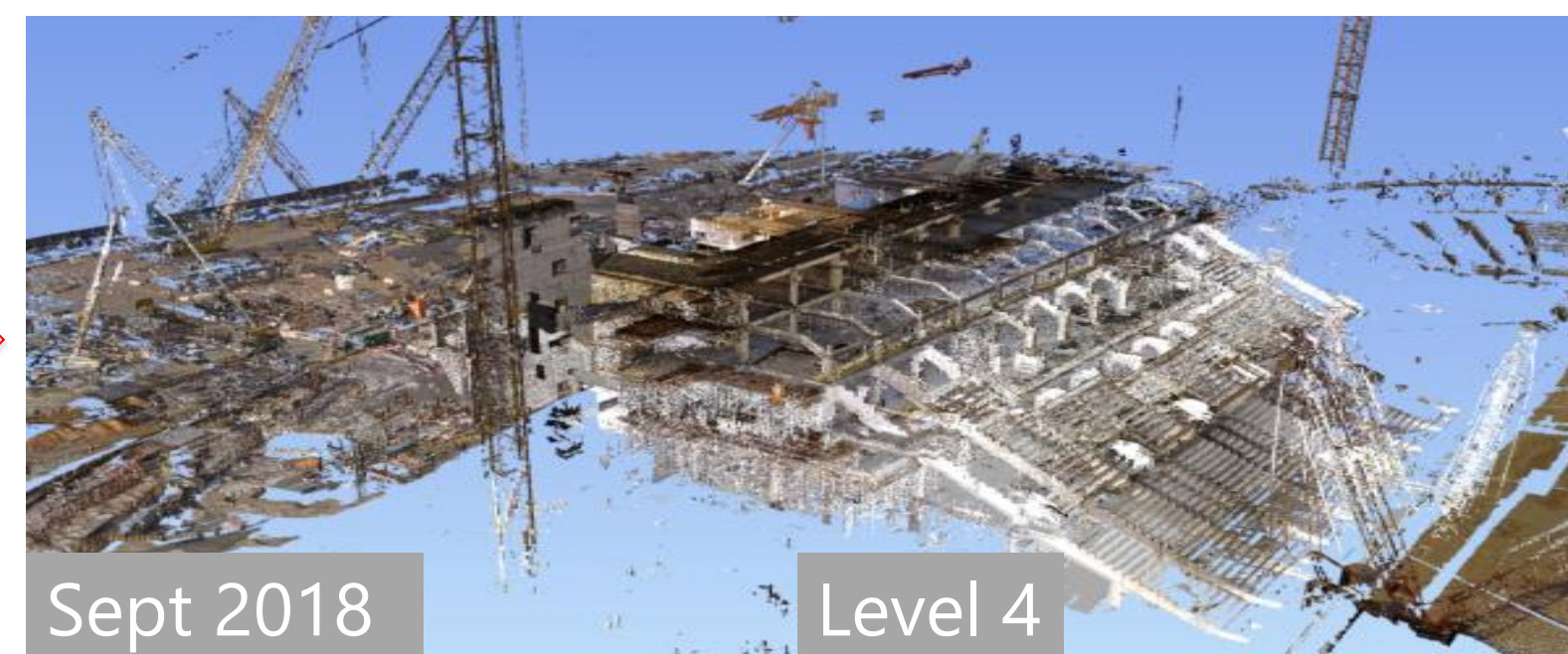
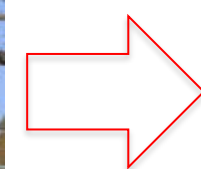
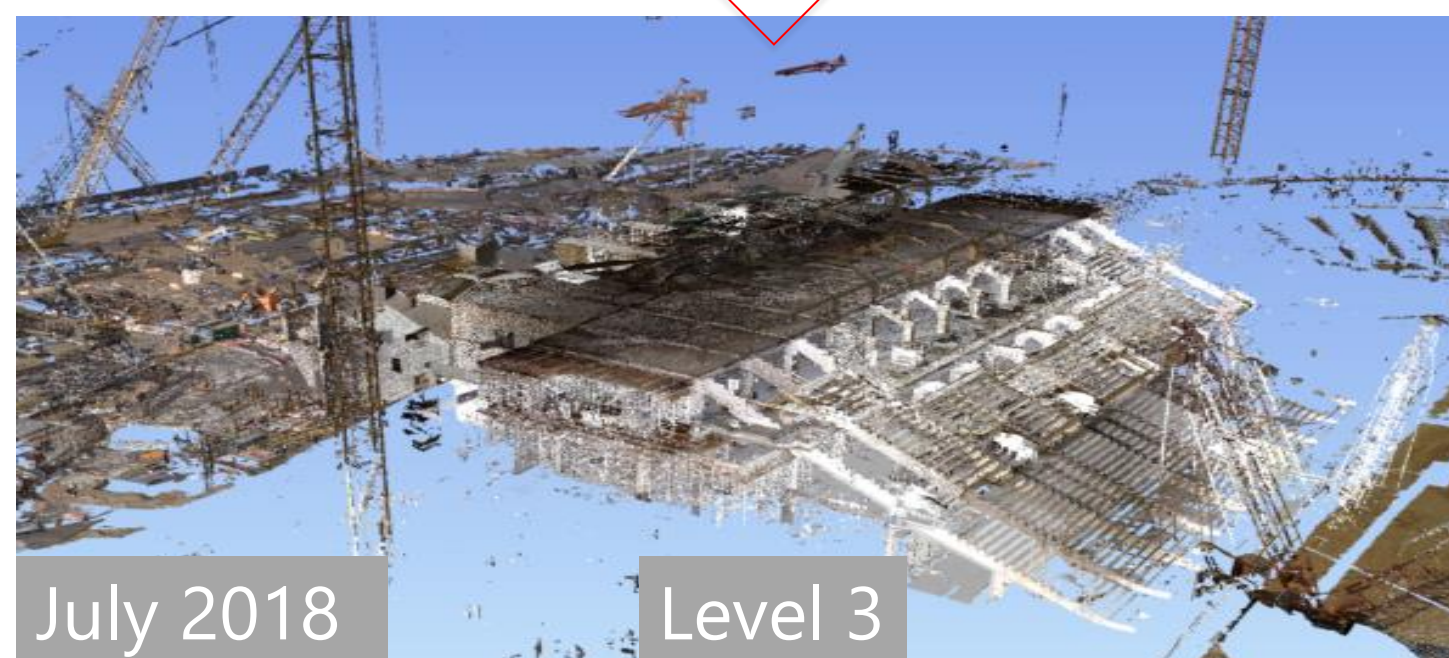
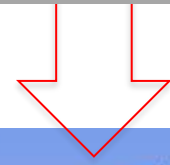
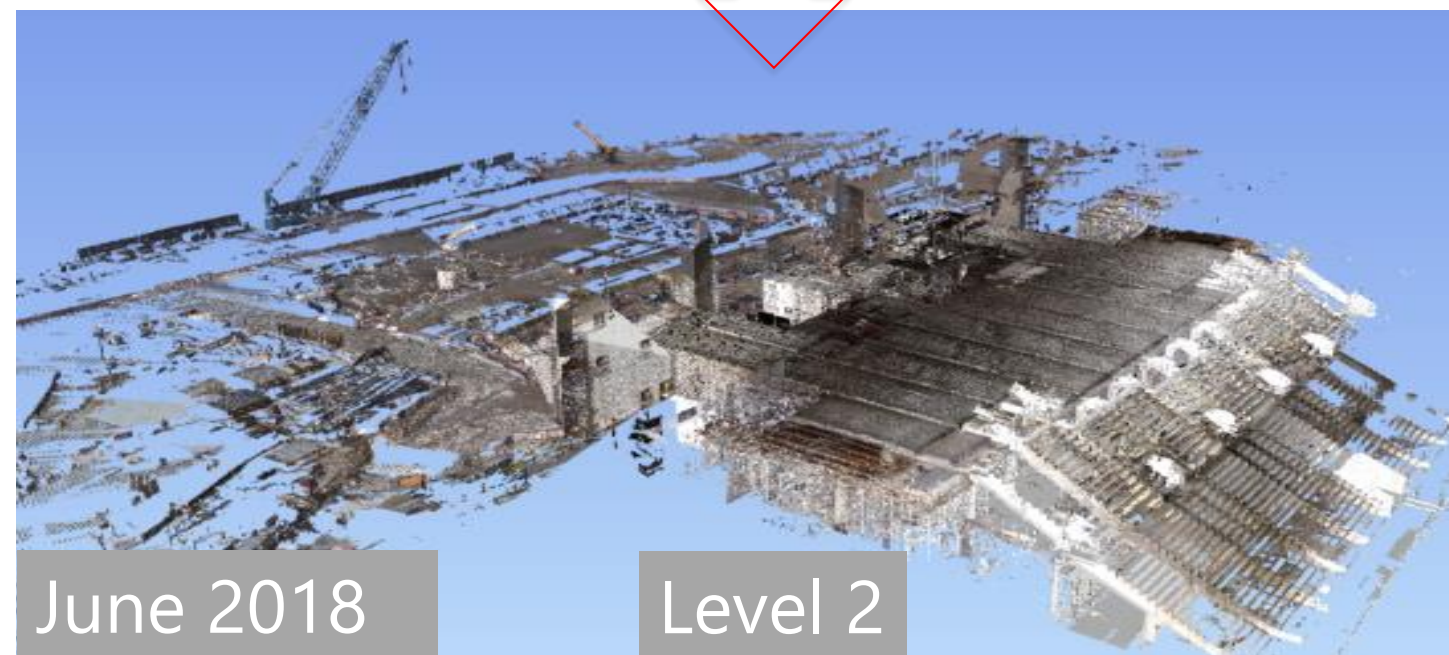
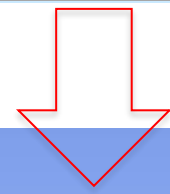
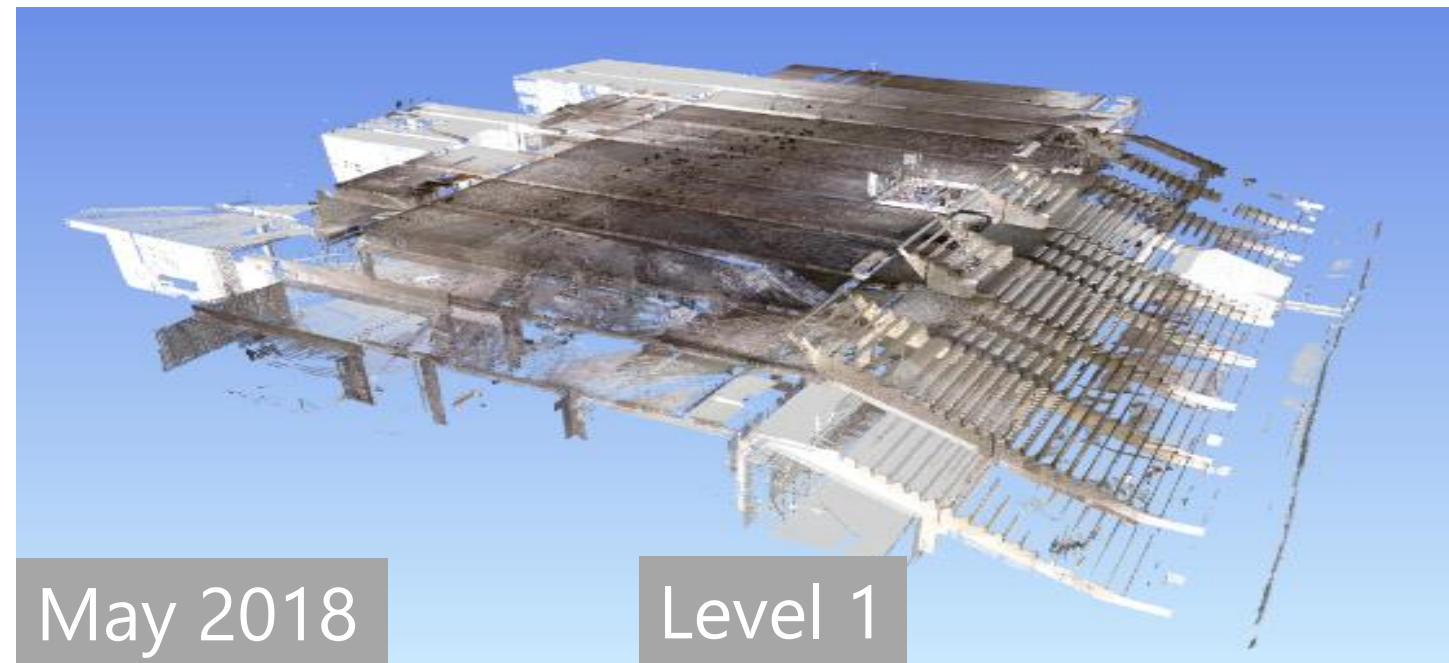


Creation of construction progress model on timely basis is now easier with laser scanning. It creates a point cloud of each element of site. The progress models from every span of time create a clear vision of construction headways.

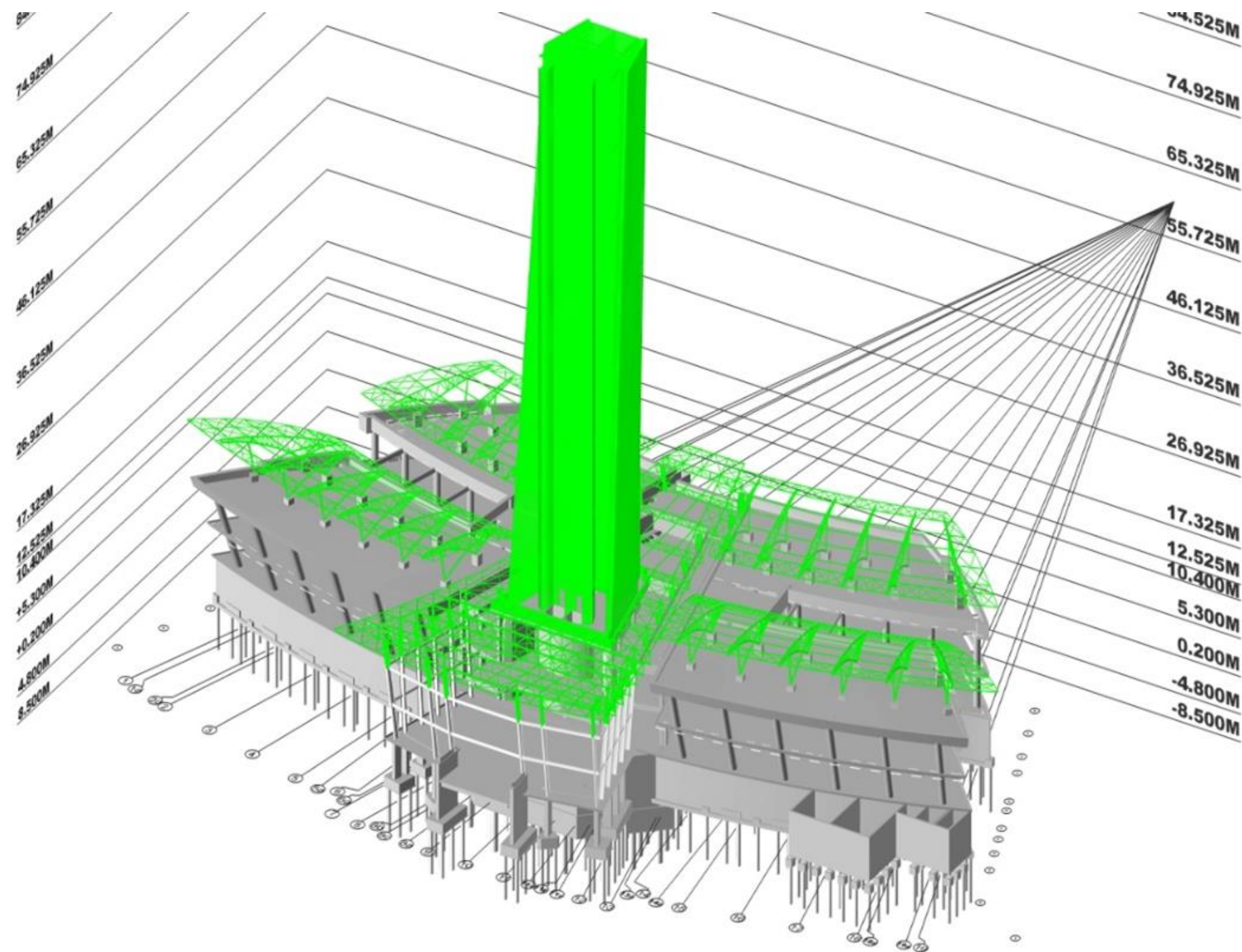


Progress Monitoring

Concrete Structure Monitoring - Planned v/s Actual

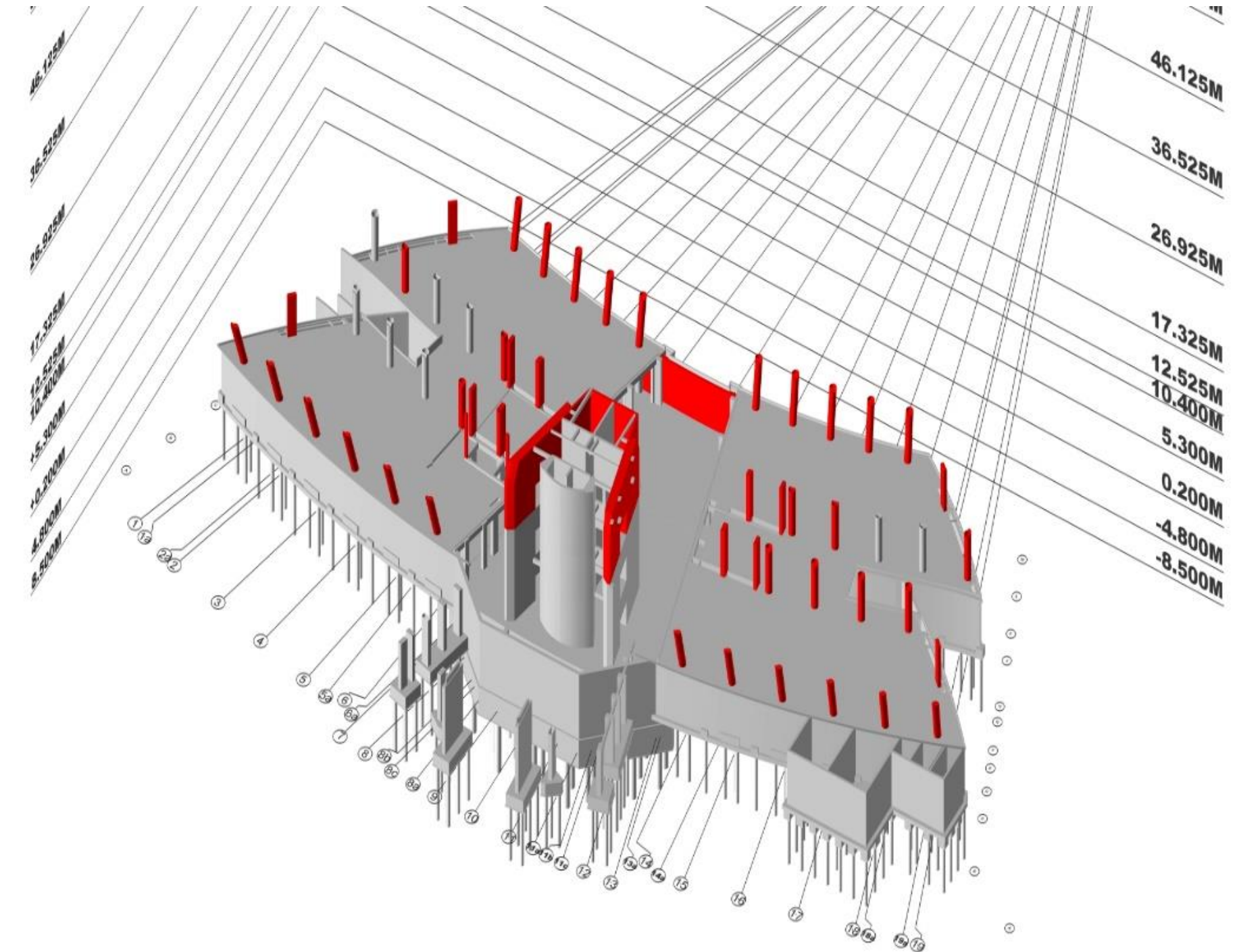


RCC Status – Planned v/s Actual on 12th Oct 2020



CCC Pile 100% Completed
CCC Raft & Pile cap 100% Completed
CCC Column & Retaining Wall 100% Completed
CCC Ground Floor Slab 100% Completed
CCC Ground Floor Lift Wall & Column 100% Completed
CCC Structural Steel Erection 72% Completed
ST Pile & Pile Cap 100% Completed
ST Shear Wall & Slab up-to LVL.106.4m 43% Completed

On Schedule	■	In progress Activity/Delay	■
Ahead of schedule	■	Completion of concreting	■



Actual Status

CCC Pile 100% Completed
CCC Raft & Pile cap 100% Completed
CCC Column & Retaining Wall 90% Completed
CCC Ground Floor Slab 70% Completed
CCC Ground Floor Lift Wall & Column 25% Completed
CCC Structural Steel Erection 0% Completed
ST Pile & Pile Cap 100% Completed
ST Shear Wall & Slab up-to LVL.12.525m Completed

Delay in Construction:38 Days

Progress Monitoring

Steel Structure Monitoring - Planned v/s actual

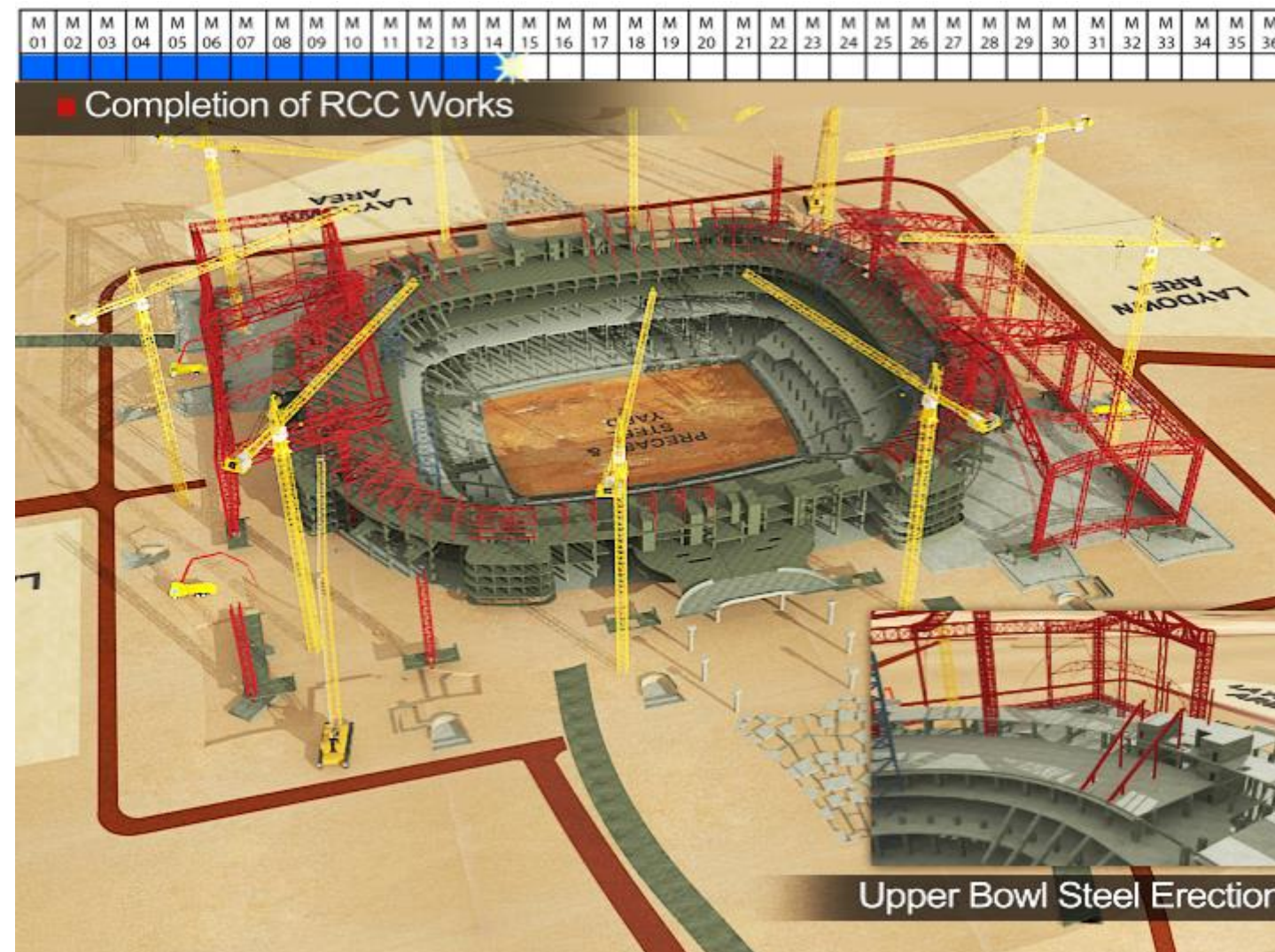
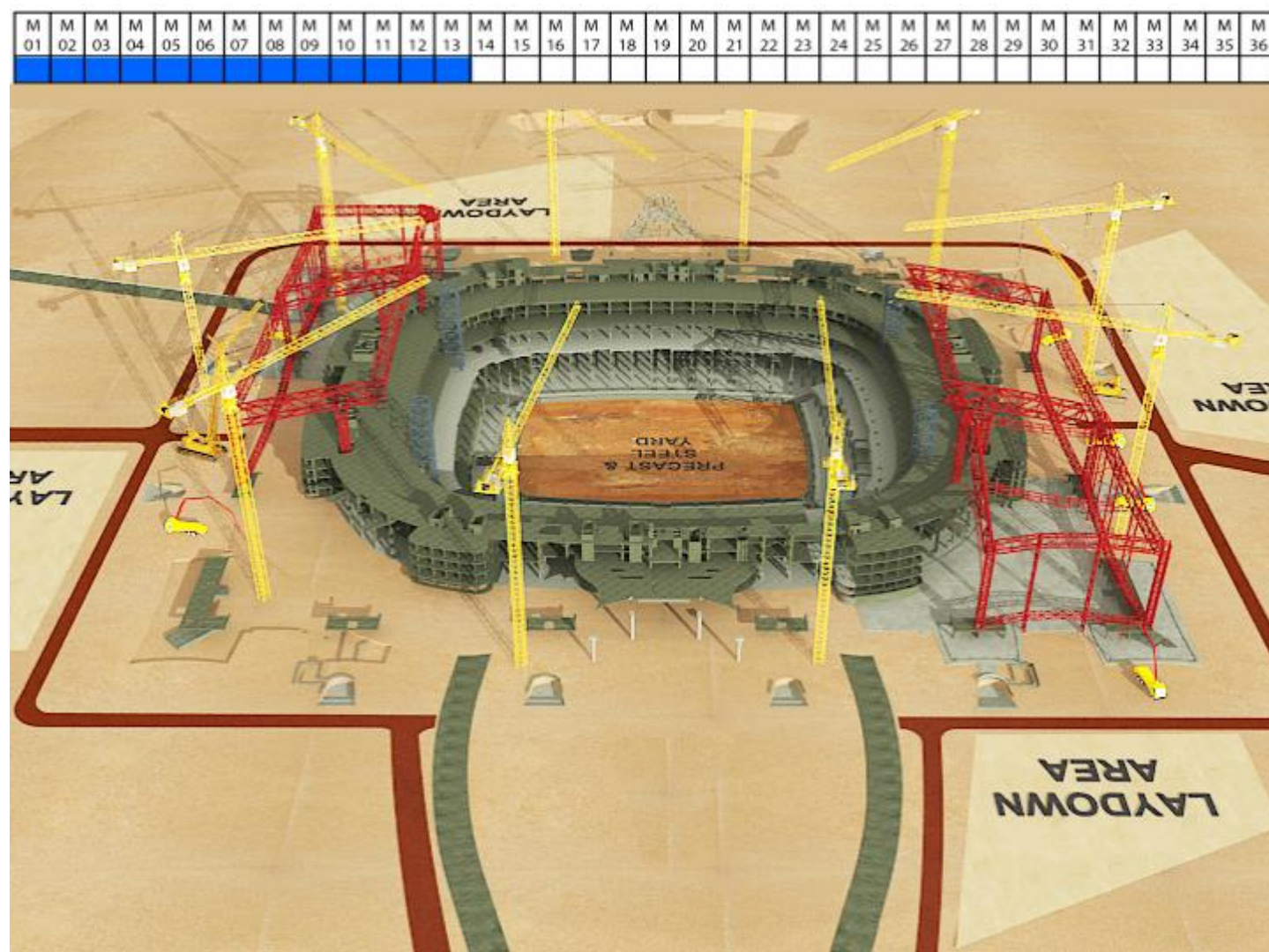
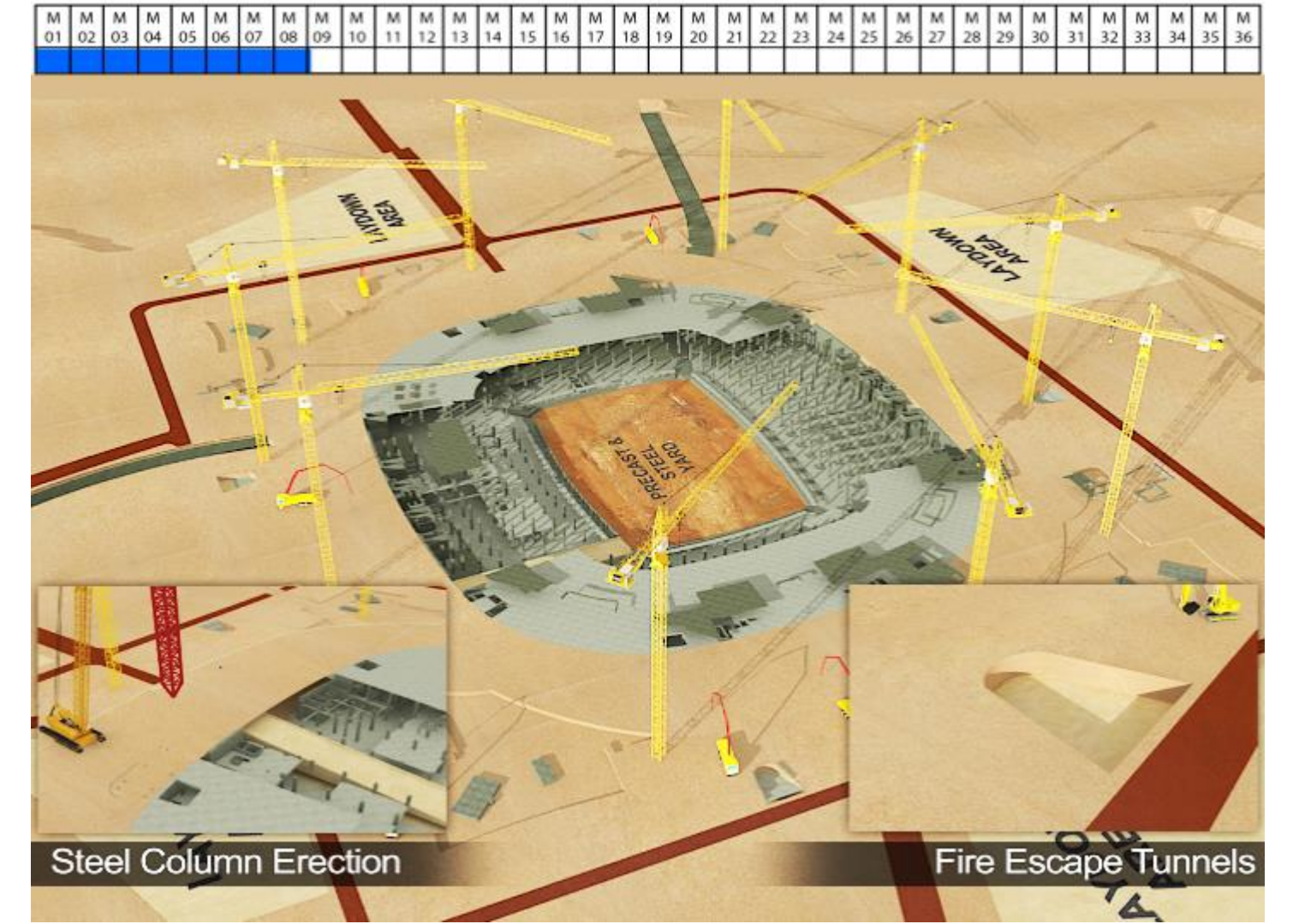
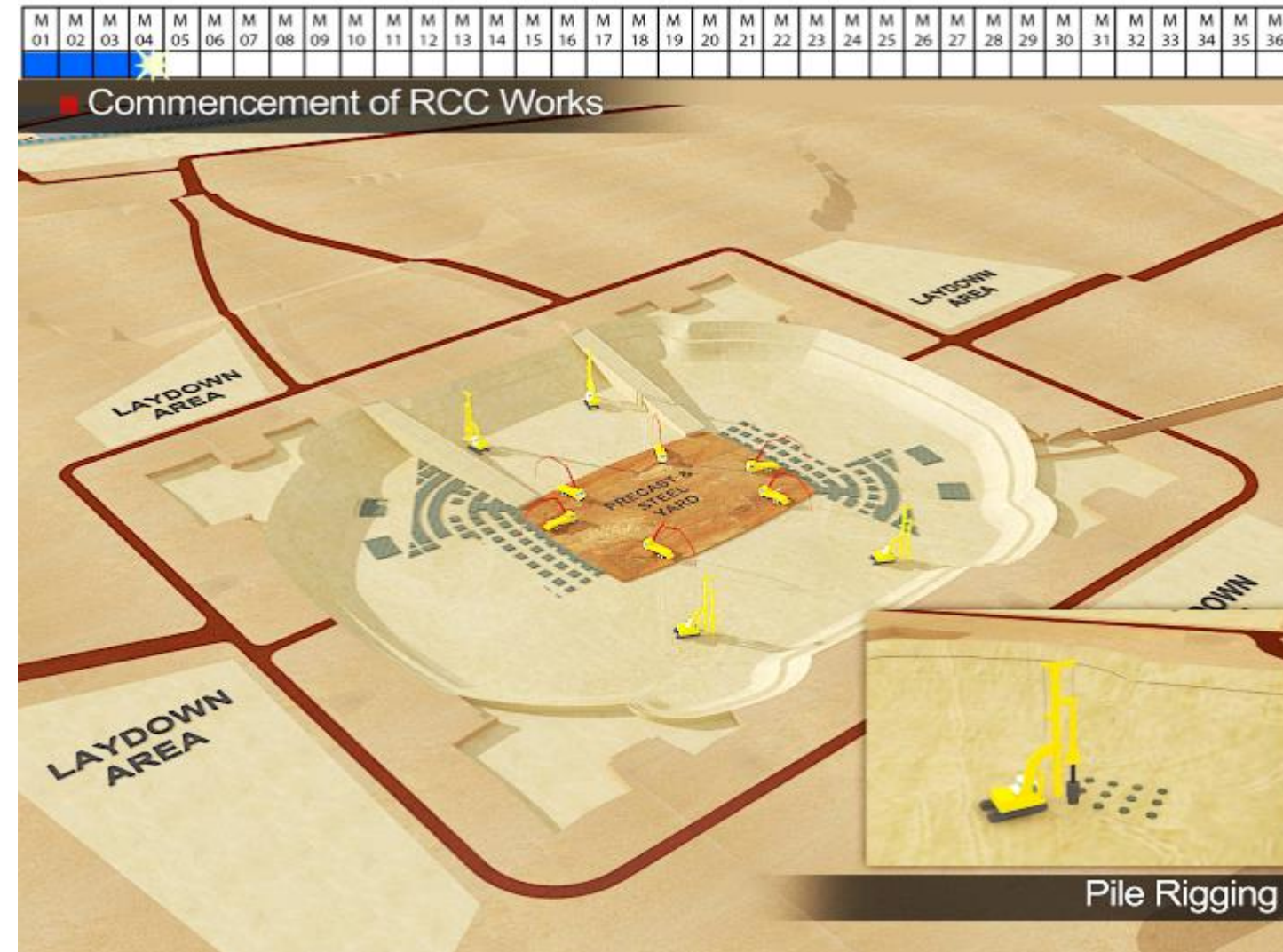


Progress Monitoring

Block Wall Monitoring



Progress Monitoring



Progress Monitoring

Concrete & Steel Structure Monitoring



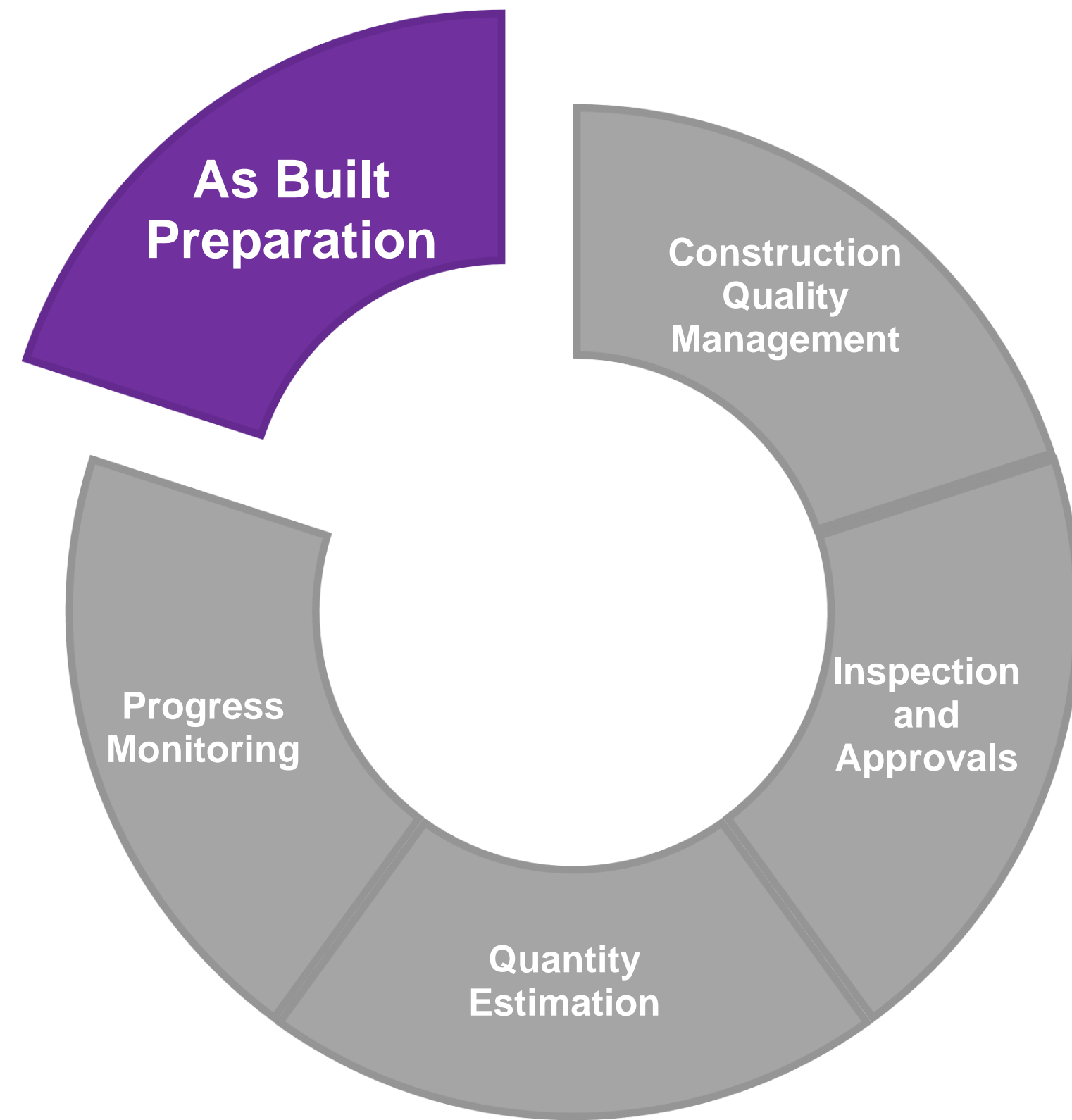
12th June 2019



18th August 2019

Site Physical Progress





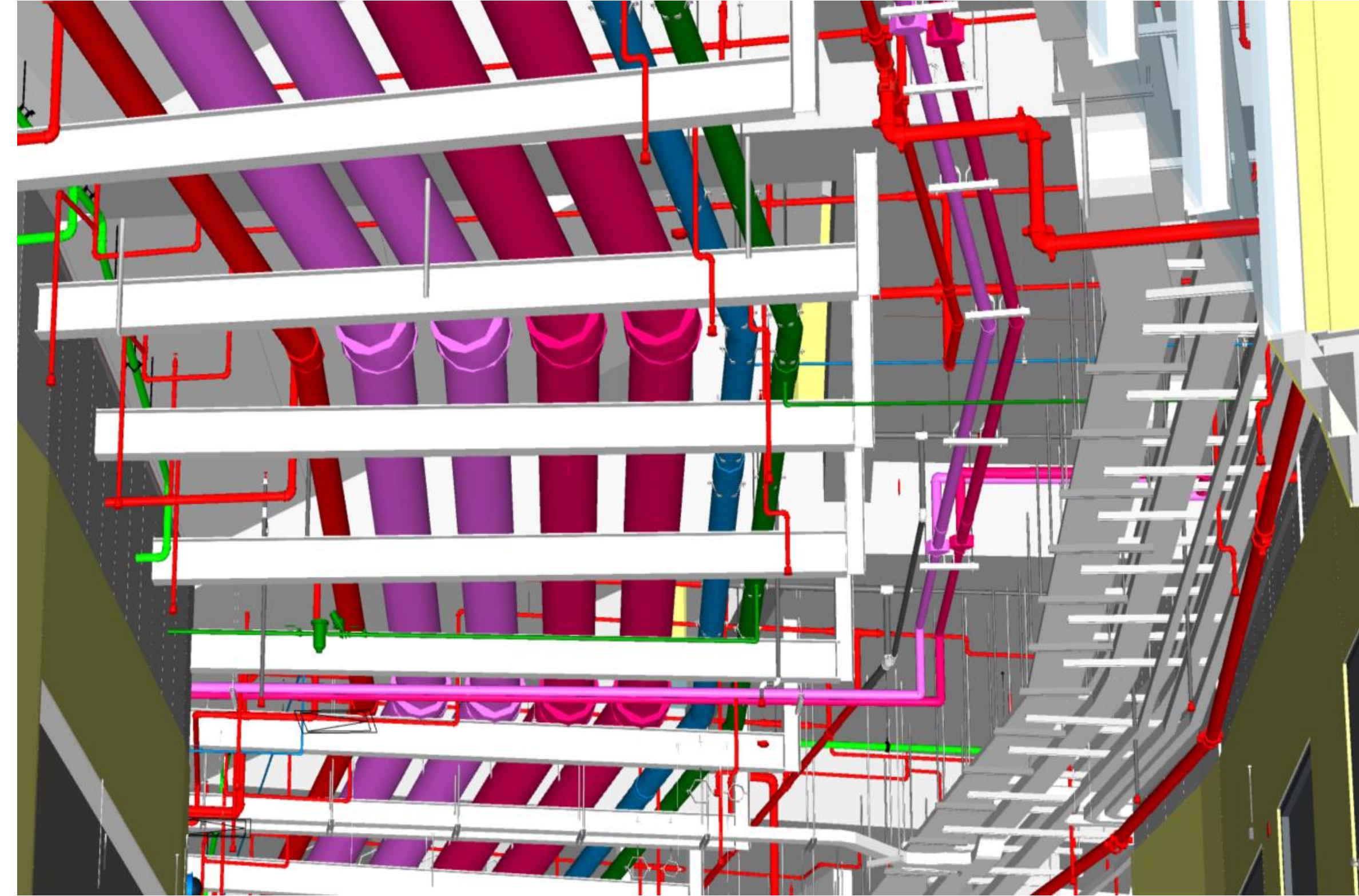
The practice of creating a digital representation of existing conditions of the building with its physical and functional characteristics in BIM.

The point cloud is imported into 3D BIM software (Autodesk's Revit) in order to create accurate as-built models.

As Built Preparation



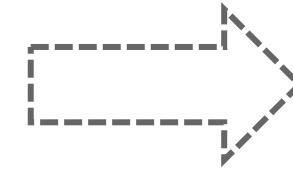
MEP Point Cloud Model



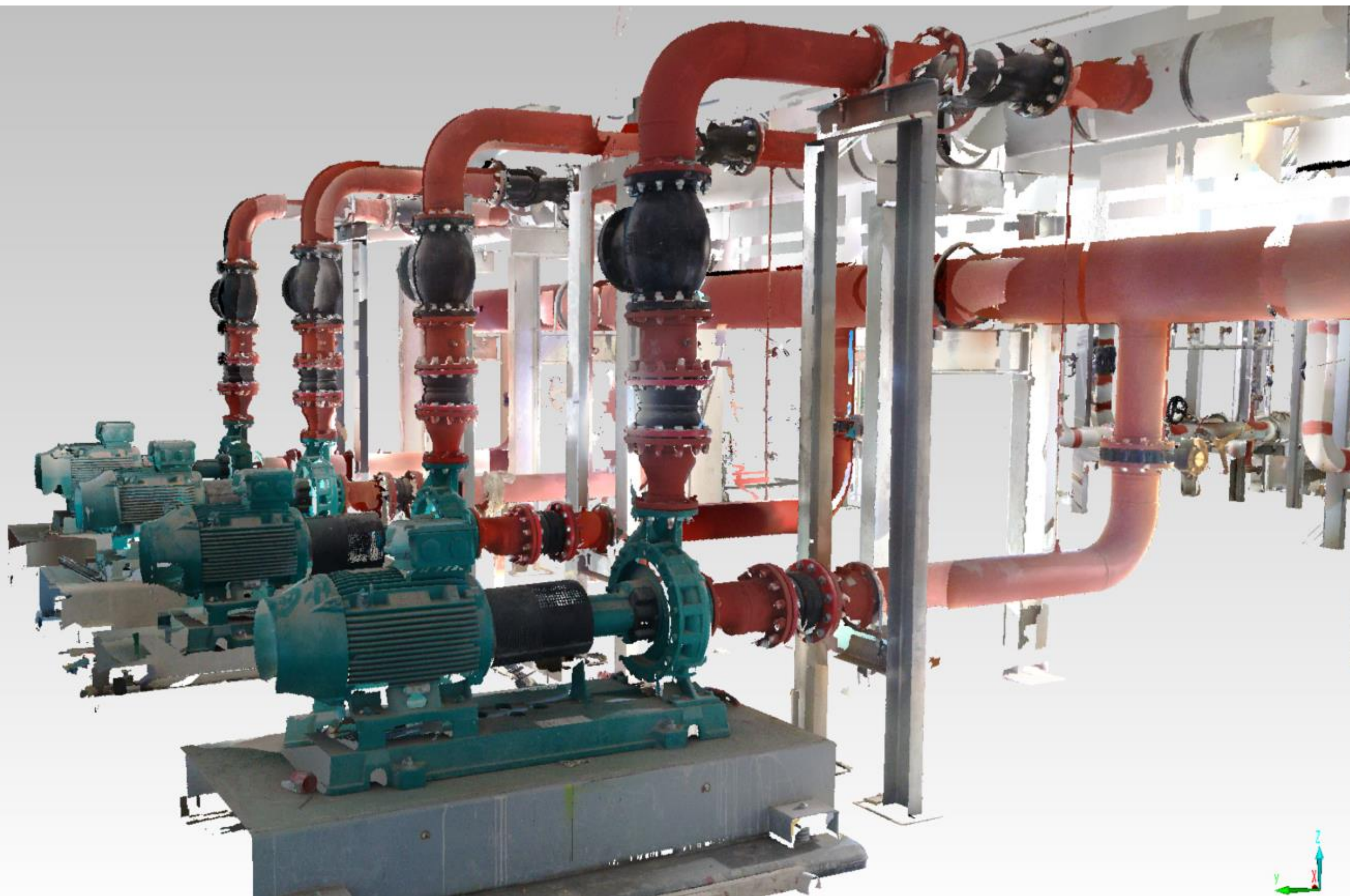
MEP BIM Model

As Built Preparation

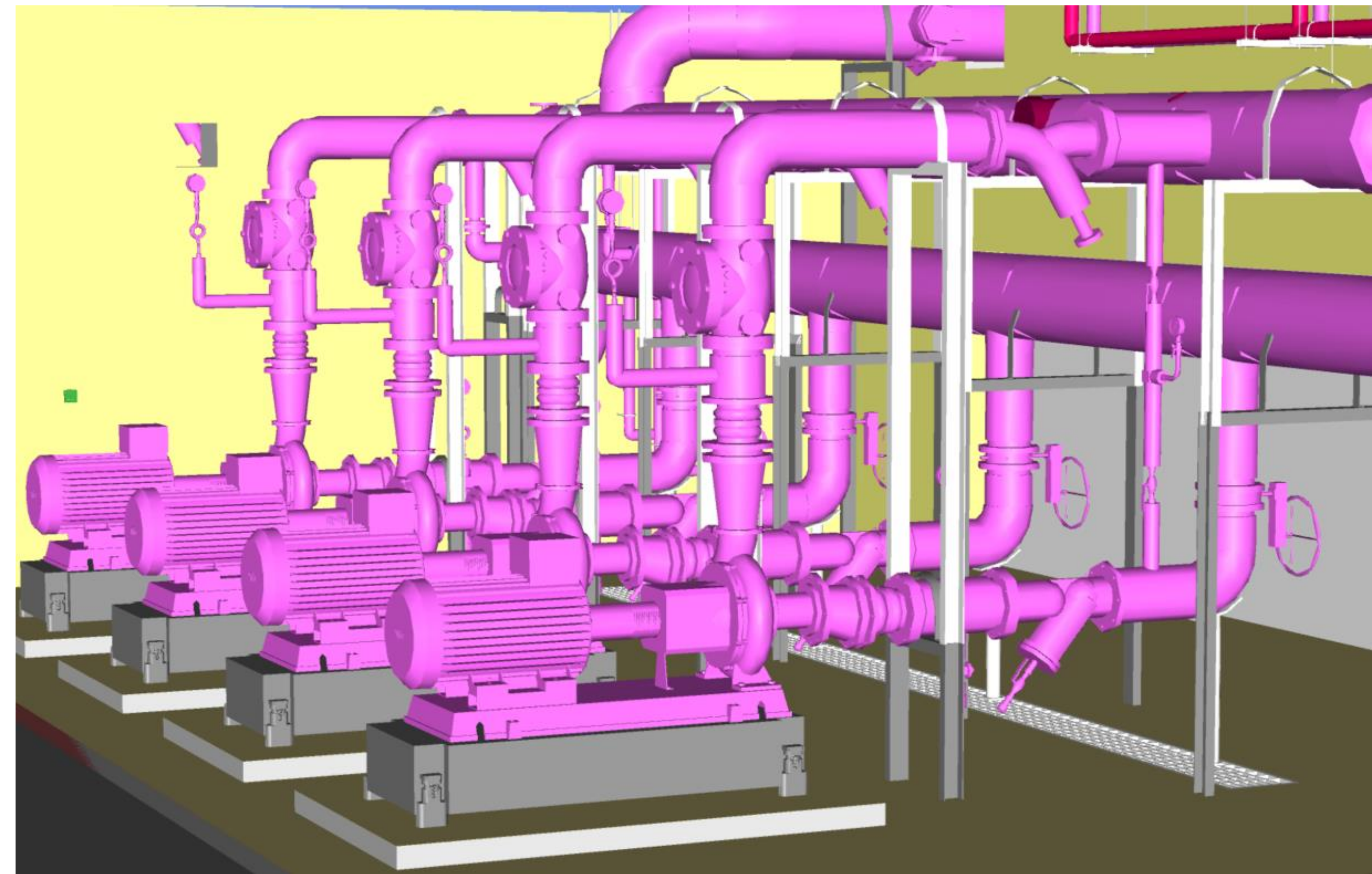
Scan



BIM



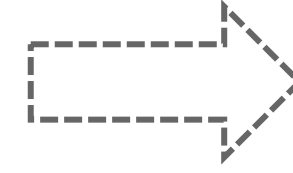
Pump Room Point Cloud Model



Pump Room BIM Model

As Built Preparation

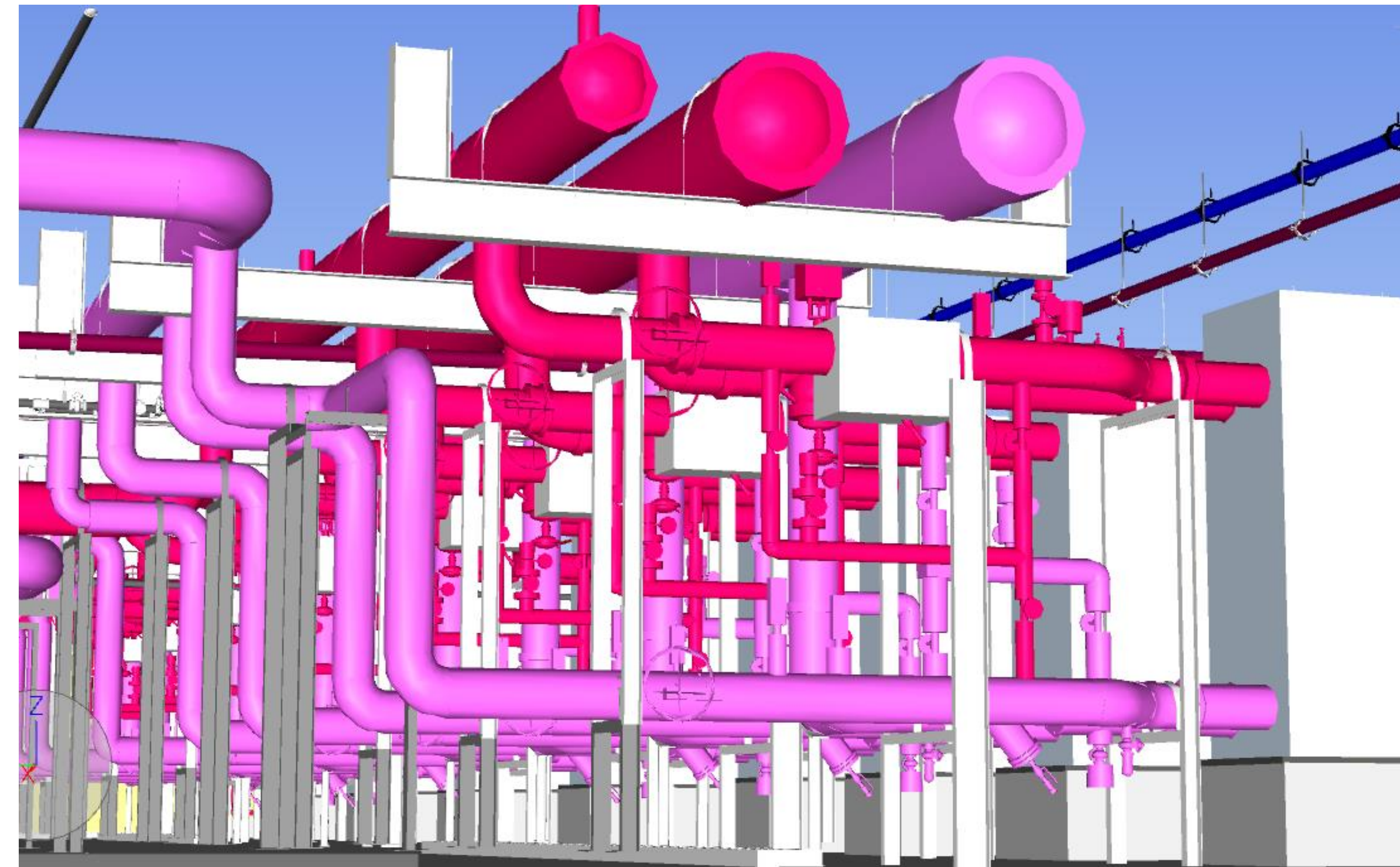
Scan



BIM



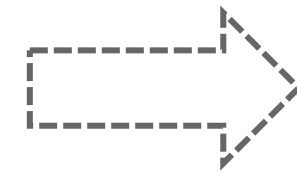
Chilled Water Pipes Point Cloud Model



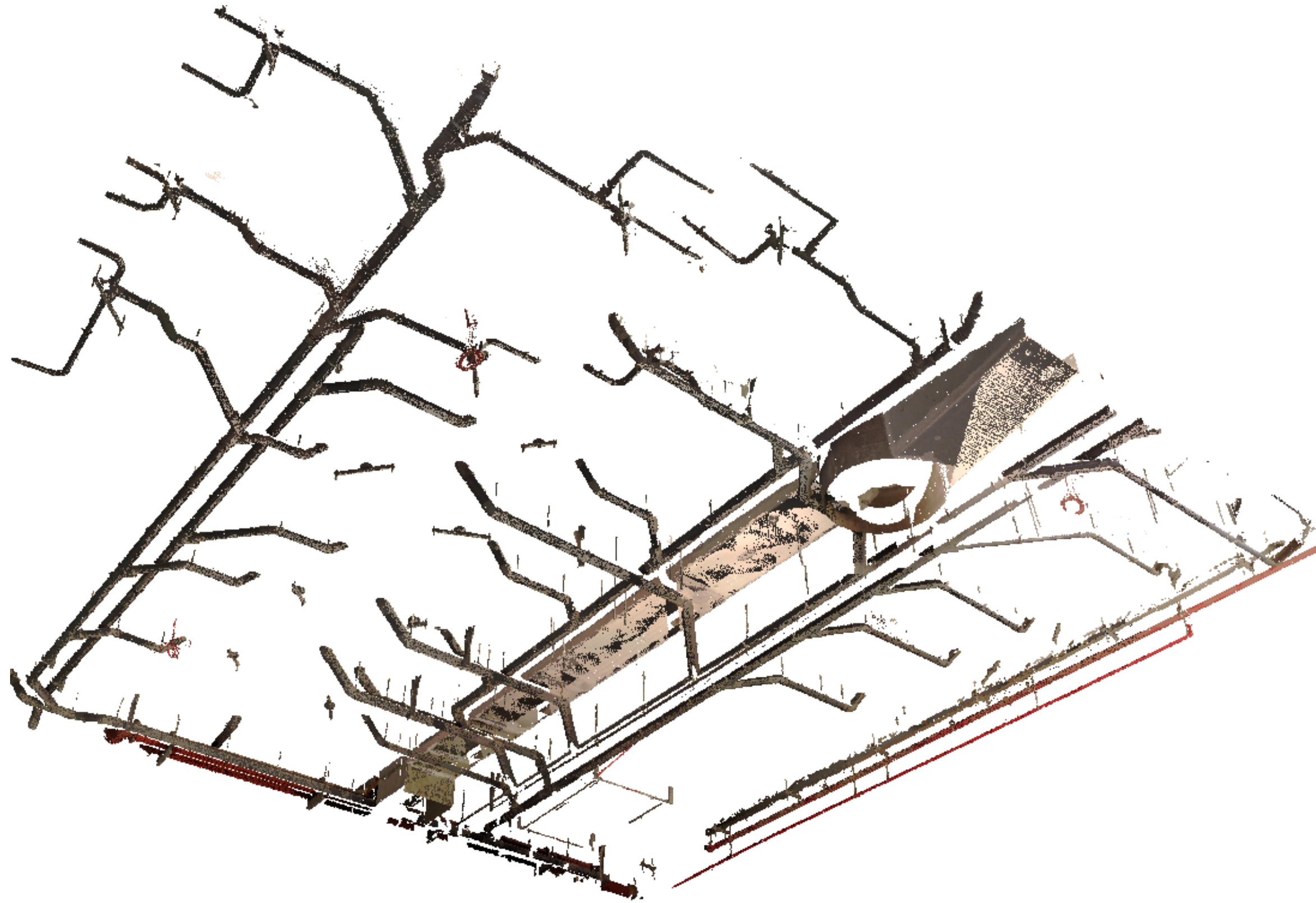
Chilled Water Pipes BIM Model

Scan to BIM of Public Health Services

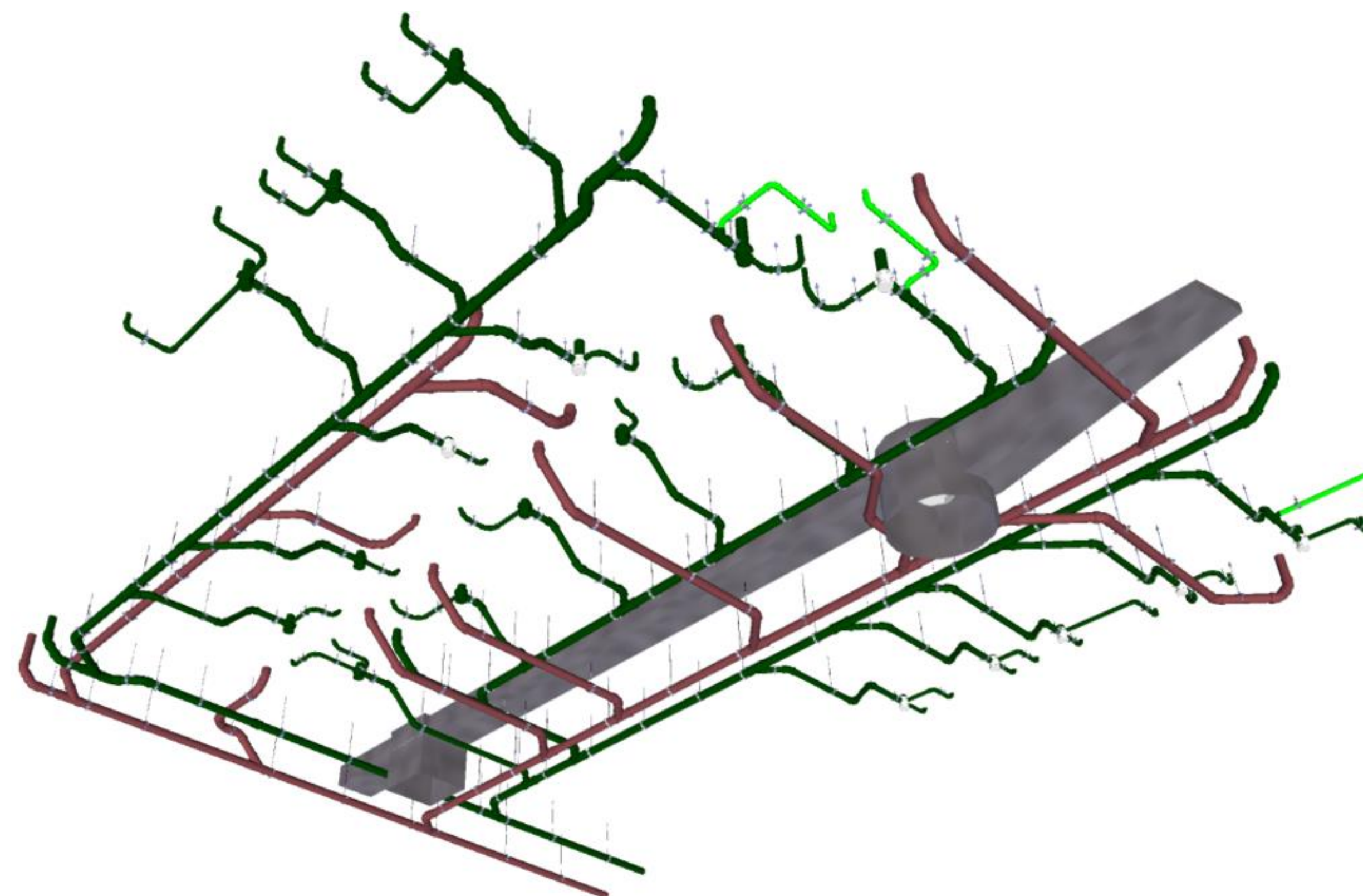
Scan



BIM



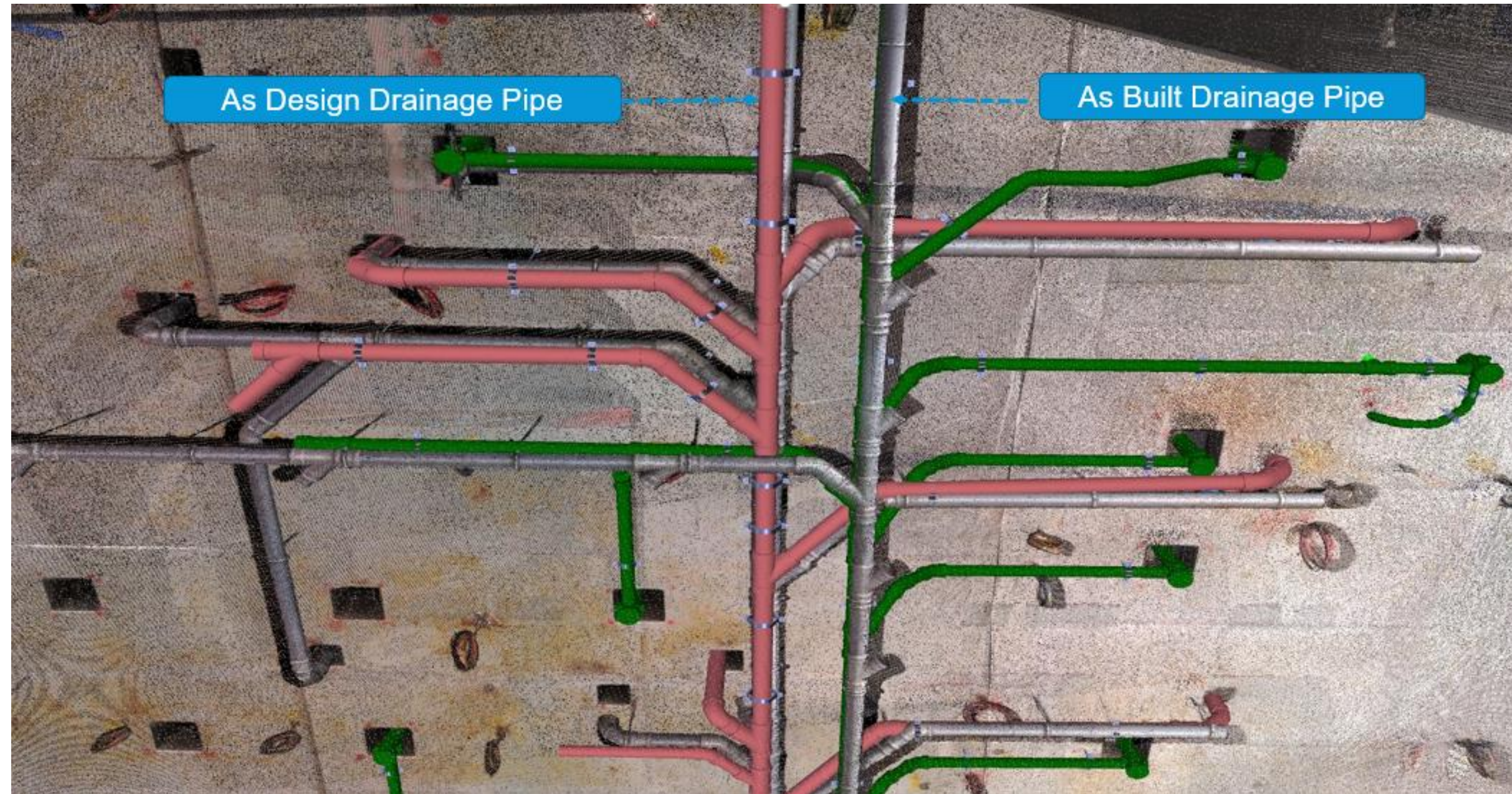
Drainage Pipes Point Cloud Model



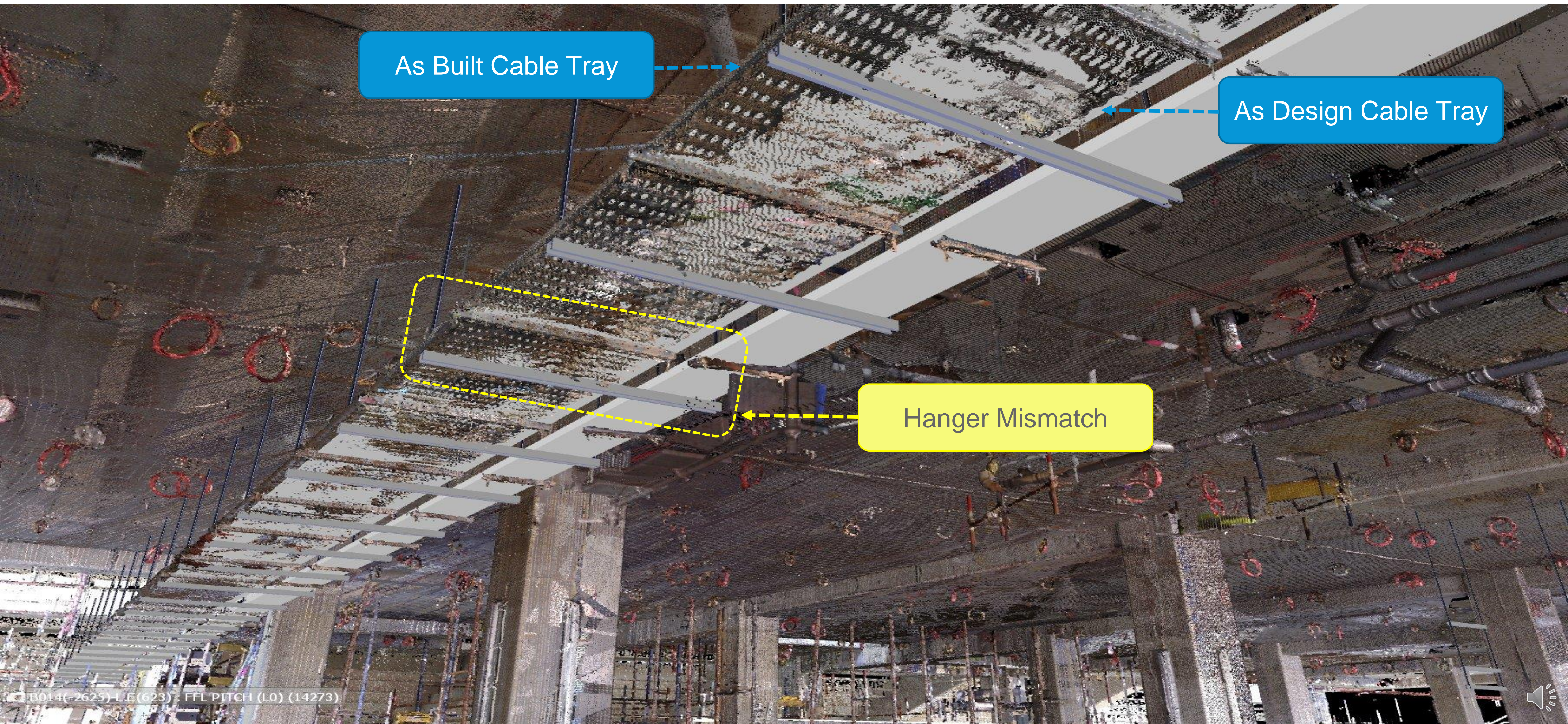
Drainage Pipes BIM Model



Builder's Work As-built



Evaluation of As-Built Conditions



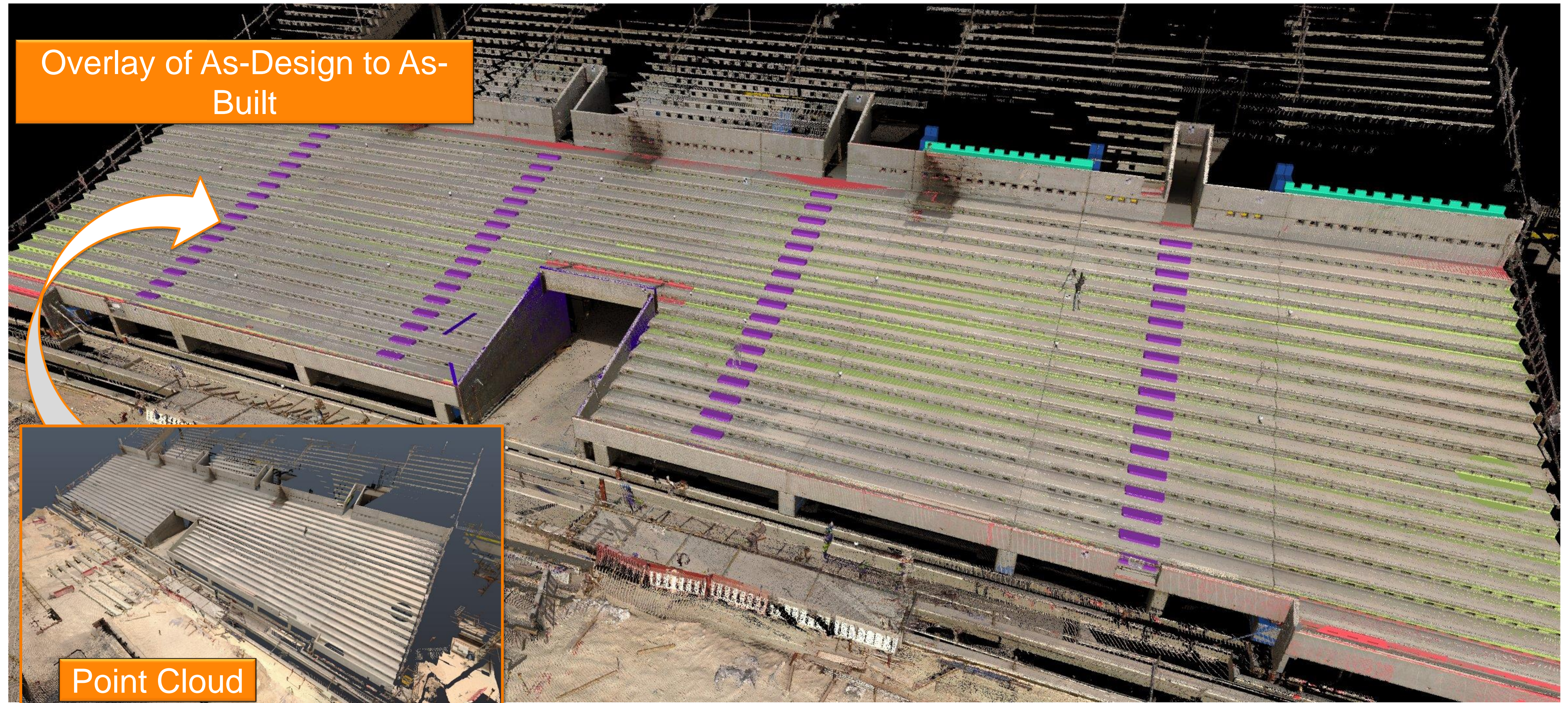
As Built Cable Tray

As Design Cable Tray

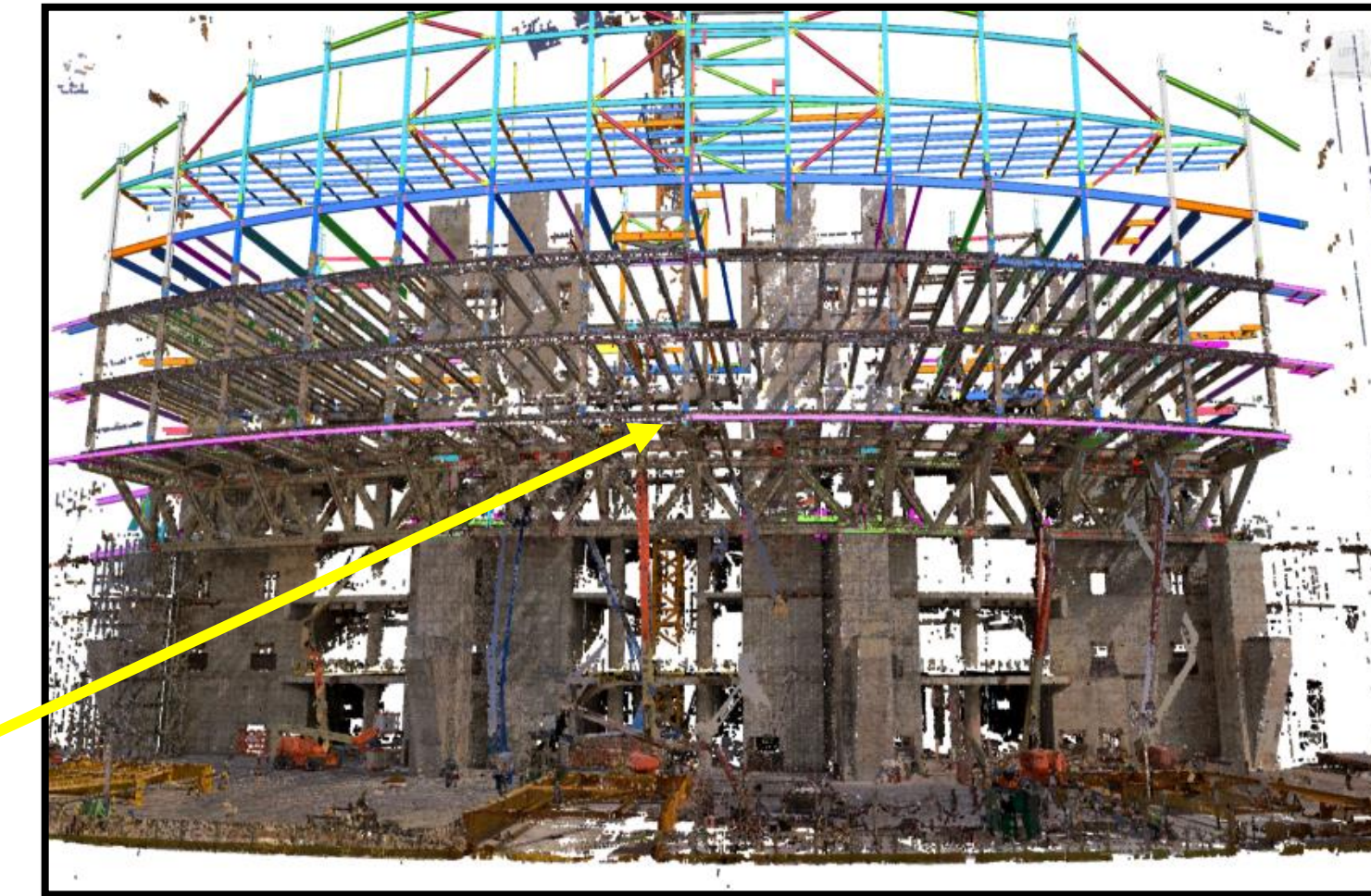
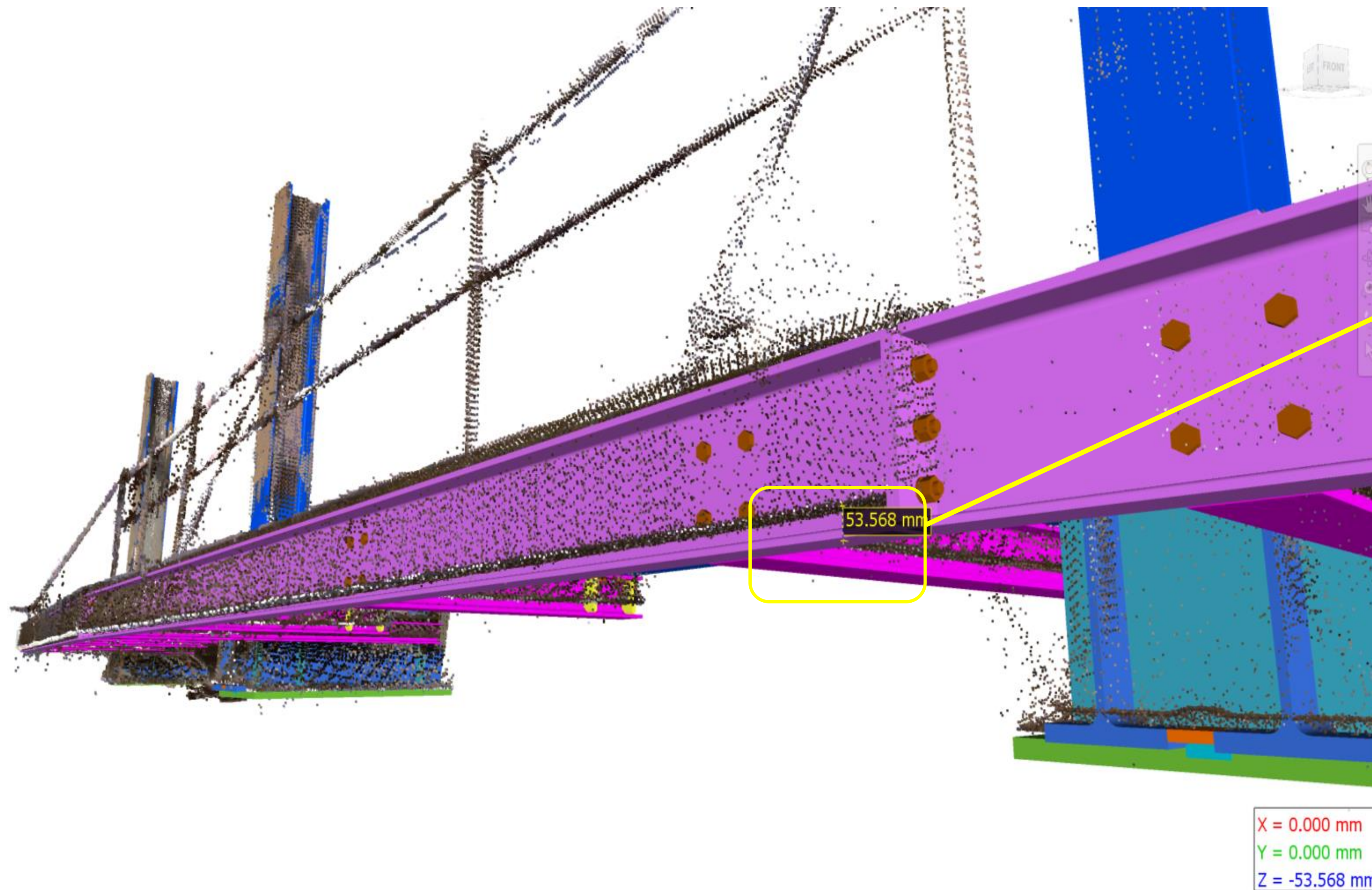
Hanger Mismatch



Updating of As-Design to As-Built

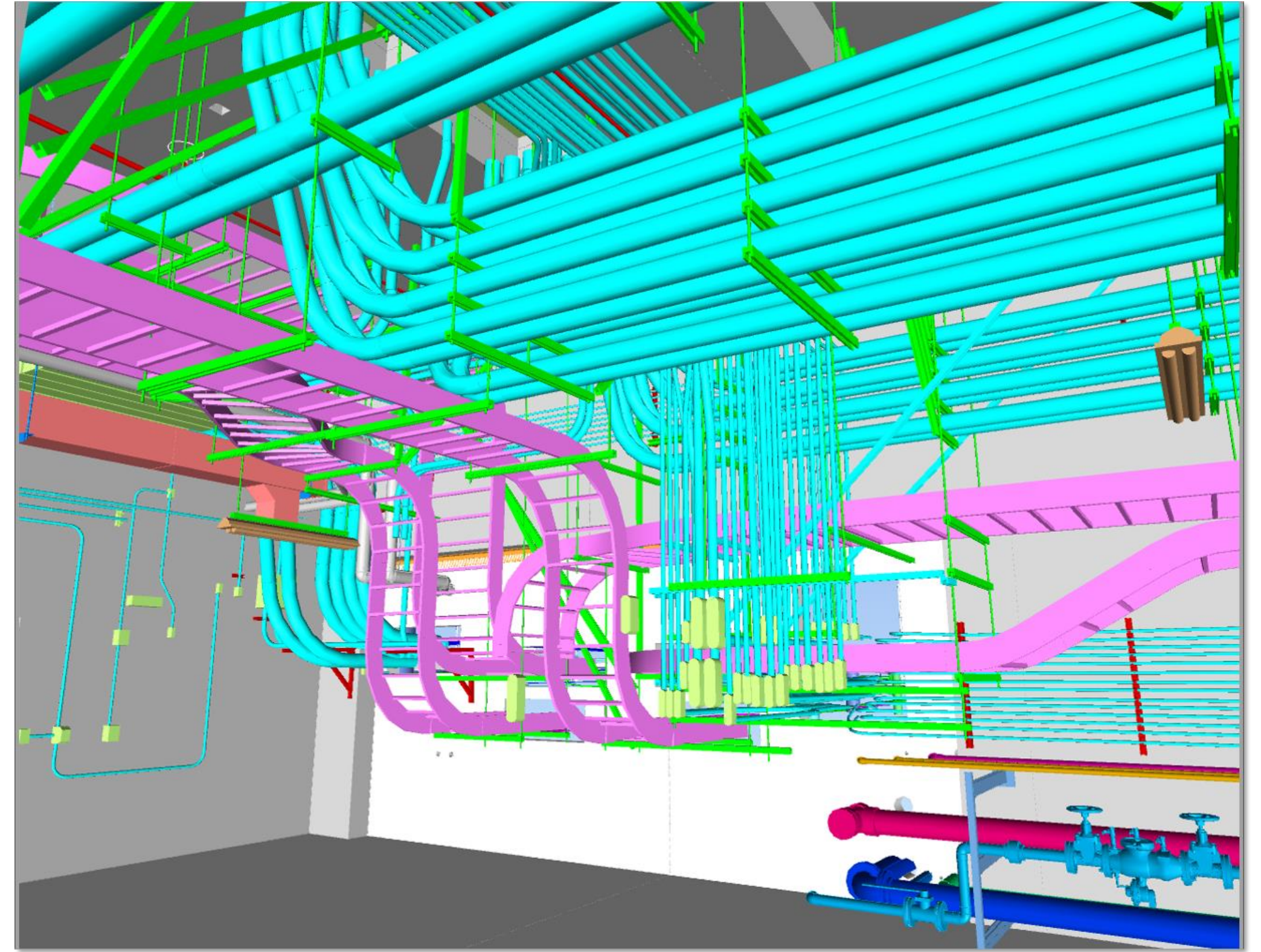


As-built to As-Design Deviation in Steel Structure



$\Delta H = -53.57\text{mm}$
At the bottom
edge of
cantilever beam

Updation of As-builts



Thank you



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